

ROGERS ENGINEERING & ASSOCIATES _____ Technical Report 89-1

Final Report

for

SPACE SHUTTLE PROPULSION ESTIMATION DEVELOPMENT VERIFICATION

Volume II

by

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Abstract

The work described in this report details the application of extended Kalman filtering to estimating the Space Shuttle Propulsion performance, i.e. specific impulse, from flight data in a post-flight processing computer program. The flight data used includes inertial platform acceleration, SRB head pressure, SSME chamber pressure and flow rates, and ground based radar tracking data. The key feature in this application is the model used for the SRB's, which is a nominal or reference quasi-static internal ballistics model normalized to the propellant burn depth. Dynamic states of mass overboard and propellant burn depth are included in the filter model to account for real-time deviations from the reference model used. Aerodynamic, plume, wind and main engine uncertainties are also included for an integrated system model. Assuming uncertainty within the propulsion system model and attempts to estimate its deviations represent a new application of parameter estimation for rocket powered vehicles. Illustrations from the results of applying this estimation approach to several missions show good quality propulsion estimates.

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C MERGES DATA FILES GENERATED FROM IMUTST, PREPRCS, AND REDRDR

C

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C DIMENSION DIMU(9),DPROL(3,6),DPROS(2),DRDR(15)
C
CSTG2 DATA IMAX, IBEGIN, IEND / 500, 130, 500 /
C DATA IMAX, IBEGIN, IEND / 130, 1, 130 /
C
C OPEN( UNIT=1,FILE='VEHROT',STATUS='OLD',ACCESS='SEQUENTIAL')
C OPEN( UNIT=2,FILE='PREPOT',STATUS='OLD',ACCESS='SEQUENTIAL')
C OPEN( UNIT=3,FILE='TRACK',STATUS='OLD',ACCESS='SEQUENTIAL')
C OPEN( UNIT=4,FILE='REALOUT',STATUS='NEW',ACCESS='SEQUENTIAL')
C
C DO 100 ITIME = 1, IMAX
C
C READ(1,901,END=100) TIME
C READ(1,906) (DIMU(I), I = 1, 3)
C READ(1,906) (DIMU(I), I = 4, 6)
C READ(1,906) (DIMU(I), I = 7, 9)
C READ(2,902) PTIME,((DPROL(I,J),I=1,3),J=1,6),(DPROS(K),K=1,2)
C READ(3,906) RTIME
C READ(3,906) (DRDR(I), I = 1, 15)
C
C IF ( (ITIME.LT.IBEGIN).OR.(ITIME.GT.IEND) ) GO TO 100
C
C WRITE(4,904) (DIMU(I), I = 1, 3)
C WRITE(4,905) ((DPROL(I,J), J = 1, 6), I = 1, 3)
C WRITE(4,906) (DRDR(I), I = 1, 9)
C WRITE(4,907) (DPROS(I), I = 1, 2)
C
C 100 CONTINUE
C CLOSE(UNIT=1)
C CLOSE(UNIT=2)
C CLOSE(UNIT=3)
C CLOSE(UNIT=4)
C
C STOP
C
C 901 FORMAT(7E15.8)
C 902 FORMAT( 3(7E15.8,/))
C 903 FORMAT(F5.1,9E14.7)
C 904 FORMAT(5X, 7E15.8)
C 905 FORMAT(5X, 6E15.8)
C 906 FORMAT(5X, 3E15.8)
C 907 FORMAT(5X, E15.8)
C
C END
```

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C DIMENSION STALE(39),VAL(39)
1 ,SPTIME(600),TSHEFT(600),GRAPH(600,39),PVAR(600),VEC(600),
DIMENSION TMP1(3,3),TMP2(3,3),TMP3(3,3),TMP4(3,3),TMP5(3,3),
1 ,REFMT1(3,3),REFMT2(3,3),REFMT3(3,3),DV1(3),DV2(3),DV3(3)
2 ,VOLD1(3),VOLD2(3),VOLD3(3),CIBRI(3,3),VECX(3)
3 ,CBI1(3,3),CBI2(3,3),CBI3(3,3),C50BR1(3,3),C50BR2(3,3)
4 ,TMP6(3,3),C50BR3(3,3),TBBR10(3,3),UNIT(3,3)
5 ,THT1(3),THT2(3),THT3(3),THTM(3),DVM(3),OMEG(3),C50BR(3,3)
6 ,Q(4),TMP7(4,4),DERQ(4),PREQ(4),CORQ(4)

C INTEGER*4 IPACK(30),IW(1440),ISTAT(39),ERROR,IBDN(4)
REAL*8 TIME,TSTART,TSTOP
CHARACTER MSID*12(39),CPACK*8,dbname*17,CHARP*4(30),YLAB*12
EQUIVALENCE (IPACK(2),CPACK),(DBNAME,IBDN),(IPACK,CHARP)

C COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2, CRAD
DATA IPACK(9),IPACK(9),IPACK(10),IPACK(11),IPACK(12),IPACK(13)
1 / 88,273,15,37,00,000 /
CVAX DATA IPACK(2),IPACK(3),IPACK(4),IPACK(5),IPACK(6),IPACK(7)
C61C 1 / 'STS6', 'ICDB', 'DAT', ' ', ' ', ' '
C61A 1 / 'STS6', 'IADB', 'DAT', ' ', ' ', ' '
C61B 1 / 'STS6', 'IBDB', 'DAT', ' ', ' ', ' '
C51B 1 / 'STS5', 'IBDB', 'DAT', ' ', ' ', ' '
CVAX DATA IPACK(8),IPACK(9),IPACK(10),IPACK(11),IPACK(12),IPACK(13)
C61C 1 / 86,012,11,54,59,997 /
C61A 1 / 85,303,17,00,00,010 /
C61B 1 / 85,331,00,29,00,006 /
C51B 1 / 85,119,16,02,17,989 /
DATA IPACK(14)/25/,IPACK(15)/2/,IPACK(16)/1440/

C DATA IST / 13 /
DATA VOLD1,VOLD2,VOLD3 / 3*0.0,3*0.0,3*0.0 /
DATA TBBR10 / 2*0.0,-1.0,0.0,1.0,0.0,1.0,2*0.0 /
DATA Q / 0.707106, 0.0, 0.707106, 0.0 /

C C51B DATA REFSMT1/-694542,.496024,-.521125,-.301635,.45684,.836847
C51B 1 ,.653167,.738415,-.167677/
C51B DATA REFSMT2/-1.20625,-.078044,.989626,.779794,-.624357,.045811
C51B 1 ,.614305,.77723,.136171/
C51B DATA REFSMT3/-517692,-.716205,-.468022,-.244835,.400140,-.883144
C51B 1 ,.817987,.571785,.0317968/
C C61A DATA REFSMT1/ 584975,-.342753,.735068, .487126,-.576157,-.656315
C61A 1 ,.648469, .741999,-.170073/
C61A DATA REFSMT2/.339075,-.0968083,-.935765,-.712631,.622931,-.322666
C61A 1 ,.614154,.776263,.142232/
C61A DATA REFSMT3/-561507,.802985,.199810,.0904577,-.180458,.979414
C61A 1 ,.822512,.568022,.0286922/
C C61B DATA REFSMT1/-756027,.641557,-.129719,.0119258,.211652,.977272
C61B 1 ,.654431,.737297,-.167666/
C61B DATA REFSMT2/.212771,-.327267,.920665,.760344,-.536331,-.366369

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C61B 1 ,.613682, .777975, .134720/
C61B DATA REFSMT3/.371235,-.485959,-.791219,-.436979,.660420,-.610651
C61B 1 ,.819288,.572441,.0328175/
C
C61CS DATA REFSMT1/.6134, -.3773, .6938, .4504, -.5546, -.6997
C61CS1 ,.6488, .7417, -.1702/
C61CS DATA REFSMT2/.2954, -.05881, -.9535, -.7317, .6278, -.2654
C61CS1 ,.6142, .7762, .1424/
C61CS DATA REFSMT3/- .5544, .7906, .2599, .1251, -.2296, .9652
C61CS1 ,.8228, .5676, .02839/
C61C DATA REFSMT1/.6133972, -.3773153, .6938130, .4503511, -.5545661
C61C 1 ,-.6997428, .6487887, .741680, .1702449/
C61C DATA REFSMT2/.2954440, -.05880850, -.9535483, -.7317411, .62777722
C61C 1 ,-.2654373, .6142209, .7761723, .1424394/
C61C DATA REFSMT3/- .5544043, .7906296, .2598850, .1250687, -.2295741
C61C 1 ,.9652219, .8227961, .5676264, .02839340/
C
DATA REFTMT1/.7124555, -.6688998, -.2120820, -.2697270, .0179653
1 ,-.9627689, .6478066, .7431343, -.1676210/
DATA REFTMT2/- .4540111, .4971972, -.7393705, -.6433136, .3912134
1 ,.6581028, .6164586, .7744331, .1422388/
DATA REFTMT3/- .1936510, .2368643, .9520475, .5359492, -.7872760
1 ,.3048846, .8217406, .5692902, .0255092/
C
DATA TSTART, TSTOP, SRATE / -10.0D0, 525.0D0, 1.0 /
DATA JUMP / 0 /
DATA DVMAX, THTMX, TMAX / 15.0, 180., 525.0 /
C
OPEN( UNIT=1, FILE='VEHRIN', STATUS='OLD', ACCESS='SEQUENTIAL' )
OPEN( UNIT=3, FILE='VEHRLP', STATUS='NEW', ACCESS='SEQUENTIAL' )
OPEN( UNIT=9, FILE='VEHROT', STATUS='NEW', ACCESS='SEQUENTIAL' )
C
IPACK(1) = -1
CPACK = 'ASTS317'
DBNAME = 'STS26DB'
CRAD = 57.295779
C
DO 10 I = 1, 4
10 IPACK(I+3) = IDBN(I)
C
WRITE(6, 12) IPACK(1), CPACK, DBNAME, (IPACK(J), J = 8, 14)
12 FORMAT( 2X, I2, 2X, A8,A17, 2X, 7I4 )
C
READ(1, 20) (MSID(J), J=1, (IPACK(14)+10))
20 FORMAT( A12 )
CLOSE ( UNIT=1 )
C
WRITE(6, 25) (MSID(J), J=1, (IPACK(14)+10))
25 FORMAT( 2X, A12 )
C
I=0
CALL ACCREQ(2, IPACK(2), DBNAME, IPACK(14), MSID, NUMBR, ISTAT, ERROR)
IF ( ERROR.NE.0 ) THEN
  WRITE(6,501) ERROR
  501 FORMAT('ERROR IN ACCREQ - ERROR= ', I5)

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C      STOP
C      END IF
C
C      50 CONTINUE
C
C      I = I + 1
C
C      TIME = TSTART
C
C      CALL ACCESS( IPACK, IW, MSID, SRATE, TIME, TSTOP, STALE, VAL, ISTAT )
C
C      IF( IPACK(1).EQ.6 ) GO TO 200
C
C      SPTIME(1)=SNGL( TIME ) - 2.0
C      SPTMAX = SNGL( TSTOP )
C      IF ( SPTIME(1).GE.SPTMAX ) GO TO 200
C
C      IF ( SPTIME(I).GT.125. ) DVMAX = 0.15
C
C      IF ( VAL(1).NE.0.0 ) THEN
C          PITCH=CRAD*VAL(1)
C          YAW=CRAD*VAL(2)
C          ROLL=CRAD*VAL(3)
C          ROLO=CRAD*VAL(4)
C
C          CALL TMATY ( -YAW, TMP1 )
C          CALL TMATR ( -ROLLI, TMP2 )
C          CALL MULT ( TMP2, TMP1, TMP3, 3, 3, 3 )
C          CALL TMATP ( -PITCH, TMP1 )
C          CALL MULT ( TMP1, TMP3, TMP2, 3, 3, 3 )
C          CALL TMATR ( -ROLO, TMP1 )
C          CALL MULT ( TMP1, TMP2, TMP3, 3, 3, 3 )
C          CALL TMATP ( -10.6, TMP2 )
C          CALL MULT ( TMP2, TMP3, TMP4, 3, 3, 3 )
C
C          ELSE
C          END IF
C
C          IF ( VAL(8).NE.0.0 ) THEN
C              PITCH = CRAD*VAL(8)
C              YAW = CRAD*VAL(9)
C              ROLL = CRAD*VAL(10)
C              ROLO = CRAD*VAL(11)
C
C              CALL TMATY ( -YAW, TMP1 )
C              CALL TMATR ( -ROLLI, TMP2 )
C              CALL MULT ( TMP2, TMP1, TMP3, 3, 3, 3 )
C              CALL TMATP ( -PITCH, TMP1 )
C              CALL MULT ( TMP1, TMP3, TMP2, 3, 3, 3 )
C              CALL TMATR ( -ROLO, TMP1 )
C              CALL MULT ( TMP1, TMP2, TMP3, 3, 3, 3 )
C              CALL TMATP ( -10.6, TMP1 )
C              CALL MULT ( TMP1, TMP3, TMP5, 3, 3, 3 )
C
C              ELSE
C              END IF
C
C              IF ( VAL(15).NE.0.0 ) THEN

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PITCH = CRAD*VAL(15)
YAW = CRAD*VAL(16)
ROLI = CRAD*VAL(17)
ROLO = CRAD*VAL(18)

C
CALL TMATY ( - YAW, TMP1 )
CALL TMATR ( - ROLI, TMP2 )
CALL MULT ( TMP2, TMP1, TMP3, 3, 3, 3 )
CALL TMATP ( - PITCH, TMP1 )
CALL MULT ( TMP1, TMP3, TMP2, 3, 3, 3 )
CALL TMATR ( - ROLO, TMP1 )
CALL MULT ( TMP1, TMP2, TMP3, 3, 3, 3 )
CALL TMATP ( -10.6, TMP1 )
CALL MULT ( TMP1, TMP3, TMP6, 3, 3, 3 )

C
ELSE
END IF

C
IF ( JUMP.LT.1 ) THEN

C
CALL MULT ( TBBR10, TMP4, C50BR1, 3, 3, 3 )
CALL MULT ( TBBR10, TMP5, C50BR2, 3, 3, 3 )
CALL MULT ( TBBR10, TMP6, C50BR3, 3, 3, 3 )
JUMP=1

C
WRITE(6, 905) ((C50BR1(J,K), J = 1, 3), K = 1, 3)
WRITE(6, 905) ((C50BR2(J,K), J = 1, 3), K = 1, 3)
WRITE(6, 905) ((C50BR3(J,K), J = 1, 3), K = 1, 3)

C
CALL MULT ( C50BR1, REFM1, C50BR, 3, 3, 3 )
CALL MULT ( C50BR2, REFM2, TMP2, 3, 3, 3 )
CALL MULT ( C50BR3, REFM3, TMP3, 3, 3, 3 )

C
WRITE(6, 999)
WRITE(6, 905) ((C50BR(II,JJ), JJ = 1, 3), II = 1, 3)
WRITE(6, 999)
WRITE(6, 905) ((TMP2(II,JJ), JJ = 1, 3), II = 1, 3)
WRITE(6, 999)
WRITE(6, 905) ((TMP3(II,JJ), JJ = 1, 3), II = 1, 3)
WRITE(6, 999)

C
ELSE
END IF

C
IF ( VAL(1).NE.0.0 ) THEN
CALL TRANS ( TMP4, TMP3, 3, 3 )
CALL MULT ( C50BR1, TMP3, CBI1, 3, 3, 3 )
IF ( ABS(CBI1(3,1)).GT.1.0 ) CBI1(3,1)=SIGN(1.0, CBI1(3,1))
THT1(2) = CRAD*ASIN( -CBI1(3,1) )
THT1(1) = CRAD*ATAN2( CBI1(3,2), CBI1(3,3) )
THT1(3) = CRAD*ATAN2( CBI1(2,1), CBI1(1,1) )

C
DV1(1) = VAL(5) - VOLD1(1)
DV1(2) = VAL(6) - VOLD1(2)
DV1(3) = VAL(7) - VOLD1(3)

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C CALL MULT ( REFM1, DV1, VECX, 3, 3, 1 )
CALL MULT ( C50BR1, VECX, DV1, 3, 3, 1 )
ELSE
END IF

C IF ( VAL(8).NE.0.0 ) THEN
CALL TRANS ( TMP3, TMP3, 3, 3 )
CALL MULT ( C50BR2, TMP3, CBI2, 3, 3, 3 )
IF ( ABS(CBI2(3,1)).GT.1.0 ) CBI2(3,1) = SIGN(1.0, CBI2(3,1))
THT2(2) = CRAD*ASIN( -CBI2(3,1) )
THT2(1) = CRAD*ATAN2( CBI2(3,2), CBI2(3,3) )
THT2(3) = CRAD*ATAN2( CBI2(2,1), CBI2(1,1) )

DV2(1) = VAL(12) - VOLD2(1)
DV2(2) = VAL(13) - VOLD2(2)
DV2(3) = VAL(14) - VOLD2(3)

CALL MULT ( REFM2, DV2, VECX, 3, 3, 1 )
CALL MULT ( C50BR2, VECX, DV2, 3, 3, 1 )
ELSE
END IF

C IF ( VAL(15).NE.0.0 ) THEN
CALL TRANS ( TMP6, TMP3, 3, 3 )
CALL MULT ( C50BR3, TMP3, CBI3, 3, 3, 3 )
IF ( ABS(CBI3(3,1)).GT.1.0 ) CBI3(3,1) = SIGN(1.0, CBI3(3,1))
THT3(2) = CRAD*ASIN( -CBI3(3,1) )
IF ( CBI3(3,3).NE.0.0 ) THEN
THT3(1) = CRAD*ATAN2( CBI3(3,2), CBI3(3,3) )
ELSE
THT3(1) = 0.0
END IF
IF ( CBI3(1,1).NE.0.0 ) THEN
THT3(3) = CRAD*ATAN2( CBI3(2,1), CBI3(1,1) )
ELSE
THT3(3) = 0.0
END IF

DV3(1) = VAL(19) - VOLD3(1)
DV3(2) = VAL(20) - VOLD3(2)
DV3(3) = VAL(21) - VOLD3(3)

CALL MULT ( REFM3, DV3, VOLD3, 3, 3, 1 )
CALL MULT ( C50BR3, VOLD3, DV3, 3, 3, 1 )
ELSE
END IF

C IF ( VAL(8).EQ.0.0 ) THEN
C DO 75 II = 1, 3
THTM(II) = THT1(II)
DVM(II) = DV1(II)
CONTINUE

```

```

ELSE
END IF

C DO 100 II = 1, 3
C IF ( ABS(THT1(II) - THT2(II)) .GT. THTMAX ) THEN
C   THTM(II) = THTM(II)
C   WRITE(*, 940) II, SPTIME(I)
C ELSE
C   THTM(II) = 0.5*( THT1(II) + THT2(II) )
C END IF

C IF ( ABS(DV1(II) - DV2(II)) .GT. DVMAX ) THEN
C   DVM(II) = DVM(II)
C   WRITE(*, 950) II, SPTIME(I)
C ELSE
C   DVM(II) = ( DV1(II) + DV2(II) + DV3(II) ) /3.0
C   DVM(II) = 0.5*( DV1(II) + DV2(II) )
C END IF

C IF ( SPTIME(I) .GT. TEND ) THEN
C   DVM(II) = ( DV1(II) + DV2(II) + DV3(II) ) /3.0
C   DVM(II) = 0.5*( DV1(II) + DV2(II) )
C ELSE
C   END IF
C 100 CONTINUE
C   OMEG(1) = VAL(24)/CRAD
C   OMEG(2) = VAL(22)/CRAD
C   OMEG(3) = VAL(23)/CRAD
C   CALL QMTRX ( OMEG, TMP7 )

C QS = 0.0
C   DO 130 J = 1, 4
C     DERQ(J) = 0.0
C   DO 120 K = 1, 4
C     DERQ(J) = DERQ(J) + TMP7(J,K) * Q(K)
C   CONTINUE
C   PREQ(J) = Q(J) + DERQ(J)/SRATE
C   QS = QS + PREQ(J) * PREQ(J)
C 120 CONTINUE
C 130 CONTINUE

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```

QSM1 = QS
QS = 0.0
DO 170 J = 1, 4
TEMP = 0.0
DO 160 K = 1, 4
TEMP = TEMP + TMP7(J, K) * PREQ(K)
CONTINUE
CORQ(J) = Q(J) + 0.5 * (DERQ(J) + TEMP) / SRATE
QS = QS + CORQ(J) * CORQ(J)
CONTINUE
C
DO 175 J = 1, 4
Q(J) = CORQ(J)
CONTINUE
C
CALL CHIMXQ ( Q, TMP1 )
CALL QUAT2E ( CORQ, THTM )
C
ALOAD = VAL(25)
C
IF( (I-IST).LE.0 ) GO TO 180
GRAPH(I-IST),1) = DVM(1)
GRAPH(I-IST),2) = DVM(2)
GRAPH(I-IST),3) = DVM(3)
GRAPH(I-IST),4) = THTM(1)
GRAPH(I-IST),5) = THTM(2)
GRAPH(I-IST),6) = THTM(3)
GRAPH(I-IST),7) = OMEG(1)*CRAD
GRAPH(I-IST),8) = OMEG(2)*CRAD
GRAPH(I-IST),9) = OMEG(3)*CRAD
GRAPH(I-IST),10) = ALLOAD
TSHFT(I-IST) = SPTIME(I)
CONTINUE
WRITE(6, 905) SPTIME(I)
WRITE(6, 902) (DVM(II), II = 1, 3), ALLOAD
WRITE(6, 905) (THTM(II), II = 1, 3)
WRITE(6, 905) (OMEG(II), II = 1, 3)
C
IMAX = I - IST
C
VOLD1(1) = VAL(5)
VOLD1(2) = VAL(6)
VOLD1(3) = VAL(7)
VOLD2(1) = VAL(12)
VOLD2(2) = VAL(13)
VOLD2(3) = VAL(14)
VOLD3(1) = VAL(19)
VOLD3(2) = VAL(20)
VOLD3(3) = VAL(21)
C
THTM(1) = THTM(1)
THTM(2) = THTM(2)
THTM(3) = THTM(3)
DVM(1) = DVM(1)

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DVM(2) = DVM(2)
DVM(3) = DVM(3)
DVMAG = SQRT(DVM(1)**2+DVM(2)**2+DVM(3)**2)

C      GO TO 50
C      200  CONTINUE
C
C      DO 220 I = 1, IMAX
C      WRITE(9,905) TSHFT(I)
C      WRITE(9,902) (GRAPH(I,J), J = 1, 3), GRAPH(I,10)
C      WRITE(9,905) (GRAPH(I,J), J = 4, 6)
C      WRITE(9,905) (GRAPH(I,J), J = 7, 9)
220  CONTINUE

C      CLOSE ( UNIT=9 )

C      XMIN = TSHFT(1)
C      XMAX = TSHFT(IMAX)

C      DO 300 NM = 1, 10
C      YMIN = GRAPH(1,NM)
C      YMAX = YMIN

C      YLAB = MSID( IPACK(14)+NM )

C      DO 250 I = 1, IMAX
C      YMIN = AMIN1( GRAPH(I,NM), YMIN )
C      YMAX = AMAX1( GRAPH(I,NM), YMAX )
C      PVAR(I) = GRAPH(I,NM)
250  CONTINUE

C      WRITE(6,25) YLAB

C      CALL PLOT2 ( XMIN, XMAX, YMIN, YMAX )
C      CALL PLOT3 ( '.', TSHFT, PVAR(1), IMAX )
C      CALL PLOTA ( 9, 'TIME (SEC)', 6, YLAB, 13, 'BRI IMU DATA' )

C      300  CONTINUE
C
C      CLOSE ( UNIT = 3 )
C
C      STOP

C      3   FORMAT(T2, 7I5)
C      FORMAT(3X, 4E15.8)
901   FORMAT( 5X, 4E15.8 )
902   FORMAT( 5X, 15 )
903   FORMAT( 5X, 3E15.8 )
905   FORMAT( 5X, 15.2X, 28HATTITUDE DATA EDITED AT TIME,3E15.8 )
940   FORMAT( 5X, 15.2X, 32HACCELERATION DATA EDITED AT TIME,3E15.8 )
950   FORMAT( 5X, 15.2X, 32HACCELERATION DATA EDITED AT TIME,3E15.8 )
999   FORMAT( / )

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C DIMENSION STALE(32), VAL(32)
1 , SPTIME(600), GRAPH(600,20), PVAR(600)
DIMENSION PCV(3,2), PXM(3,2), TXM(3,2), PX(3,2), TX(3,2), WEHE(3,2)
1 , PCM(3), Y8(3), PH(3), TH(3)

C INTEGER*4 IPACK(30), IW(1920), ISTAT(32), ERROR, IDBN(4)
REAL*8 TIME, TSTART, TSTOP
CHARACTER MSID*12(52), CPACK*8, DBNAME*17, CHARP*4(30), YLAB*12
EQUIVALENCE (IPACK(2),CPACK), (DBNAME, IDBN), (IPACK, CHARP)

C COMMON / DATAG / DTP(2), C(32,2), GAMMA(2), R(2), VP(8,2), IE
COMMON / CDATA / EM(2), PATH, RK, FR, GAM
COMMON/NDATA/AK, ALWS(3,2), AREAHX(2), BK, CD(3,2), CK,
DAR(3,2), DCD(3,2), FK(3,2), TOL(2)

CVAX DATA IPACK(2), IPACK(3), IPACK(4), IPACK(5), IPACK(6), IPACK(7)
C61A 1 / 'STS6', 'ICDB', 'DAT', 'DAT', 'DAT', 'DAT', 'DAT'
C61A 1 / 'STS6', 'IADB', 'DAT', 'DAT', 'DAT', 'DAT', 'DAT'
C61B 1 / 'STS6', 'IBDB', 'DAT', 'DAT', 'DAT', 'DAT', 'DAT'
C51B 1 / 'STS5', 'IBDB', 'DAT', 'DAT', 'DAT', 'DAT', 'DAT'

CVAX DATA IPACK(8), IPACK(9), IPACK(10), IPACK(11), IPACK(12), IPACK(13)
C61C 1 / 86,012,11,54,59,997 /
C61A 1 / 85,331,00,29,00,006 /
C61B 1 / 85,331,00,29,00,006 /
C51B 1 / 85,119,16,02,17,989 /

C DATA IPACK(8), IPACK(9), IPACK(10), IPACK(11), IPACK(12), IPACK(13)
1 / 88,273,15,37,00,016 /
DATA IPACK(14)/32/, IPACK(15)/2/, IPACK(16)/1920/
```

C DATA TSTART, SRATE, TSTAGE / 0.0D0, 524.D0, 1.0, 128. /

C OPEN(UNIT=1,FILE='PREPIN', STATUS='OLD', ACCESS='SEQUENTIAL')
OPEN(UNIT=3,FILE='PREPPL', STATUS='NEW', ACCESS='SEQUENTIAL')
OPEN(UNIT=9,FILE='PREPOT', STATUS='NEW', ACCESS='SEQUENTIAL')

C IPACK(1) = -1
CPACK = 'ASTSS317',
DBNAME = 'STS26DB',
DBNAME = 'STS61CDB',
COND = 2.831685E-1/4.5335924

C DO 10 I = 1, 4
10 IPACK(I+3) = IDBN(I)

C WRITE(6,12) IPACK(1),CPACK,DBNAME,(IPACK(J), J = 8, 14)
12 FORMAT(2X, I2, 2X, A8, A17, 2X, 7I4)

C READ(1, 20) (MSID(J), J = 1, (IPACK(14)+20))
20 FORMAT(A12)
C WRITE(6, 25) (MSID(J), J = 1, (IPACK(14)+20))

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25 FORMAT( 2X, A12 )

C      I = 0
      CALL ACCREQ( 2, IPACK(2), DBNAME, IPACK(14), MSID, NUMBR, ISTAT, ERROR )
      IF ( ERROR.NE.0 ) THEN
        WRITE( 6, 501 ) ERROR
        FORMAT( ' ERROR IN ACCREQ - ERROR=' , I5 )
        STOP
      END IF

C      50 CONTINUE
C      I = I + 1
C      TIME = TSTART

C      CALL ACCESS( IPACK, IW, MSID, SRATE, TIME, TSTOP, STALE, VAL, ISTAT )

C      IF( IPACK(1) .EQ. 6 ) GO TO 200

C      SPTIME(I) = SNGL( TIME )

C      FCV(1,1) = FLOAT( IFIX( VAL(1) ) )
      FCV(2,1) = FLOAT( IFIX( VAL(2) ) )
      FCV(3,1) = FLOAT( IFIX( VAL(3) ) )
      FCV(1,2) = FLOAT( IFIX( VAL(4) ) )
      FCV(2,2) = FLOAT( IFIX( VAL(5) ) )
      FCV(3,2) = FLOAT( IFIX( VAL(6) ) )
      PXM(1,1) = VAL(7)
      PXM(2,1) = VAL(8)
      PXM(3,1) = VAL(9)
      PXM(1,2) = VAL(10)
      PXM(2,2) = VAL(11)
      PXM(3,2) = VAL(12)
      TXM(1,1) = VAL(13) + FR
      TXM(2,1) = VAL(14) + FR
      TXM(3,1) = VAL(15) + FR
      TXM(1,2) = VAL(16) + FR
      TXM(2,2) = VAL(17) + FR
      TXM(3,2) = VAL(18) + FR

C      CALCULATE PRESSURANT MASS FLOW RATES FROM PRESSURE AND TEMPERATURES

C      DO 100 L = 1, 2
C      DO 100 M = 1, 3

C      WZ = 0.0
      IF( PXM(M,L).LE.0.0 ) GO TO 95
      PX(M,L) = PXM(M,L)
      TX(M,L) = TXM(M,L)
      PP = PXM(M,L)/PATM
      TT = TXM(M,L)

C      80 CONTINUE

C      CALL FINDD( PP, TT, L, DD )

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C 90 CONTINUE
C
C      WEHE(M,L) = (ALWS(M,L) + FCV(M,L))*DAR(M,L)*PX(M,L)*SQRT(EM(L)/
1      (TX(M,L)*1545.0))*3.8839427*(CD(M,L) + FCV(M,L)*DCD(M,L))
C      WRITE(*,901) AREAHX(L), RHO
C      VEL = 14.4*WEHE(M,L)/(AREAHX(L)*RHO)
C
C      PX(M,L) = TXM(M,L)+(1.0-FK(M,L))*RHO*VEL**2/(2.0*32.174*144.0)
C      PSTAT = PX(M,L) - RHO*VEL**2/(2.0*32.174*144.0)
C      TX(M,L) = TXM(M,L)*(PX(M,L)/PSTAT)**GAM
C
C      IF( ABS(WEHE(M,L) - WZ) .LE. TOL(L) ) GO TO 100
C      WZ = WEHE(M,L)
C      PP = PSTAT/PATM
C      GO TO 80
C
C 95  CONTINUE
C      WEHE(M,L) = 0.0
C
C 100 CONTINUE
C
C      PCM(1) = VAL(19)
C      PCM(2) = VAL(20)
C      PCM(3) = VAL(21)
C      Y8(1) = VAL(22)
C      Y8(2) = VAL(23)
C      Y8(3) = VAL(24)
C      PH(1) = VAL(25)
C      PH(2) = VAL(26)
C      PH(3) = VAL(27)
C      TH(1) = VAL(28)
C      TH(2) = VAL(29)
C      TH(3) = VAL(30)
C
C      DO 150 J = 1, 3
C      GRAPH(I,J) = PCM(J)
C      GRAPH(I,J+3) = WEHE(J,1)
C      GRAPH(I,J+6) = WEHE(J,2)
C      GRAPH(I,J+9) = Y8(J)
C      GRAPH(I,J+12) = PH(J)
C      GRAPH(I,J+15) = TH(J)
C
C      CONTINUE
C
C      IF( SPTIME(I).LT.TSTAGE ) THEN
C      GRAPH(I,19) = VAL(31)
C      GRAPH(I,20) = VAL(32)
C
C      ELSE
C
C      GRAPH(I,19) = 0.0
C      GRAPH(I,20) = 0.0
C
C      CONTINUE
C
C      IF( SPTIME(I).LT.TSTAGE ) THEN
C

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```
END IF
C      IMAX = I
C      GO TO 50
C      CONTINUE
200
C      DO 225 I = 1, IMAX
        WRITE(9, 995) SPTIME(I), (GRAPH(I,J), J = 1, 20)
995    FORMAT( 3(7E15.8,/))
225    CONTINUE
C
      XMIN = SPTIME(1)
      XMAX = SPTIME(IMAX)
C
      DO 300 NM = 1, 20
        YMIN = GRAPH(1,NM)
        YMAX = YMIN
        YLAB = MSID( IPACK(14)+NM )
        DO 250 I = 1, IMAX
          YMIN = AMIN1( GRAPH(I,NM), YMIN )
          YMAX = AMAX1( GRAPH(I,NM), YMAX )
          PVAR(I) = GRAPH(I,NM)
250    CONTINUE
        WRITE(6,25) YLAB
C
        CALL PLOT2( XMIN, XMAX, YMIN, YMAX )
        CALL PLOT3( '.', SPTIME, PVAR(1), IMAX )
        CALL PLOT4( 9, 'TIME (SEC)', 6, YLAB, 13, 'PROP MEASURES' )
C
300
      CONTINUE
C      WRITE(6,903) IPACK(1)
903    FORMAT( 5X, 15 )
C      CLOSE ( UNIT=3 )
      CLOSE ( UNIT=9 )
C      STOP
END
```

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C DIMENSION AZM(9), ELM(9), RNGM(9), AZM2(5), ELM2(5), RNGM2(5)
1   , KOUT(5) , KOUT(3)
C CSTGX1CSTGX
C DATA NOUT / 5 /
C DATA NOUT / 3 /
C DATA KOUT / 1, 3, 5, 4, 6 /
C CSTG1 DATA KOUT / 1, 3, 5 /
C CSTG2 DATA KOUT / 3, 4, 6 /
C DATA ITIME / 0 /
C
C OPEN ( UNIT=1, NAME='RADAR.DAT', STATUS='OLD' )
C OPEN ( UNIT=3, NAME='TRACK.DAT', STATUS='NEW' )
C
C READ(1,901,END=100) TIME, (AZM(I), ELM(I), RNGM(I), I = 1, 6)
C
C TSAVE = TIME
C IF( ITIME.GT.0 ) GO TO 16
C ITIME = 1
C TINC = 1.0
C TIME = 1.0
C
C CONTINUE
10 DO 14 I = 1, NOUT
C
C AZM2(I) = 0.0
C ELM2(I) = 0.0
C RNGM2(I) = 0.0
C
C CONTINUE
14 WRITE(3, 902) TIME, (AZM2(I), ELM2(I), RNGM2(I), I = 1, NOUT)
C
C WRITE(3, 902) TIME
C WRITE(3, 902) (AZM2(I), ELM2(I), RNGM2(I), I = 1, NOUT)
C
C TIME = TIME + TINC
C IF( TIME.GE.TSAVE ) GO TO 16
C GO TO 12
C
C CONTINUE
16 CONTINUE
C
C ITIME = IFIX( TIME )
C XTIME = FLOAT( ITIME )
C IF( XTIME.EQ.TLAST ) GOTO 10
C
C TLAST = TIME
DO 20 IPICK= 1, NOUT
IOUT = KOUT(IPICK)
AZM2(IPICK) = AZM(IOUT)
IF( AZM2(IPICK).GT.180.0 ) AZM2(IPICK) = AZM(IOUT) - 360.0
ELM2(IPICK) = ELM(IOUT)
RNGM2(IPICK) = RNGM(IOUT)
CONTINUE
20
C
C WRITE(3, 902) TIME, (AZM2(I), ELM2(I), RNGM2(I), I = 1, NOUT)
C
C WRITE(3, 902) TIME
C WRITE(3, 902) (AZM2(I), ELM2(I), RNGM2(I), I = 1, NOUT)
C
C GO TO 10
C
C CONTINUE
100 CONTINUE
C
C CLOSE ( UNIT=3 )
C CLOSE ( UNIT=1 )
C
C 901 FORMAT( 1X, F5.1,7(1X,F8.4,1X,F7.4,1X,F8.0) )
C 902 FORMAT( 5X, 3E15.8 )
C

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```
C DIMENSION STALE(26),VAL(26)
1 ,SPTIME(600),TSHTF(600),GRAPH(600,17),PVAR(600),VEC(600)
DIMENSION TMP1(3,3),TMP2(3,3),TMP3(3,3),TMP4(3,3),TMP5(3,3)
1 ,REFMT1(3,3),REFMT2(3,3),REFMT3(3,3)
3 , CBI1(3,3),CBI2(3,3),CBI3(3,3),C50BR1(3,3),C50BR2(3,3)
4 , TBBR1(3,3)
5 , TH1(3),TH2(3),THM(3)

C INTEGER*4 IPACK(30),IW(1440),ISTAT(26),ERROR,IDBN(4)
REAL*8 TIME1,TIME2,TSTART,TSTOP
CHARACTER MSID*12(43),CPACK*8,DENAME*17,CHARP*4(30),YLAB*12
EQUIVALENCE (IPACK(2),CPACK),(DBNAME, IDBN),(IPACK,CHARP)

C DATA IPACK(8),IPACK(9),IPACK(10),IPACK(11),IPACK(12),IPACK(13)
1 / 88,273,15,37,00,000 /
DATA IPACK(14)/26/,IPACK(15)/2/,IPACK(16)/1560/

C DATA IST / 11 /
DATA TBBR10 / 2+0.0,-1.0,0,0,1,0,0,0,1,0,2+0.0 /
C51B DATA REFT1/-694542,-496024,-521125,-301635,.45684,.836847
C51B 1 ,653167,.738415,-167677/
C51B DATA REFT2/-120625,-078044,.989626,.779794,-.624357,.045811
C51B 1 ,614305,.77723,136171/
C51B DATA REFT3/.517692,-716205,-468022,-244835,.400140,-.883144
C51B 1 ,817987,.571785,.0317968/
C C61A DATA REFT1/.584975,-342975,.735068,-47126,-.576157,-.656315
C61A 1 ,648469,.741999,-170073 /
C61A DATA REFT2/-339075,-0968083,-.935765,-.712631,.622931,-.3226666
C61A 1 ,614154,.77626,142232 /
C61A DATA REFT3/-5544043,.802985,.199810,.0904577,-.180458,.979414
C61A 1 ,822512,.568022,.0286922/
C C61C DATA REFT1/-6133972,-3773153,.6938130,.4503511,-.5545661
C61C 1 ,6997428,.6487887,.741680,-1702449/
C61C DATA REFT2/-2954440,-0584850,-.2654373,.6142209,-.7761723,.1424394/
C61C 1 ,2654373,.6142209,-.7761723,.1424394/
C61C DATA REFT3/-1936510,.7906296,.2598850,.1250687,-.2295741
C61C 1 ,9652219,.8227961,.56776264,.02839340/
C DATA REFT1/-7124555,-6688998,-2120820,-2697270,.0179653
1 ,9622768,-6478066,.743134,-.1676210/
DATA REFT2/-4540111,.4971972,-.7393705,-.6433136,.3912134
1 ,6581028,.6164586,.7744331,.1422388/
DATA REFT3/-1936510,.2368643,.9520475,.5359492,-.78722760
1 ,3048846,.8217406,.5692902,.0255092/
C DATA TSTART,TSTOP,SRATE / -10.0D0, 523.0D0, 1.0 /
DATA JUMP / 0 /
C OPEN( UNIT=1,FILE='CTRLIN',STATUS='OLD',ACCESS='SEQUENTIAL' )
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OPEN( UNIT=3,FILE='CTRLP',STATUS='NEW',ACCESS='SEQUENTIAL' )
OPEN( UNIT=9,FILE='CTRLQ',STATUS='NEW',ACCESS='SEQUENTIAL' )

C      CRAD = 57.295779
      IPACK(1) = -1
      CPACK = 'ASTS317'
      DBNAME = 'STS26DB'
      C61C   DBNAME = 'STS61CDB'
      C

      DO 10 I = 1, 4
 10   IPACK(I+3) = IDBN(I)

C      WRITE(6, 12) IPACK(1),CPACK,DBNAME,(IPACK(J), J= 8, 14)
 12   FORMAT( 2X, I2, 2X, A4,A17, 2X, 7I4 )

C      READ(1, 20) (MSID(J), J=1, (IPACK(14)+17))
 20   FORMAT( A12 )
      CLOSE ( UNIT=1 )

C      WRITE(6, 25) (MSID(J), J=1, (IPACK(14)+17))
 25   FORMAT( 2X, A12 )

C      I=0
      CALL ACCREQ(2,IPACK(2),DBNAME,IPACK(14),MSID,NUMBR,ISTAT,ERROR)
      IF ( ERROR.NE.0 ) THEN
        WRITE(6,501) ERROR
        FORMAT(' ERROR IN ACCREQ - ERROR=', I5)
        STOP
      END IF

C      50 CONTINUE
C      I = I + 1
      TIME1 = TSTART

C      CALL ACCESS( IPACK,IW,MSID,SRATE,TIME1,TSTOP,STALE,VAL,ISTAT )
      IF( IPACK(1).EQ.6 ) GO TO 200
      SPTIME(1) = SNGL( TIME1 ) - 1.0
      SPTMAX = SNGL( TSTOP )

C      PITCH=CRAD*VAL(1:2)
      YAW=CRAD*VAL(1:3)
      ROLI=CRAD*VAL(1:4)
      ROLO=CRAD*VAL(1:5)

C      CALL TMATY ( -YAW, TMP1 )
      CALL TMATR ( -ROLI, TMP2 )
      CALL MULT ( TMP2, TMP1, TMP3, 3, 3, 3 )
      CALL TMATP ( -PITCH, TMP1 )
      CALL MULT ( TMP1, TMP3, TMP2, 3, 3, 3 )
      CALL TMATR ( -ROLO, TMP1 )
      CALL MULT ( TMP1, TMP2, TMP3, 3, 3, 3 )
      CALL TMATP ( -10.6, TMP2 )
      CALL MULT ( TMP2, TMP3, TMP4, 3, 3, 3 )

C

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PITCH = CRAD*VAL(16)
YAW = CRAD*VAL(17)
ROLL = CRAD*VAL(18)
ROL0 = CRAD*VAL(19)

C
CALL TMATY ( -YAW, TMP1 )
CALL TMATR ( -ROLL, TMP2 )
CALL MULT ( TMP2, TMP1, TMP3, 3, 3, 3 )
CALL TMATP ( -PITCH, TMP1 )
CALL MULT ( TMP1, TMP3, TMP2, 3, 3, 3 )
CALL TMATR ( -ROLL, TMP1 )
CALL MULT ( TMP1, TMP2, TMP3, 3, 3, 3 )
CALL TMATP ( -10.6, TMP1 )
CALL MULT ( TMP1, TMP3, TMP5, 3, 3, 3 )

C IF ( JUMP.LT.1 ) THEN
C
CALL MULT ( TBBR10, TMP4, C50BR1, 3, 3, 3 )
CALL MULT ( TBBR10, TMP5, C50BR2, 3, 3, 3 )
JUMP=1

C
WRITE(6, 905) ((C50BR1(J,K), J = 1, 3), K = 1, 3)
WRITE(6, 905) ((C50BR2(J,K), J = 1, 3), K = 1, 3)
C
ELSE
END IF

C
CALL TRANS ( TMP4, TMP3, 3, 3 )
CALL MULT ( C50BR1, TMP3, CBI1, 3, 3, 3 )
IF ( ABS(CBI1(3,1)).GT.1.0 ) CBI1(3,1)=SIGN(1.0, CBI1(3,1))
THT1(2) = CRAD*ASIN( -CBI1(3,1) )
THT1(1) = CRAD*ATAN2 ( CBI1(3,2), CBI1(3,3) )
THT1(3) = CRAD*ATAN2 ( CBI1(2,1), CBI1(1,1) )

CALL TRANS ( TMP5, TMP3, 3, 3 )
CALL MULT ( C50BR2, TMP3, CBI2, 3, 3, 3 )
IF ( ABS(CBI2(3,1)).GT.1.0 ) CBI2(3,1)=SIGN(1.0, CBI2(3,1) )
THT2(2) = CRAD*ASIN( -CBI2(3,1) )
THT2(1) = CRAD*ATAN2 ( CBI2(3,2), CBI2(3,3) )
THT2(3) = CRAD*ATAN2 ( CBI2(2,1), CBI2(1,1) )

DO 100 II = 1, 3

C
IF ( ABS(THT1(II) - THT2(II)).GT.1.0 ) THEN
C
THTM(II) = THTM(II)
C
ELSE
C
THTM(II) = 0.5*( THT1(II) + THT2(II) )
C
END IF
C
CONTINUE
C
100
C

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QI = VAL(24)
RI = VAL(25)
PI = VAL(26)

C      IF( (I-IST).LE.0 ) GO TO 180
GRAPH((I-IST),1) = VAL(1)
GRAPH((I-IST),2) = VAL(2)
GRAPH((I-IST),3) = VAL(3)
GRAPH((I-IST),4) = VAL(4)
GRAPH((I-IST),5) = VAL(5)/100.
GRAPH((I-IST),6) = VAL(6)
GRAPH((I-IST),7) = VAL(7)
GRAPH((I-IST),8) = VAL(8)
GRAPH((I-IST),9) = VAL(9)
GRAPH((I-IST),10) = VAL(10)
GRAPH((I-IST),11) = VAL(11)
GRAPH((I-IST),15) = THTM(1)
GRAPH((I-IST),16) = THTM(2)
GRAPH((I-IST),17) = THTM(3)
GRAPH((I-IST),12) = PI/CRAD
GRAPH((I-IST),13) = QI/CRAD
GRAPH((I-IST),14) = RI/CRAD
TSHFT(I-IST) = SPTIME(I)
CONTINUE
180

C      IMAX = I - IST
C      THTM(1) = THTM(1)
THTM(2) = THTM(2)
THTM(3) = THTM(3)
C      GO TO 50
C      CONTINUE
C      CONTINUE
220
C      XMIN = TSHFT(1)
XMAX = TSHFT(IMAX)
C      DO 300 NM = 1, 17
C      YMIN = GRAPH(1,NM)
YMAX = YMIN
C      YLAB = MSID( NM+IPACK(14) )
C      DO 250 I = 1, IMAX
YMIN = AMIN1( GRAPH(I,NM), YMIN )
YMAX = AMAX1( GRAPH(I,NM), YMAX )
PVAR(I) = GRAPH(I,NM)
CONTINUE
250
C      DO 270 II = 1, IMAX
VEC(II) = PVAR(II)

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```
270      CONTINUE
C      CALL DATSMTH ( IMAX, VEC, PVAR )
C      DO 280 II = 1, IMAX
GRAPH(II, NM) = PVAR(II)
CONTINUE
C      CALL PLOT2 ( XMIN, XMAX, YMIN, YMAX )
CALL PLOT3 ( ' ', TSHFT, PVAR(1), IMAX )
CALL PLOT4 ( 9, 'TIME (SEC)', 6, YLAB, 13, 'CONTRL INPUT' )
C      CONTINUE
DO 350 I = 1, IMAX
WRITE(9, 905) TSHFT(I), (GRAPH(I,J), J = 1, 4)
WRITE(9, 905) (GRAPH(I,J), J = 5, 11)
WRITE(9, 905) (GRAPH(I,J), J = 12, 14)
WRITE(9, 905) (GRAPH(I,J), J = 15, 17)
CONTINUE
C      CLOSE ( UNIT = 3 )
CLOSE ( UNIT = 9 )
C      STOP
C      FORMAT(T2, 7I5)
901   FORMAT(3X, 4E15.8)
902   FORMAT( 5X, 4E15.8 )
903   FORMAT( 5X, 15 )
905   FORMAT(5X, 7E15.8 )
C      END
```

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C PROGRAM METST
C PROGRAM MAIN
C
C DIMENSION STALE(11), VAL(11)
C   ALT(405), GRAPH(405,13), PVAR(405)
C
C INTEGER*4 IPACK(30), IW(660), ISTAT(11), ERROR, IDBN(4)
C REAL*8 TIME, TSTART, TSTOP
C CHARACTER MSID*12(14), CPACK*8, DBNAME*17, CHARP*4(30), YLAB*12
C EQUIVALENCE (IPACK(2),CPACK), (DBNAME, IDBN), (IPACK,CHARP)
C
C DATA IPACK(8), IPACK(9), IPACK(10), IPACK(11), IPACK(12), IPACK(13)
C   / 88,273,15,37,00,000 /
C61C 1 / 86,012,11,54,59,997 /
C
C DATA IPACK(14)/11/,IPACK(15)//2/,IPACK(16)//660/
C
C CVAX DATA TSTART,TSTOP,SRATE / 0.0D0, 160000.D0, '00328084 /
C DATA TSTART,TSTOP,SRATE / 0.0D0, .804D0, 500. /
C
C OPEN( UNIT=1,FILE='METDIN',STATUS='OLD',ACCESS='SEQUENTIAL' )
C OPEN( UNIT=3,FILE='METDOT',STATUS='NEW',ACCESS='SEQUENTIAL' )
C
C IPACK(1) = -1
C CPACK = 'ASTS317,
C DBNAME = 'MET026 FINIE'
C61C DBNAME = 'MET61C FINIM.
C CRAD = 57.295779
C
C DO 10 I = 1, 4
C 10 IPACK(I+3) = IDBN(I)
C
C WRITE(6,12) IPACK(1),CPACK,DBNAME,(IPACK(J), J = 8 , 14)
C 12 FORMAT( 2X, 12, 2X, A8,A17, 2X, 7I4 )
C
C READ(1, 20) (MSID(J), J = 1, (IPACK(14)+3))
C 20 FORMAT( A12 )
C
C WRITE(6, 25) (MSID(J), J = 1, (IPACK(14)+3))
C 25 FORMAT(' 2X, A12 ')
C
C I = 0
C CALL ACCREQ(2,IPACK(2),DBNAME,IPACK(14),MSID,NUMBR,ISTAT,ERROR)
C IF ( ERROR.NE.0 ) THEN
C   WRITE(6,501) ERROR
C   FORMAT(' ERROR IN ACCREQ - ERROR= ', 15 )
C   STOP .
C END IF
C
C 50 CONTINUE
C   I = I + 1
C TIME = TSTART
C
C CALL ACCESS( IPACK,IW,MSID,SRATE,TIME,TSTOP,STALE,VAL,ISTAT )
C

```

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```

IF( IPACK(1) .EQ. 6 ) GO TO 200

C      SPALT = SNGL( TIME )/.3048
C      SPALT = VAL(11)
C
C      WS = VAL(1)
C      WD = VAL(2)
C
C      IF( I.EQ.1 ) THEN
C          DENS = .002378
C          PRES = 2116.
C
C          ELSE
C              DENS = VAL(4)*.6243E-4/32.174
C              PRES = VAL(5)*144.*.014505
C          END IF
C          TEMP = ( VAL(3) + 273.16 ) *9./5.

C          VSOUND = 49.02*SQRT(TEMP)
C          VWX = -WS*COS( WD/CRAD )
C          VWY = -WS*SIN( WD/CRAD )

C          ALT(I) = SPALT
C          GRAPH(I,1) = WS
C          GRAPH(I,2) = WD
C          GRAPH(I,3) = TEMP
C          GRAPH(I,4) = DENS
C          GRAPH(I,5) = PRES
C          GRAPH(I,6) = VSOUND
C          GRAPH(I,7) = VWX
C          GRAPH(I,8) = VWY

C          UWS = VAL(6)
C          UWD = VAL(7)
C          UDENS = VAL(9)*.6243E-4/32.174
C          UPRES = VAL(10)*144.*.014505
C          UTEMP = VAL(8)*9./5.

C          UVS = 49.02*UTEMP/(2.*SQRT(TEMP))
C          UVWX1 = UWS*COS( WD/CRAD )
C          UVWX2 = -WS*SIN( WD/CRAD )*UWD/CRAD
C          UVWX = SQRT( UVWX1**2 + UVWX2**2 )
C          UVWY1 = UWS*SIN( WD/CRAD )
C          UVWY2 = WS*COS( WD/CRAD )*UWD/CRAD
C          UVWY = SQRT( UVWY1**2 + UVWY2**2 )

C          GRAPH(I,9) = UDENS
C          GRAPH(I,10) = UPRES
C          GRAPH(I,11) = UTEMP
C          GRAPH(I,12) = UVWX
C          GRAPH(I,13) = UVWY

C          IMAX = I
C
C          GO TO 50
C

```

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```
C      CONTINUE
C      DO 220 I = 1, IMAX
      WRITE(3, 998) ALT(I), GRAPH(I,J), J = 4, 8)
      WRITE(3, 999) (GRAPH(I,J), J = 9, 13)
220   CONTINUE
      FORMAT( 5X, 6E15.8 )
      FORMAT( 20X, 5E15.8 )
C
      XMIN = ALT(1)
      XMAX = ALT(IMAX)
C
      DO 300 NM = 1, (IPACK(14)+3)
C
      YMIN = GRAPH(1, NM)
      YMAX = YMIN
      YLAB = MSID( NM )
      DO 250 I = 1, IMAX
      YMIN = AMIN1( GRAPH(I,NM), YMIN )
      YMAX = AMAX1( GRAPH(I,NM), YMAX )
      PVAR(I) = GRAPH(I,NM)
250   CONTINUE
C
      CALL PLOT2 ( XMIN, XMAX, YMIN, YMAX )
      CALL PLOT3 ( '.', ALT, PVAR(1), IMAX )
      CALL PLOT4 ( 9, 'FT ALTITUDE', 6, YLAB, 13, 'METEOROLOGY' )
C
300   CONTINUE
      WRITE(*, 903) IPACK(1)
      903  FORMAT( 5X, 15 )
C
      CLOSE ( UNIT=3 )
C
      STOP
C
      END
```


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```
C ROUTINE TO PLOT OUTPUT OF THE LFILTER.EXE PROGRAM
C
C DIMENSION YLBFL(3,45),T(500),PVAR(500,3),XKM(500,30),PKM(500,30)
1 ,RG(30),COVZ(500,15), RESID(500,15)
C DIMENSION YLAB(3)
C
C OPEN(UNIT=2,FILE='YLABLFL.DAT',STATUS='OLD',ACCESS='SEQUENTIAL',
1 RECL=9,CARRIAGECONTROL='LIST')
C
C READ(2,5)((YLBFL(I,J),I=1,3),J=1,45)
5 FORMAT( 2A4, A1 )
C
C CLOSE ( UNIT=2 )
C
C WRITE(*,6)((YLBFL(I,J),I=1,3),J=1,45)
6 FORMAT( T2, 2A4, A1 )
C
C OPEN ( UNIT=1, FILE='LFILOUT.DAT', STATUS='OLD',
1 ACCESS='SEQUENTIAL', FORM='UNFORMATTED' )
OPEN ( UNIT=3, FILE='PLTFIL.DAT', STATUS='NEW' )
C
C I = 1
10 CONTINUE
J = 0
20 CONTINUE
C
C J = J + 1
C
C READ(1, END = 100) T(I), TL, IMEAS, NMEAS
WRITE(*, 901) T(I), TL, IMEAS, NMEAS
READ(1) (XKM(I,K), K = 1, 30)
READ(1) (PKM(I,K), K = 1, 30)
C READ(1) (RG(K), K = 1, 30)
READ(1) COVZ(I,J)
READ(1) RESID(I,J)
C
C IF ( IMEAS - NMEAS ) 20, 30, 30
30 CONTINUE
C
C IMAX = I
I = I + 1
IF ( I.GE.500 ) GO TO 100
GO TO 10
C
100 CONTINUE
C
C XMIN = T(1)
XMAX = T(IMAX)
C
C DO 200 KK = 1, 30
C
C DO 110 II = 1, IMAX
C
C SIGV = SQRT ( PKM(II,KK) )
BUPPER = XKM(II,KK) + SIGV
BLOWER = XKM(II,KK) - SIGV
C
C PVAR(II,1) = BUPPER
PVAR(II,2) = XKM(II,KK)
PVAR(II,3) = BLOWER
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```
C
110  CONTINUE
C
C   WRITE(3, 903) ((PVAR(II, JJ), JJ = 1, 3), II = 1, IMAX)
C
C   WRITE(*, 904) KK
C   WRITE(*,6) YLBFIL(1,KK)
C   YLAB(1) = YLBFIL(1,KK)
C   YLAB(2) = YLBFIL(2,KK)
C   YLAB(3) = YLBFIL(3,KK)
C   WRITE(*,6)(YLAB(L),L=1,3)
C
C   YMIN = PVAR(1,3)
C   YMAX = PVAR(1,1)
C
C   DO 120 II = 1, IMAX
C   YMIN = AMIN1( PVAR(II,3), YMIN )
C   YMAX = AMAX1( PVAR(II,1), YMAX )
120  CONTINUE
C
C   CALL PLOT2 ( XMIN, XMAX, YMIN, YMAX )
C   CALL PLOT3 ( '+', T(1), PVAR(1,1), IMAX )
C   CALL PLOT3 ( '.', T(1), PVAR(1,2), IMAX )
C   CALL PLOT3 ( '-', T(1), PVAR(1,3), IMAX )
C   CALL PLOT4 ( 9,'TIME (SEC)',6,YLAB(1),13,'PLTFIL ESTIMATE ' )
C
200  CONTINUE
C
C   DO 300 JJ = 1, 15
C
C   DO 210 II = 1, IMAX
C
C   SIGR = SQRT ( COVZ(II, JJ) )
C
C   PVAR(II,1) = SIGR
C   PVAR(II,2) = RESID(II,JJ)
C   PVAR(II,3) = -SIGR
C
210  CONTINUE
C
C   WRITE(3, 903) ((PVAR(II,KK), KK = 1, 3), II = 1, IMAX)
C
C   YLAB(1) = YLBFIL(1,JJ+30)
C   YLAB(2) = YLBFIL(2,JJ+30)
C   YLAB(3) = YLBFIL(3,JJ+30)
C
C   YMIN = PVAR(1,3)
C   YMAX = PVAR(1,1)
C
C   DO 220 II = 1, IMAX
C   YMIN = AMIN1 ( PVAR(II,3), YMIN )
C   YMIN = AMIN1 ( PVAR(II,2), YMIN )
C   YMAX = AMAX1 ( PVAR(II,1), YMAX )
C   YMAX = AMAX1 ( PVAR(II,2), YMAX )
220  CONTINUE
C
C   WRITE(*, 904) JJ
C   WRITE(*, 6) YLBFIL(1,JJ+30)
C   CALL PLOT2 ( XMIN, XMAX, YMIN, YMAX )
C   CALL PLOT3 ( '-', T(1), PVAR(1,1), IMAX )
```

```
CALL PLOT3 ( '+', T(1), PVAR(1,2), IMAX )
CALL PLOT3 ( '-', T(1), PVAR(1,3), IMAX )
CALL PLOT4 ( 9,'TIME (SEC)',6,YLAB(1),13,'PLTFIL RESIDUAL ' )
C
300  CONTINUE
C
C      CLOSE ( UNIT=1 )
C      CLOSE ( UNIT=3 )
C
STOP
C
901  FORMAT( 2E15.8, 2I5 )
902  FORMAT( 5E15.8 )
903  FORMAT( 5X, 3E15.8 )
904  FORMAT( 2X, I5 )
C
END
```



```

C
C
COMMON / EARTH / GRAV(3) , AGMX(3,3)
COMMON / RDMEAS / AZM(5) , ELM(5) , RNGM(5)
COMMON / RDREST / AZHAT(5) , ELHAT(5) , RNGHAT(5)
COMMON / PROPAG / XKP(30) , PKP(30,30)
COMMON / PREUP / XKW(30) , PKW(30,30)
COMMON / UDWORK / RH(30) , U(465) , PO(465) , SF(465) , SG(30) , RESID , COVZ
COMMON / UDWRK2 / PHI(30,30) , PHIU(30,30) , W(30,54)
1      COMMON / SNOWRK / D(30) , D((30)) , DW(54) , V(54)
COMMON / RSTATE / TMP(30,24) , GT(24,30) , QGQT(30,30)
1      COMMON / RSTATE / RBRI(3) , VBRI(3) , ABRI(3) , THTI(3)
1      COMMON / GRAV1 / GRAV1(3) , CIBRI(3,3) , CBIEF(3,3) , CEFBRI(3,3)
2      COMMON / RITO / RITO(3) , VITO(3) , REF(3) , ANET(3) , OMEG(3)
2      COMMON / TALT / TALT(400) , TSRHO(400) , TSP(400) , TSSUND(400)
1      COMMON / USRHO / 'TVWX(400)' , 'TVWY(400)' , 'NALT'
2      COMMON / USRHO / 'USRHO(400)' , 'USP(400)' , 'USSUND(400)'
3      COMMON / USRHO / 'UVWX(400)' , 'UVWY(400)'

C
C
BLOCK DATA
C
C
COMMON / TIMDAT / TIME , TMAX , HSTEP , TSAMP , TSTOP
COMMON / ITYPE / ISMOOTH
COMMON / IREFOUT / IASSES S
COMMON / EDATA / RE , FLAT , OMEGE , XNU , XJ2
COMMON / CONST / CRAD , AGRAD , HRSEC , PERNT , XMRAD
COMMON / LAUCOR / OLAUT , OLONG , OHT
1      COMMON / RDRDAT / XNO(5) , RLAT(5) , RLONG(5) , RHT(5) , NRDR
COMMON / APRIOR / ER(3) , EV(3)
1      COMMON / ETLT / ETLT(3) , EAB(3) , EASF(3) , EGRV(3) , EX(3)
2      COMMON / ERDR / ERDR(3)
COMMON / NOISES / R(3) , G(30,24) , Q(24,24) , NP
COMMON / FPARAM / TAUT(3) , TAU(3) , TAUS(3) , TAUG(3) , TAUR(3)
1      COMMON / LINFMT / UT(3) , UA(3) , US(3) , UG(3) , UX(3) , UR(3)
COMMON / LINHMT / F(30,30) , N
COMMON / NRMENS / H(15,30) , NRMENS

C
OPEN( UNIT=2 , FILE='TRACK.DAT' , STATUS='OLD' )
OPEN( UNIT=3 , FILE='REFIPT.DAT' , STATUS='OLD' )
OPEN( UNIT=6 , FILE='LFILOUT.DAT' , STATUS='NEW'
1      , ACCESS='SEQUENTIAL' , FORM='UNFORMATTED' )

C
IF ( ISMOOTH.EQ.1 ) THEN
OPEN( UNIT=7 , FILE='SREFIPT.DAT' , STATUS='NEW' )
1C   ACCESS='SEQUENTIAL' , FORM='UNFORMATTED' )
OPEN( UNIT=8 , FILE='SMOIFT.DAT' , STATUS='NEW'
1      , ACCESS='SEQUENTIAL' , FORM='UNFORMATTED' )
ELSE
END IF

C
IF ( IASSES.S.EQ.1 ) THEN
OPEN( UNIT=4 , FILE='METDAT.DAT' , STATUS='OLD' )

C
DO 20 I = 1 , NALT
READ(4,998) TALT(I) , TSRHO(I) , TSP(I) , TSSUND(I) , TVWX(I) , TVWY(I)
READ(4,999) USRHO(I) , USP(I) , USSUND(I) , UVWX(I) , UVWY(I)
WRITE(*,997) TALT(I) , TSRHO(I) , TSP(I) , TSSUND(I)
CONTINUE
20
CLOSE( UNIT=4 )

C
OPEN( UNIT=9 , FILE='LASSOUT.DAT' , STATUS='NEW' )
1      , ACCESS='DIRECT' , RECL=90 , IOSTAT=IOS )
C

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ELSE
END IF

C      KTEST = TSAMP/HSTEP
C      CALL INITIL
C      CONTINUE
C      50
C      TIME = TIME + HSTEP
C      CALL UDTIME
C      KS = KS + 1
IF( KS - KTEST ) 200, 100, 100
CONTINUE
KS = 0

C      CALL GETDAT( TIME )
C      CALL RADAR
C      IF ( TASSESS.EQ.1 ) THEN
C          CALL ASSESS
C          ELSE
C          END IF
C          GO TO 800
C          200
CONTINUE
C          800
CONTINUE
C          IF( TIME - TMAX ) 50, 900, 900
C          900
CONTINUE
C          CLOSE( UNIT=2 )
CLOSE( UNIT=3 )
CLOSE( UNIT=6 )
CLOSE( UNIT=7 )
CLOSE( UNIT=8 )
CLOSE( UNIT=9 )

C          901
FORMAT( 15 )
902
FORMAT( 5X, 3E15.8 )
997
FORMAT( 3X, 5E15.8 )
998
FORMAT( 5X, 6E15.8 )
999
FORMAT( 20X, 5E15.8 )

C          STOP
END
SUBROUTINE GETDAT( TIME )
C      DIMENSION ACC(3), VOLD(3),
1      , VEC1(3), VEC2(3)

C      COMMON / RDRDAT / XNO(5), RLAT(5), RLONG(5), RHT(5), NRDR
COMMON / EARTH / GRAV(3), AGMX(3,3)
COMMON / RSTATE / RBRI(3), VBRI(3), ABRI(3), THTI(3),
1      , GRAVI(3), CIBRI(3,3), CERBRI(3,3), CEFBRI(3,3)
2      , RITO(3), VITO(3), REF(3), ANET(3), OMEG(3)
C      COMMON / RDMEAS / AZM(5), ELM(5), RNGM(5)

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```
C DATA VOID / 3*0.0 /
DATA VOID / 3*0.0 /
C CALL ZEROM( RNGM, 5, 1 )
READ( 2, 901, END=100 ) RTIME
READ( 2, 901 ) AZM(I), ELM(I), RNGM(I), I = 1, NRDR )
100 CONTINUE
READ( 3, 901 ) XMTIME
READ( 3, 901 ) ABRI(I), I = 1, 3 )
READ( 3, 901 ) THTI(I), I = 1, 3 )
READ( 3, 901 ) OMEG(I), I = 1, 3 )
IF ( TIME.GT.125. ) RNGM(3) = 0.0
C IF ( THTI(1).LT.0.0 ) THTI(1) = 360. + THTI(1)
OOSAMP = 1.0/0.96
CALL SMLT( OOSAMP, ABRI, ABRI, 3, 1 )
C RETURN
C 901 FORMAT( 5X, 3E15.8 )
C END
?
```

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BLOCK DATA

```

C COMMON / TIMDAT / TIME, TMAX, HSTEP, TSAMP, TSTOP
C COMMON / ITYPE / ISMOOTH
C COMMON / IREFOUT / IASSESS
C COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2
C COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
C COMMON / LAUCOR / OLATD, OLONG, OHT
1 COMMON / RDRDAT / XNO(5), RLAT(5), RLONG(5), RHT(5), NRDR
COMMON / APRIOR / ER(3), EV(3)
1 ETLT(3), EAB(3), EASF(3), EGRV(3), EX(3)
2 ERDR(3)
COMMON / NOISES / R(3), G(30,24), Q(24,24), NP
COMMON / FPARAM / TAUT(3), TAUA(3), TAUS(3), TAUG(3), TAUX(3), TAUR(3)
1 UT(3), UA(3), US(3), UG(3), UX(3), UR(3)
COMMON / LINFMNT / F(30,30), N
COMMON / LINHMT / H(15,30), NRMEAS
COMMON / METEOR / TALT(400), TSRHO(400), TSP(400), TSSUND(400),
1 , TVWX(400), TVWY(400), NALT
2 , USRHO(400), USP(400), USSUND(400)
3 , UVWX(400), UVWY(400)

C DATA TIME, TMAX, HSTEP, TSAMP / 0.0, 523., 1.0, 1.0 /
C
C DATA ISMOOTH / 1 /
C DATA IASSESS / 0 /
C
C DATA NALT / 400 /
C
C DATA N / 30 /
C DATA NP / 24 /
C DATA NRMEAS / 5 /
C DATA NRMEAS / 15 /
C DATA F / 900*0.0 /
C DATA H / 450*0.0 /
C DATA G / 720*0.0 /
C DATA Q / 576*0.0 /
C
C DATA CRAD / 57.295779 /
C DATA AGRAV, HRSEC, PERCNT, XMRAD / 32.174, 3600., 100., 1000. /
C DATA RE, FLAT, OMEGE, XMU, XJ2 / 20925606., 298.257224, .7292155E-4
C FISCHDATA RE, FLAT, OMEGE, XMU, XJ2 / 20925741., 298.3, 0.7292115E-4
1, 1.4076468E+16, .10827E-2 /
C
C DATA ER / 2*10.0,10.0 /
C DATA EV / 2*1.0,1.0 /
C DATA ETLT / 3*2.E-2 /
C DATA EAB / 3*0.1 /
C DATA EASF / 3*0.1 /
C DATA EGRV / 3*0.0 /
C DATA EX / 3*1.0E+0 /
C DATA ERDR / 1.E-2,1.E-1,1.E+2 /
C
C DATA TAUT / 3*100. /
C DATA TAUA / 3*100. /
C DATA TAUS / 3*100. /
C DATA TAUG / 3*200. /
C DATA TAUX / 3*200. /
C DATA TAUR / 3*400. /
C
C DATA UT / 3*2.E-2 /
C DATA UA / 3*0.1 /
C DATA US / 3*0.1 /
C DATA UG / 3*0.0 /
C DATA UV / 3*1.E+0 /

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```
C DATA NRDR / 5 /
DATA XNO / 4*0.0 , 0.0000 /
DATA RLAT / 28.226391,28.463168,28.625932,26.983000,28.424700 /
DATA RLONG / -80.599287,-80.583111,-80.682805,-80.108204,-80.664399 /
DATA RHT / -44., -49., -58., -21., -56. /
C61CFEDATA RLAT / 28.226553,28.528885,28.626090,26.615781,32.348051 /
C61CFEDATA RLONG / -80.599293,-80.590225,-80.682808,-78.347837,-64.653613 /
C61CFEDATA RHT / 65., 37., 52., 63., 75. /

C DATA R / 1.E-4,1.E-4,1.E+4 /
C
DATA OLATD, OLONG, OHT / 28.62721, -80.62079, 0.0 /
C39AFEDATA OLATD, OLONG, OHT / 28.608420, -80.604089, 0.0 /
DATA CM50EF / 422004, 490734, 762294, 233136, -871298
1 , 431842, .876105, -.004520, -.482099 /

C END
?
```

SUBROUTINE INITIL

```

C      DIMENSION CUENED(3,3),VEC(3),TMP1(3,3),TMP2(3,3),TMP3(3,3)
C
C      COMMON / LAUCOR / OLATD, OLONG, OHT
1     COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2
C      COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
C      COMMON / APRIOR / ER(3), EV(3)
1     'ETLT(3), EAB(3), EASF(3), EGRV(3), EX(3)
2     'ERDR(3)
C
C      COMMON / LINFMT / F(30,30), N
C      COMMON / PROPAG / X(30), PXP(30,30)
C      COMMON / PREUP / XKM(30), PKM(30,30)
C      COMMON / UDWORK / RH(30), U(465), PO(465), SF(465), SG(30), RESID, COVZ
C      COMMON / RSTATE / RBRI(3), VBR(3), ABRI(3), THTI(3)
1     'GRAVI(3), CIBRI(3,3), CEFBRI(3,3), CEFBRI(3,3)
2     'RITO(3), VITO(3), REF(3), ANET(3), OMEG(3)
C
C      DATA CUENED / 2*0.0,-1.0,0.0,1.0,0.0,1.0,2*0.0 /
C
C      C*** COMPUTE TRANSFORMATION FROM EARTH CENTERED INERTIAL TO BRI
C
C      CALL ECPOS ( OLATD, OLONG, OHT, VEC(1), VEC(2), VEC(3) )
C      CALL ECPOS ( OLATD, OLONG, 0.0, X0, Y0, Z0 )
C      CIEFMX ( 0.0, TMP1 )
C      CALL TMATY ( -OLONG, TMP2 )
C      CALL MULT ( TMP1, TMP2, TMP3, 3, 3 )
C
C      E = 1.0/FLAT
RDMAG = SQRT( X0**2 + Y0**2 )
RMAG = SQRT( VEC(1)**2 + VEC(2)**2 + VEC(3)**2 )
DEV = CRAD*2.*E*(1.-E/2.)*(RDMAG/RMAG)*SIN(3.1415926-OLATD/CRAD)
OLATC = OLATD - DEV
C
C      CALL TMATP ( OLATD, TMP1 )
CALL MULT ( TMP1, TMP3, TMP2, 3, 3 )
CALL MULT ( CUENED, TMP2, CIBRI, 3, 3 )
C
C      C*** TIME ZERO VEHICLE POSITION IN BOOST REFERENCE FRAME
C
C      WRITE(*,901) ((CIBRI(I,J), J = 1, 3), I = 1, 3)
CALL MULT ( CIBRI, VEC, RBRI, 3, 3, 1 )
WRITE(*,901) (RBRI(I), I = 1, 3)
CALL SWITCH ( RBRI, RITO, 3, 1 )
C
C      VITO(1) = 0.0
VITO(2) = 0.0
VITO(3) = OMEGE
C
C      CALL MULT ( CIBRI, VITO, VEC, 3, 3, 1 )
CALL SKEW ( RBRI, TMP1 )
CALL SMLT ( -1.0, TMP1, TMP2, 3, 3 )
CALL MULT ( TMP1, VEC, VBR(3,3,1) )
WRITE(*,901) (VBR(1,I), I = 1, 3)
CALL SWITCH ( VBR(1,3,1) )
C
C      CALL CIEFMX ( TIME, TMP1 )
CALL TRANS ( TMP1, TMP2, 3, 3 )
CALL MULT ( CIBRI, TMP2, CEFBRI, 3, 3 )
CALL TRANS ( CEFBRI, CIBRI, 3, 3 )
C
C      C*** TIME ZERO SENSED ACCELERATION IN BOOST REFERENCE FRAME
C
C      ABRI(1) = 0.0
C      ABRI(1) = 0.0

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C      BRI (77) - A
C      *** INITIALIZE ERROR COVARIANCES AND U-D FACTOR
C
C      DO 100 I = 1, 3
C
C      POSITION AND VELOCITY ERROR IN BRI
C
C      XKM(I) = 0.0
C      XKM(I+3) = 0.0
C      X(I) = XKM(I)
C      X(I+3) = XKM(I+3)
C      PKM(I,I) = ER(I)**2
C      PKM(I+3,I+3) = EV(I)**2
C
C      PLATFORM TILT, ACCELEROMETER BIAS AND SCALE FACTOR
C
C      PKM(I+6,I+6) = (ETLT(I)/CRAD)**2
C      PKM(I+9,I+9) = (EAB(I)**2
C      PKM(I+12,I+12) = (EX(I)/(CRAD*HERSEC))**2
C      PKM(I+12,I+12) = (EASF(I)/PERCNT)**2
C
C      RADAR TRACK AZIMUTH, ELEVATION AND RANGE BIASES
C
C      PKM(I+15,I+15) = (ERDR(I))**2
C      PKM(I+18,I+18) = (ERDR(I))**2
C      PKM(I+21,I+21) = (ERDR(I))**2
C      PKM(I+24,I+24) = (ERDR(I))**2
C      PKM(I+27,I+27) = (ERDR(I))**2
C
C      100  CONTINUE
C
C      WRITE(*, 901) (PKM(I,I), I = 1, N)
C
C      KJ = 0
C      DO 200 J = 1, N
C      DO 200 K = 1, J
C      KJ = KJ + 1
C      U(KJ) = PKM(K,J)
C
C      200  CONTINUE
C
C      CALL COV2UD ( U, N )
C
C      RETURN
C
C      901  FORMAT( 5X, 3E15.8 )
C
C      END
C
C

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SUBROUTINE UDTIME

```

C      COMMON / TIMDAT / TIME, TMAX, HSTEP, TSAMP, TSTOP
C      COMMON / ITYPE / ISMOOTH
C      COMMON / LINFMT / F(30,30), N
C      COMMON / LINHMT / H(15,30), NMEAS
C      COMMON / NOISES / R(3), G(30,24), Q(24,24), NP
C      COMMON / PROPAG / X(30), PKP(30,30)
C      COMMON / PREUP / XKM(30), PKM(30,30)
C      COMMON / RSTATE / RBRI(3), VBRI(3), ABRI(3), THTI(3),
C      , GRAVI(3), CIBRI(3,3), CBRIEF(3,3), CEFBRI(3,3)
C      1   , RIT0(3), VITO(3), REF(3), ANET(3), OMEG(3)
C      2   COMMON / UDWORK / RH(30), U(465), PO(465), SF(465), SG(30), RESID, COVZ
C      COMMON / UDWRK2 / PHI(30,30), PHIU(30,30), W(30,54),
C      , D(30), B(24), DW(54), V(54)
C
C      NPNP = N + NP
C      NP1 = N + 1
C
C      C** FORM SYSTEM LINEARIZED DYNAMICS MATRICIES F, G AND Q
C
C      CALL SYSTEM
C
C      C** COMPUTE STATE TRANSITION MATRIX PHI
C
C      DO 20 I = 1, N
C      DO 10 J = 1, N
C      PHI(I,J) = F(I,J) * HSTEP
C
C      10 CONTINUE
C      PHI(I,I) = 1.0 + PHI(I,I)
C
C      20 CONTINUE
C
C      C** PROPAGATE STATE ERROR ESTIMATES FORWARD IN TIME
C
C      DO 22 I = 1, N
C      SUM = 0.0
C      DO 21 J = 1, N
C      SUM = SUM + PHI(I,J) * XKM(J)
C
C      21 CONTINUE
C      X(I) = SUM
C
C      22 CONTINUE
C
C      DO 25 I = 1, 3
C      RBRI(I) = RBRI(I) + VBRI(I)*HSTEP + 0.5*ANET(I)*HSTEP*HSTEP
C      VBRI(I) = VBRI(I) + ANET(I)*HSTEP
C
C      25 CONTINUE
C
C      C** COMPUTE PRODUCT OF PHI AND U OF THE U-D FACTOR
C
C      CALL XPHIU ( PHI, N, N, U, N, PHIU, N )
C
C      CALL IMBED ( PHIU, N, N, W, N, NPNP, 1, 1 )
C      CALL IMBED ( G, N, NP, W, N, NPNP, 1, NP1 )
C
C      DO 30 I = 1, NP
C      B(I) = Q(I,I)*HSTEP
C
C      30 CONTINUE
C
C      DO 40 L = 1, N
C      J = NP1 - L
C      KJ = J*(J+1)/2
C      D(J) = U(KJ)
C
C      40 CONTINUE
C
C      CALL IMBED ( D, N, 1, DW, NPNP, 1, 1, 1 )
C      CALL IMBED ( P, NP, 1, DW, NPNP, 1, NP1, 1 )

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```
C      WEIGHTED GRAMM-SCHMIDT FACTORIZATION FOR TIME UPDATE
C
C      CALL WGS ( W, N, N, NPNP, DW, U, V )
C
C      CALL UD2COV ( U, PO, N )
C
C      IJ = 0
DO 100 J = 1, N
DO 100 I = 1, J
IJ = IJ + 1
PKP(I,J) = PO(IJ)
PKP(J,I) = PKP(I,J)
100  CONTINUE
C
C      CALL SWITCH ( X, XKM, N, 1 )
C
C      RETURN
C
C      991  FORMAT( 3X, 9E8.2 )
992  FORMAT ( / )
C
C      END
C
C      §
```

SUBROUTINE RADAR

ROGERS ENGINEERING & ASSOCIATES

42

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```

C
C      DIMENSION RRDR(3),CEFLLR(3,3),TMP(3,3),UTEMP(465)
1
C      COMMON / TIMDAT / TIME, TMAX, HSTEP, TSAMP, TSTOP
C      COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
C      COMMON / RSTATE / RBRI(3),VBRI(3),ABRI(3),THTI(3)
1
2      ,GRAVI(3),CIBRI(3,3),CBRIEF(3,3),CEFBRI(3,3)
C      COMMON / NOISES / R(3), VITO(3),REP(3),ANET(3),OMEG(3)
C      COMMON / LINFMNT / F(30,30), N
C      COMMON / LINHMT / H(15,30), NMES
C      COMMON / RDRDAT / XNO(5),RLAT(5), RLONG(5), RHT(5), NR
C      COMMON / RDMEAS / AZM(5), ELM(5), RNGM(5)
C      COMMON / RDREST / AZHAT(5), ELHAT(5), RNGHAT(5)
C      COMMON / PREUP / XKM(30,30), PKM(30,30)
C      COMMON / PROPAG / X(30), PKP(30,30)
C      COMMON / UDWORK / RH(30), U(465), PO(465), SF(465), SG(30), RESID, COVZ

C      DATA IAZ, IEL, IRG / 16, 17, 18 /
C      DATA C1 / 2*0.01.0, 1.0, 3*0.0, 1.0, 0.0 /
C      DATA CS / 9.8356796E+8 /

C      KMEAS = 0

C      COMPUTE VEHICLE POSITION IN EARTH CENTERED EARTH FIXED COORDINATES
C
C      CALL CIEFMX ( TIME, TMP )
C      CALL TRANS ( TMP, TMP1, 3, 3 )
C      CALL MULT ( CIBRI, TMP1, CEFBRI, 3, 3 )
C      CALL TRANS ( CEFBRI, CBRIEF, 3, 3 )

C      PROCESS MEASUREMENTS FOR EACH RADAR
C
C      DO 300 IR = 1, NR
C      DO 100 I = 1, 3
C      DR(I) = XKM(I)
C      CONTINUE
100

C      CALL SUBT ( VBRI, VITO, RRDR, 3, 1 )
C      CALL MULT ( CBRIEF, RRDR, DR, 3, 3, 1 )
C      CALL ECPOS(RLAT(IR),RLONG(IR),RHT(IR),RRDR(1),RRDR(2),RRDR(3))
C      CALL SUBT ( REF, RRDR, VC, 3, 1 )
C      RVCORR = -RRATE/CS

C      CALL TMATY ( -RLONG(IR), TMP1 )
C      CALL TMATP ( RLAT(IR), CEFLLR )
C      CALL MULT ( CEFLLR, TMP1, TMP, 3, 3, 3 )
C      CALL MULT ( C1, TMP, CEFLLR, 3, 3, 3 )
C      CALL MULT ( CEFLLR, VC, DR, 3, 3, 1 )
C      CALL TRANS ( CEFBRI, TMP1, 3, 3 )
C      CALL MULT ( CEFLLR, TMP1, TMP, 3, 3 )

RNGES = DR(1)*DR(1) + DR(2)*DR(2) + DR(3)*DR(3)
RNGH = SQRT(RNGES)
XYs = RNGES - DR(3)*DR(3)
XY = SQRT(XYs)
AZHAT(IR) = CRAD*ATAN2(DR(1),DR(2)) + XKM(3*(IR-1) + IAZ)
ELH = CRAD*ATAN(DR(3)/XY)
CALL ECAC(ELH, ELM, RNGH, DEL, DRANGE)

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C   :LHAT(IR) = X(IR) + Y(IR)*(IR-1) + DE(IR)
C   RNGHAT(IR) = RNHG + RVCORR + XKM(3*(IR-1) + IRG) + DRAIGE
C
C   MEASUREMENT LINEARIZATION - AZIMUTH
C
C   VC(1) = CRAD*DR(2)/XYS
C   VC(2) = -CRAD*DR(1)/XYS
C   VC(3) = 0.0
C
C   H(3*(IR-1)+1,1)=VC(1)*TMP(1,1)+VC(2)*TMP(2,1)+VC(3)*TMP(3,1)
C   H(3*(IR-1)+1,2)=VC(1)*TMP(1,2)+VC(2)*TMP(2,2)+VC(3)*TMP(3,2)
C   H(3*(IR-1)+1,3)=VC(1)*TMP(1,3)+VC(2)*TMP(2,3)+VC(3)*TMP(3,3)
C
C   H(3*(IR-1)+1,3*(IR-1)+IAZ) = 1.0
C
C   MEASUREMENT LINEARIZATION - ELEVATION
C
C   VC(1) = -CRAD*DR(1)*DR(3)/(RNGES*XY)
C   VC(2) = -CRAD*DR(2)*DR(3)/(RNGES*XY)
C   VC(3) = CRAD*XY/RNGES
C
C   H(3*(IR-1)+2,1)=VC(1)*TMP(1,1)+VC(2)*TMP(2,1)+VC(3)*TMP(3,1)
C   H(3*(IR-1)+2,2)=VC(1)*TMP(1,2)+VC(2)*TMP(2,2)+VC(3)*TMP(3,2)
C   H(3*(IR-1)+2,3)=VC(1)*TMP(1,3)+VC(2)*TMP(2,3)+VC(3)*TMP(3,3)
C
C   H(3*(IR-1)+2,3*(IR-1)+IEL) = 1.0
C
C   MEASUREMENT LINEARIZATION - RANGE
C
C   VC(1) = DR(1)/RNGHAT(IR)
C   VC(2) = DR(2)/RNGHAT(IR)
C   VC(3) = DR(3)/RNGHAT(IR)
C
C   H(3*(IR-1)+3,1)=VC(1)*TMP(1,1)+VC(2)*TMP(2,1)+VC(3)*TMP(3,1)
C   H(3*(IR-1)+3,2)=VC(1)*TMP(1,2)+VC(2)*TMP(2,2)+VC(3)*TMP(3,2)
C   H(3*(IR-1)+3,3)=VC(1)*TMP(1,3)+VC(2)*TMP(2,3)+VC(3)*TMP(3,3)
C
C   H(3*(IR-1)+3,3*(IR-1)+IRG) = 1.0
C
C   PROCESS AZIMUTH, ELEVATION AND RANGE MEASUREMENTS
C
C   DO 200 IM = 1, 3
C
C   KMEAS = KMEAS + 1
C
C   IF( RNGM(IR).EQ.0.0 ) THEN
C     RESID = 0.0
C     COVZ = 0.0
C     CALL ZEROM( RH, N, 1 )
C   ELSE
C
C     UDU*T FACTORED COVARIANCE UPDATE
C
C     DO 140 J = 1, N
C       RH(J) = H(KMEAS,J)
C
C     CONTINUE
C
C   CALL SWITCH( U, UTEMP, 465, 1 )
C   RR = R(IM)
C   ALPHA = -1.0
C   CALL UDMEAS( U, N, RR, RH, SF, SG, ALPHA )
C
C   IF( IM.EQ.1 ) THEN
C     RESID = AZM(IR) - AZHAT(IR)
C

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```
C      IF ( IM.EQ.2 ) THEN
C      RESID = ELM(IR) - ELHAT(IR)
C
C      ELSE
C      RESID = RNGM(IR) - RNGHAT(IR)
C
C      END IF
C
C      COVZ = ALPHA
C
C      IF ( ABS(RESID).GT.(6.*SQRT(COVZ)) ) THEN
C
C      COVZ = 0.0
C      CALL SWITCH ( UTEMP, U, 465, 1 )
C      GO TO 190
C
C      ELSE
C      END IF
C
C      DO 150 J = 1, N
C      XKM(J) = XKM(J) + (SG(J)/ALPHA)*RESID
C      150  CONTINUE
C
C      END IF
C
C      CONVERT U-D FACTORS TO COVARIANCE MATRICES FOR OUTPUT
C
C      CALL UD2COV( U, PO, N )
C
C      IJ = 0
C      DO 160 J = 1, N
C      DO 160 I = 1, J
C      IJ = IJ + 1
C      PKM(I,J) = PO(IJ)
C      PKM(J,I) = PKM(I,J)
C      160  CONTINUE
C
C      CONTINUE
C
C      CALL OUTPUT
C
C      200  CONTINUE
C
C      300  CONTINUE
C
C      RETURN
C
C      995  FORMAT( 3X, 5E15.8 )
C      998  FORMAT( 7X, 4E15.8 )
C      997  FORMAT( 5X, 3E15.8 )
C
C      END
C
C
```

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```

C      COMMON / TIMDAT / TIME, TMAX, HSTEP, TSAMP, TSTOP
C      COMMON / ITYPE / ISMOOTH
C      COMMON / PREUP / XKM(30), PKM(30,30)
C      COMMON / LINPFT / F(30,30), N
C      COMMON / UDWORK / RH(30), U(465), PO(465), SF(465), SG(30), RESID, COVZ
C      COMMON / SMOVRK / TMP(30,24), GT(24,30), QGQT(30,30)
C      COMMON / LINHMT / R(15,30), NMEAS
C      COMMON / NOISES / R(3), G(30,24), Q(24,24), NP
C      COMMON / RSTATE / RBRI(3), VBRI(3), ABRI(3), THTI(3)
C      , GRAVI(3), CIBRI(3,3), CBRIEF(3,3), CEFBRI(3,3)
C      , RITO(3), VITO(3), REF(3), ANET(3), OMEG(3)
C
C      DATA KO / 0 /
C      DATA TLAST / 0.0 /
C
C      KO = KO + 1
C
C      WRITE(6) TIME, TLAST, KO, NMEAS
C      WRITE(6) (XKM(I), I = 1, N)
C      WRITE(6) (PKM(I,I), I = 1, N)
C      WRITE(6, 902) (RH(I), I = 1, N)
C      WRITE(6) COVZ
C      WRITE(6) RESID
C
C      IF ( KO - NMEAS ) 20, 10, 10
10    CONTINUE
C
C      WRITE(*, 901) TIME, TLAST, KO, NMEAS
C
C      IF ( ISMOOTH.EQ.1 ) THEN
C
C      CALL TRANS ( G, GT, N, NP )
C      CALL MULT ( Q, GT, TMP, NP, NP, N )
C      CALL MULT ( G, TMP, QGQT, N, NP, N )
C
C      WRITE(7, 903) TIME
C      WRITE(7, 903) (ABRI(I), I = 1, 3)
C      WRITE(7, 903) (THTI(I), I = 1, 3)
C      WRITE(7, 903) (OMEG(I), I = 1, 3)
C      WRITE(7, 903) (RBRI(I), I = 1, 3)
C      WRITE(7, 903) (VBRI(I), I = 1, 3)
C      WRITE(7, 903) ((CIBRI(I,J), J = 1, 3), I = 1, 3)
C      WRITE(7, 903) ((CBRIEF(I,J), J = 1, 3), I = 1, 3)
C
C      WRITE(8) TIME, TLAST, KO, NMEAS
C      WRITE(8) (XKM(I), I = 1, N)
C      WRITE(8) ((PKM(I,J), J = 1, N), I = 1, N)
C      WRITE(8) ((F(I,J), J = 1, N), I = 1, N)
C      WRITE(8) ((GQGT(I,J), J = 1, N), I = 1, N)
C
C      ELSE
C      END IF
C
C      TLAST = TIME
C
C      KO = 0
C
C      20 CONTINUE
C
C      RETURN
C
C      901 FORMAT( 2E15.8, 2I5 )
C      902 FORMAT( 5E15.8 )
C      903 FORMAT( 4X, 3E15.8 )

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C DIMENSION UNIT(3,3),CBI(3,3),CIB(3,3),VB(3),AB(3)
1 ,VEC1(3),VEC2(3),VEC3(3),VEC4(3),VEC5(3)
2 ,TMP1(3,3),TMP2(3,3),TMP3(3,3),TMP4(3,3),TMP5(3,3)
3 ,VECX(3),VECY(3),VECZ(3),TMPX(3,3),TMPY(3,3),TMPZ(3,3)
4 ,TMPA(3,3),CCIB(3,3),VBR(3),RBR(3),ACC(3)
5 ,VW(3),VR(3),ARRAY(90),BARRY(90)
6 ,PVW(3,3),C1(3,3)
7 ,VEC6(6),VEC7(6)

C COMMON / TIMDAT / TIME, TMAX, HSTEP, TSAMP, TSTOP
COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2
COMMON / CONST / CRAD, AGRAV, HRSEC, PERCENT, XMRAD
COMMON / LAUCOR / OLATD, OLONG, OHT
1 COMMON / PREUP / XKM(30), PKM(30,30)
COMMON / EARTH / GRAV(3), AGMX(3,3)
COMMON / ESTATE / RBRI(3), VBRI(3), ABRI(3), THTI(3)
COMMON / RHO / PS, VSOUND / .002378, 2116., 1117. /
1 DATA WKX, VWY / 2*0.0 /
2 DATA PRHOPH, PSPH, PVSPH / 3*0.0 /
DATA PVWXPH, PVWYPH / 2*0.0 /
DATA PWV / 9*0.0 /
DATA C1 / 2*0.0,1.0,1.0,3*0.0,1.0,0.0 /
2 ,TUVK(400),TVWX(400),NALT
,USRHO(400),USP(400),USSUND(400)
,UVWX(400),UVWY(400)

C DATA UNIT / 1.,3*0.,1.,3*0.,1., /
DATA NR / 16 /
DATA RHO, PS, VSOUND / .002378, 2116., 1117. /
DATA WKX, VWY / 2*0.0 /
DATA PRHOPH, PSPH, PVSPH / 3*0.0 /
DATA PVWXPH, PVWYPH / 2*0.0 /
DATA PWV / 9*0.0 /
DATA C1 / 2*0.0,1.0,1.0,3*0.0,1.0,0.0 /
3 ,TUVK(400),TVWX(400),NALT
,USRHO(400),USP(400),USSUND(400)
,UVWX(400),UVWY(400)

C CALL CBIMX ( THTI, CBI )
CALL ZEROM ( ARRAY, 90, 1 )
CALL ZEROM ( BARRY, 90, 1 )
C CALL CBIMX ( THTI, CBI )
CALL TRANS ( CBI, CIB, 3, 3 )
C DO 20 I = 1, 3
DO 10 J = 1, 3
TMP1(I,J) = PKM(I,J)
TMP2(I,J) = PKM(I+3,J+3)
TMP3(I,J) = PKM(I+6,J+6)
TMP4(I,J) = PKM(I+9,J+9)
TMP5(I,J) = PKM(I+12,J+12)
CONTINUE
10 RBR(I) = BBRI(I) + XKW(I)
VBR(I) = VBR(I) + XKW(I+3)
VEC2(I) = VBR(I)
VEC3(I) = XKW(I+6)
VEC4(I) = XKW(I+9)
VEC5(I) = XKW(I+12)
CONTINUE
C CALL SKEW ( VEC3, TMPX )
CALL ADD ( UNIT, TMPX, TMPX, 3, 3 )
CALL MULT ( CIB, TMPX, CCIB, 3, 3 )
ARRAY(1) = TIME
BARRY(1) = 0.0
C VEHICLE POSITION
C ARRAY(2) = RBR(1)

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ARRAY(3) = RBR(2)
ARRAY(4) = RBR(3)
BRRAY(2) = SQRT( PKM(1,1) )
BRRAY(3) = SQRT( PKM(2,2) )
BRRAY(4) = SQRT( PKM(3,3) )

C
CALL COOR ( REF(1), REF(2), REF(3), XLAT, XLONG, ALT )
RM = SQRT ( REF(1)**2 + REF(2)**2 + REF(3)**2 )
XYSQR = REF(1)**2 + REF(2)**2
OMECC = 1.0 - 1.0/FLAT
ALT = ( 1.0 - RE*OMECC/SQRT( OMECC**2*XYSQR+REF(3)**2 ) )*RM
ARRAY(49) = XLONG
ARRAY(50) = XLAT
ARRAY(51) = ALT
ARRAY(54) = RM
BRRAY(49) = CRAD*SQRT( PKM(2,2) )/(RM*COS( XLAT/CRAD ) )
RMS = RM*RM
CALL MULT ( TMP1, RBR, VECX, 3, 3, 1 )
CALL INNER ( RBR, VECX, SIGRMS, 3 )
SIGRM = SQRT ( SIGRMS/RMS )
BRRAY(51) = SIGRM
BRRAY(54) = SIGRM

C
CALL ECPOS ( OLATD, OLONG, OHT, VECZ(1), VECZ(2), VECZ(3) )
DO 30 I = 1, 3
VECX(I) = REF(I) - VECZ(I)
CONTINUE
RS = SQRT( VECX(1)**2 + VECX(2)**2 + VECX(3)**2 )
AREAY(58) = RS
CALL MULT ( TMP1, VECX, VECY, 3, 3, 1 )
CALL INNER ( VECX, VECY, SIGRSS, 3 )
IF ( RS.NE.0.0 ) THEN
SIGRSS = SIGRSS/(RS*RS)
ELSE
SIGRSS = 0.0
END IF
BRRAY(58) = SQRT ( SIGRSS )

C ** BOOST REFERENCE VELOCITY AND UNCERTAINTY BOUNDS
C
VMI = SQRT ( VEC2(1)**2 + VEC2(2)**2 + VEC2(3)**2 )
AREAY(5) = VBR(1)
AREAY(6) = VBR(2)
AREAY(7) = VBR(3)
ARRAY(55) = VMI
BRRAY(5) = SQRT( PKM(4,4) )
BRRAY(6) = SQRT( PKM(5,5) )
BRRAY(7) = SQRT( PKM(6,6) )
VMIS = VMI*VMI
CALL MULT ( TMP2, VBR, VECX, 3, 3, 1 )
CALL INNER ( VBR, VECX, SIGVMS, 3 )
IF ( VMI.NE.0.0 ) THEN
SIGVM = SQRT ( SIGVMS/VMIS )
ELSE
SIGVM = 0.0
END IF
BRRAY(55) = SIGVM

C ** BODY REFERENCED VELOCITY AND UNCERTAINTY BOUNDS
C
CALL ZEROM ( VEC1, 3, 1 )
VEC1(3) = OMEGE
CALL SKEW ( VEC1, TMPX )
CALL MULT ( TMPX, REF, VEC1, 3, 3, 1 )
CALL MULT ( CMBR1, VEC1, VECX, 3, 3, 1 )

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C CALL [REDACTED] ( [REDACTED], VECX, 1, [REDACTED] )
C CALL MULT ( CCIB, VECY, VB, 3, 1, 1 )
C
C VT = SQRT ( VB(1)**2 + VB(2)**2 + VB(3)**2 )
C ARRAY(20) = VB(1)
C ARRAY(21) = VB(2)
C ARRAY(22) = VB(3)

C C* INERTIAL VELOCITY
C
C CALL MULT ( TMP2, CBI, TMPY, 3, 3, 3 )
C CALL MULT ( CIB, TMPY, TMPX, 3, 3, 3 )
C
C C* PLATFORM TILT
C
C CALL SKEW ( VEC2, TMPY )
C CALL MULT ( CIB, TMPY, TMPZ, 3, 3, 3 )
C CALL TRANS ( TMPZ, TMPA, 3, 3 )
C CALL MULT ( TMPZ, TMP3, TMPY, 3, 3, 3 )
C CALL MULT ( TMPY, TMPA, TMPZ, 3, 3, 3 )
C
C CALL ADD ( TMPX, TMPZ, TMPX, 3, 3 )
C BRAY(20) = SQRT( TMPX(1,1) )
C BRAY(21) = SQRT( TMPX(2,2) )
C BRAY(22) = SQRT( TMPX(3,3) )

C C* ANGLE OF ATTACK, SIDESLIP AND VELOCITY WRT AIR MASS W/UNCERTAIN
C IF ( ALT.LT.400000. ) THEN
C
C CALL INTRP1 ( ALT, TALT, TSRHO, NALT, RHO, PRHOPH )
C CALL INTRP1 ( ALT, TALT, TSP, NALT, PS, PSSPH )
C CALL INTRP1 ( ALT, TALT, TSSUND, NALT, VSOUND, PVSPPH )
C CALL INTRP1 ( ALT, TALT, TVWX, NALT, VWX, PVWXPH )
C CALL INTRP1 ( ALT, TALT, TVWY, NALT, VWY, PVWYPH )
C CALL INTRP1 ( ALT, TALT, USRHO, NALT, UNCRHO, SLOPE )
C CALL INTRP1 ( ALT, TALT, USP, NALT, UNCSP, SLOPE )
C CALL INTRP1 ( ALT, TALT, USSUND, NALT, UNCVS, SLOPE )
C CALL INTRP1 ( ALT, TALT, UVWX, NALT, UNCWX, SLOPE )
C CALL INTRP1 ( ALT, TALT, UVWY, NALT, UNCVY, SLOPE )

C ELSE
C END IF

C
C VW(1) = VWX
C VW(2) = VWY
C VW(3) = 0.0
C PW(1,1) = UNCWX
C PW(2,2) = UNCVY

C ATEMP = (VSOUND/49.02)**2
C ARRAY(79) = ATEMP
C ARRAY(80) = PS
C ARRAY(81) = RHO
C BRAY(79) = UNCVS*SQRT( ATEMP )*(2./49.02)
C BRAY(80) = UNCSP
C BRAY(81) = UNCRHO

C CALL TMATY ( -XLONG, TMPX )
C CALL TMATP ( XLAT, TMPY )
C CALL MULT ( TMPY, TMPX, TMPZ, 3, 3, 3 )
C CALL TRANS ( TMPZ, TMPX, TMPY, 3, 3, 3 )
C CALL MULT ( CEFBRI, TMPX, TMPY, 3, 3, 3 )
C CALL MULT ( TMPY, VW, VECX, 3, 3, 1 )
C CALL SUBT ( VB, VECX, VR, 3, 1 )

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VMA = SQRT( VR(1)**2 + VR(2)**2 + VR(3)**2 )
VMAS = VMA*VMA
ALPHA = CRAD*ATAN( VR(3)/VR(1) )
BETA = CRAD*ASIN( VR(2)/VMA )
ARRAY(68) = VMA
ARRAY(72) = ALPHA
ARRAY(84) = BETA

C
CALL TRANS( TMPY, TMPZ, 3, 3 )
CALL MULT( PVW, TMPZ, TMPA, 3, 3, 3 )
CALL MULT( TMPY, TMPA, TMPZ, 3, 3, 3 )
CALL ADD( TMPX, TMPZ, TMPX, 3, 3 )
BERRY(68) = SQRT( TMPX(1,1) + TMPX(2,2) + TMPX(3,3) )
V13S = VR(1)**2 + VR(3)**2
V13 = SQRT( V13S )
VECX(1) = -VR(3)/V13S
VECX(2) = 0.0
VECX(3) = VR(1)/V13S
CALL MULT( TMPX, VECX, VECY, 3, 3, 1 )
CALL INNER( VECX, VECY, SIGAS, 3 )
BERRY(72) = CRAD*SORT( SIGAS )

C IF ( V13.NE.0.0 ) THEN
  VECX(1) = VR(2)*VR(1)/(VMAS*V13)
  VECX(2) = VR(2)*VR(2)/(VMAS*V13)
  VECX(3) = VR(2)*VR(3)/(VMAS*V13)
  CALL MULT( TMPX, VECX, VECY, 3, 3, 1 )
  CALL INNER( VECX, VECY, SIGBS, 3 )
  CALL INNER( VECX, VECY, SIGBS, 3 )
  VECX(1) = 0.0
  VECX(2) = 1.0/V13
  VECX(3) = 0.0
  CALL MULT( TMPX, VECX, VECY, 3, 3, 1 )
  CALL INNER( VECX, VECY, SIGS, 3 )
  SIGB = SORT( SIGBS + SIGS )
  BERRY(84) = CRAD*SIGB

C ELSE
END IF

C C** MACH NUMBER AND DYNAMIC PRESSURE W/UNCERTAINTY BOUNDS
C
PDYNMC = 0.5*RHO*VMAS
XMACH = VMA/V SOUND
ARRAY(74) = PDYNMC
ARRAY(77) = XMACH
CALL MULT( TMPX, VR, VECX, 3, 3, 1 )
CALL INNER( VR, VECX, SIGVS, 3 )
SIGVS = RHO*SIGVS
SIGS = (0.5*VMAS*PRHOPH*SIGRM)**2
SIGQS = SIGQS + SIGS
BERRY(74) = SORT( SIGQS )
VSS = VSOUND*VSOUND
SIGMS = SIGVS/VSS
SIGS = (VMA*PVSPH*SIGRM/VSS)**2
SIGMS = SIGMS + SIGS
BERRY(84) = SORT( SIGMS )

C C** Q-ALPHA AND Q-BETA WITH UNCERTAINTY BOUNDS
C
QALPHA = PDYNMC*ALPHA
QBETA = PDYNMC*BETA
ARRAY(75) = QALPHA
ARRAY(76) = QBETA
ALPHAS = ALPHA*ALPHA
BETAS = BETA*BETA

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C      DYN [REDACTED] DYN
C      BRRAY(75) = SQRT(ALPHAS*BRRAY(74)**2 + PDYNS*BRRAY(72)**2)
C      BRRAY(76) = SQRT(BETAS*BRRAY(74)**2 + PDYNS*BRRAY(84)**2)

C    C** VEHICLE ATTITUDE AND UNCERTAINTY BOUNDS
C
C      CALL SMIT ( CRAD, VEC3, VEC3, 3, 1 )
C      CALL ADD ( THTI, VEC3, VEC3, 3, 1 )
C      DO 40 I = 1, 3
C      VECZ(I) = CRAD+SQRT(TMP3(I,I))
C
C      CONTINUE
C      ARRAY(85) = VEC3(3)
C      ARRAY(86) = VEC3(2)
C      ARRAY(87) = VEC3(1)
C      BRRAY(85) = VECZ(3)
C      BRRAY(86) = VECZ(2)
C      BRRAY(87) = VECZ(1)

C      (B) AND (I) REFERENCED ACCELERATION AND UNCERTAINTY BOUNDS
C
C      CALL ADD ( ABRI, VEC4, VEC1, 3, 1 )
C      CALL DIAG ( ABRI, 3, TMPX )
C      CALL MULT ( TMPX, VEC5, AB, 3, 3, 1 )
C      CALL ADD ( AB, VEC1, VEC1, 3, 1 )
C      ARRAY(8) = VEC1(1)
C      ARRAY(9) = VEC1(2)
C      ARRAY(10) = VEC1(3)

C      CALL MULT ( CCIB, VEC1, AB, 3, 3, 1 )
C
C      CRFTSTAT = SQRT( ABRI(1)**2 + ABRI(2)**2 + ABRI(3)**2 )
C      AT = SQRT( AB(1)**2 + AB(2)**2 + AB(3)**2 )
C      ARRAY(23) = AB(1)
C      ARRAY(24) = AB(2)
C      ARRAY(25) = AB(3)
C      ARRAY(83) = AT/AGRAV

C      C* ACCELEROMETER BIAS
C
C      TMP4
C
C      C* ACCELEROMETER SCALE FACTOR
C
C      CALL DIAG ( ABRI, 3, TMPZ )
C      CALL MULT ( TMPZ, TMP5, TMPX, 3, 3, 3 )

C      C* PLATFORM TILT
C
C      CALL SKW ( ABRI, TMPZ )
C      CALL MULT ( TMPZ, TMP3, TMPY, 3, 3, 3 )
C
C      CALL ADD ( TMP4, TMPX, TMPZ, 3, 3 )
C      CALL ADD ( TMPY, TMPZ, TMPX, 3, 3 )
C      BRRAY(8) = SQRT( TMPX(1,1) )
C      BRRAY(9) = SQRT( TMPX(2,2) )
C      BRRAY(10) = SQRT( TMPX(3,3) )

C      CALL MULT ( CIB, TMPX, TMPY, 3, 3, 3 )
C      CALL MULT ( TMPY, CBI, TMPX, 3, 3, 3 )
C      BRRAY(23) = SQRT( TMPX(1,1) )
C      BRRAY(24) = SQRT( TMPX(2,2) )
C      BRRAY(25) = SQRT( TMPX(3,3) )
C      BRRAY(83) = SQRT(BRRAY(23)**2+BRRAY(24)**2+BRRAY(25)**2)/AGRAV

C      C** FLIGHT PATH ANGLE
C

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CALL INNER ( RBR, VBR, RDOTV, 3 )
IF ( VMI.NE.0.0 ) THEN
  GAMMA = CRAD*ASIN( RDOTV/(RM*VMI) )
ELSE
  GAMMA = 0.0
END IF
ARRAY(56) = GAMMA

C
B = RM*VMI
RFAC = RDOTV/B
RFAC1 = RFAC*VMI/RM
RFAC2 = RFAC*RM/VMI
DENO = SQRT( B*B - RDOTV*RDOTV )
50
CONTINUE

C
DO 50 I = 1, 3
  VEC6(I) = ( VBR(I) + RFAC1*RBR(I) )/DENO
  VEC6(I+3) = ( RBR(I) + RFAC2*VBR(I) )/DENO
CONTINUE

C
DO 70 I = 1, 6
  TEMP = 0.0
  DO 60 J = 1, 6
    TEMP = TEMP + PKM(I,J)*VEC6(J)
    CONTINUE
  VEC7(I) = TEMP
  CONTINUE

C
SIGGMS = 0.0
DO 80 I = 1, 6
  SIGGMS = SIGGMS + VEC6(I)*VEC7(I)
CONTINUE
SIGGM = CRAD*SQRT ( SIGGMS )
BRRAY(56) = SIGGM

C
CALL TMATY ( -XLONG, TMPX )
CALL TMATP ( XLAT, TMPY )
CALL MULT ( TMPY, TMPX, TMPZ, 3, 3, 3 )
CALL MULT ( C1, TMPZ, TMPX, 3, 3, 3 )
CALL MULT ( CBRIEF, VBR, VECX, 3, 3, 1 )
CALL MULT ( TMPX, VECX, VECY, 3, 3, 1 )
IF ( VECY(2).NE.0.0 ) THEN
  SIGMA = CRAD*ATAN2( VECY(1), VECY(2) )
ELSE
  SIGMA = 90.0
END IF

C
ARRAY(57) = SIGMA

C
DENO = VECY(1)*VECY(1) + VECY(2)*VECY(2)
VECX(1) = VECY(2)/DENO
VECX(2) = VECY(1)/DENO
VECX(3) = 0.0

C
CALL TRANS ( TMPX, TMPY, 3, 3 )
CALL MULT ( TMPY, VECX, VECZ, 3, 3, 1 )
CALL MULT ( TMP2, VECZ, VECY, 3, 3, 1 )
CALL INNER ( VECX, VECY, SIGSMS, 3 )
IF ( SIGSMS.GE.0.0 ) THEN
  SIGSM = CRAD*SQRT ( SIGSMS )
END IF
BRRAY(57) = SIGSM

C
C * VEHICLE ROTATION RATE
C
ARRAY(45) = OMEG(3)
ARRAY(46) = OMEG(2)
ARRAY(47) = OMEG(1)

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```
C      ARRAY(1) = 0.0 (1)
C      C** OUTPUT COMPUTED QUANTITIES
C
C      WRITE(9,NR) (ARRAY(I), I = 1, 90)
C      WRITE(9, 902) (ARRAY(I), I = 1, 90)
C      WRITE(9, 902) (BARRY(I), I = 1, 90)
C      NR = NR + 1
C
C      RETURN
C
C      901  FORMAT ( 7X, 4E15.8 )
C      902  FORMAT ( 2X, 6E12.5 )
C
C      END
```

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SUBROUTINE SYSTEM

```

C   DIMENSION UNIT(3,3),TEMP(3,3),VEC(3)
C
C   COMMON / TIMDAT / TIME, TMAX, HSTEP, TSAMP, TSTOP
C   COMMON / RSTATE / VBRI(3),ABRI(3),THI(3)
C   COMMON / RSTATE / GRAVI(3),CIBRI(3,3),CBRIEF(3,3),CEFBRI(3,3)
C   1      ,RITO(3),VITO(3),REF(3),ANET(3),OMEG(3)
C   2      ,CONST / CRAD, AAGRAV, HRSEC, PERCNT, XMRAD
C   COMMON / EARTH / GRAV(3),AGMX(3,3)
C   COMMON / FPARAM / TAUT(3),TAUS(3),TAUS(3),TAUG(3),TAUX(3),TAUR(3)
C   1      ,UT(3),UA(3),US(3),UG(3),UX(3),UR(3)
C   COMMON / LINPNT / F(30,30),N
C   COMMON / NOISES / R(3),G(30,24),Q(24,24),NP
C
C   DATA JUMP / 0 /
C   DATA UNIT / 1.0, 3*0.0, 1.0, 3*0.0, 1.0 /
C
C   IF ( JUMP ) 10, 10, 20
C
C   10  CONTINUE
C
C***  FIXED OR CONSTANT MATRIX ELEMENTS
C
C***  INTEGRATE VELOCITY ERROR INTO POSITION ERROR
C
C   CALL IMBED ( UNIT, 3, 3, F, N, N, 1, 4 )
C
C***  ACCELEROMETER BIAS
C
C   CALL IMBED ( UNIT, 3, 3, F, N, N, 4, 10 )
C
C***  PROCESS NOISE
C
C***  PLATFORM TILT ERROR
C
C   CALL OODIAG ( TAUT, 3, TEMP )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 7, 7 )
C
C***  ACCELEROMETER BIAS
C
C   CALL OODIAG ( TAU, 3, TEMP )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 10, 10 )
C
C***  ACCELEROMETER SCALE FACTOR ERROR
C
C   CALL OODIAG ( TAUS, 3, TEMP )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 13, 13 )
C
C***  RADAR AZIMUTH, ELEVATION AND RANGE BIAS
C
C   CALL OODIAG ( TAUR, 3, TEMP )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 16, 16 )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 19, 19 )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 22, 22 )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 25, 25 )
C   CALL IMBED ( TEMP, 3, 3, F, N, N, 28, 28 )
C
C   DO 15 I = 1, 3
C
C   Q(I,I) = 2.0*TAUT(I)*(UT(I)/CRAD)**2
C   G(I+6,I) = 1.0/TAUT(I)
C   Q(I+3,I+3) = 2.0*TAU(I)*(UA(I))**2
C   G(I+9,I+3) = 1.0/TAU(I)
C   Q(I+6,I+6) = 2.0*TAUS(I)*(US(I)/PERCNT)**2
C   G(I+12,I+6) = 1.0/TAUS(I)
C   Q(I+9,I+9) = 2.0*TAUR(I)*(UR(I))**2

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C   +15,    = TAUR(I)
Q(I+12,I+12) = 2.0*TAUR(I)*(UR(I))**2
G(I+18,I+12) = 1.0/TAUR(I)
Q(I+15,I+15) = 2.0*TAUR(I)*(UR(I))**2
G(I+21,I+15) = 1.0/TAUR(I)
Q(I+18,I+18) = 2.0*TAUR(I)*(UR(I))**2
G(I+24,I+18) = 1.0/TAUR(I)
Q(I+21,I+21) = 2.0*TAUR(I)*(UR(I))**2
G(I+27,I+21) = 1.0/TAUR(I)

C   CONTINUE
C   JUMP = 1

C   CONTINUE
C   **** TIME VARYING MATRIX ELEMENTS
C   *** TILT ERROR
C
CALL SKEW ( ABRI, TEMP )
CALL SMLT ( -1.0, TEMP, TEMP, 3, 3 )
CALL IMBED ( TEMP, 3, 3, F, N, N, 4, 7 )

C   GRAVITY ERROR
C
CALL MULT ( CBRIEF, RBRI, VEC, 3, 3, 1 )
CALL AGRAV ( VEC )
CALL MULT ( CEFBRI, GRAV, GRAVI, 3, 3, 1 )
DO 40 I = 1, 3
SUM = 0.0
DO 30 J = 1, 3
SUM = SUM + CEFBRI(I,J)*GRAV(J)
CONTINUE
GRAVI(I) = SUM
40 CONTINUE
CALL ADD ( GRAVI, ABRI, ANET, 3, 1 )
CALL MULT ( CEFBRI, AGMX, TEMP, 3, 3, 3 )
CALL MULT ( TEMP, CBRIEF, AGMX, 3, 3, 3 )
CALL IMBED ( AGMX, 3, 3, F, N, N, 4, 1 )

C   TFAC = HSTEP/2.0
CALL SMLT ( TPAC, AGMX, AGMX, 3, 3 )
CALL IMBED ( AGMX, 3, 3, F, N, N, 1, 1 )
CALL IMBED ( AGMX, 3, 3, F, N, N, 4, 4 )

C   ACCELEROMETER SCALE FACTOR
C
CALL DIAG ( ABRI, 3, TEMP )
CALL IMBED ( TEMP, 3, 3, F, N, N, 4, 13 )

C   RETURN
C   FORMAT ( 3X, 9E8.2 )
C
END
§

```

SUBROUTINE COV2UD (U, N)

C IMPLICIT DOUBLE PRECISION (A-H, O-Z)

C DIMENSION U(1)

C Z = 0.E0
ONE = 1.E0
NONE = 1C JJ = N*(N+1)/2
NP2 = N + 2
DO 50 L = 2, N
J = NP2 - L
ALPHA = Z
IF (U(JJ).GE.Z) GO TO 10
WRITE(*,100) J, U(JJ)
U(JJ) = Z
10 IF (U(JJ).GT.Z) ALPHA = ONE/U(JJ)
JJ = JJ - J
KK = 0
KJ = JJ
JM1 = J - 1
DO 40 K = 1, JM1
KJ = KJ + 1
BETA = U(KJ)
U(KJ) = ALPHA*U(KJ)
IJ = JJ
IK = KK
DO 30 I = 1, K
IK = IK + 1
IJ = IJ + 1
30 U(IK) = U(IK) - BETA*U(IJ)40 KK = KK + K
50 CONTINUEIF (U(1).GE.Z) GO TO 60
WRITE(*,100) NONE, U(1)
U(1) = Z
60 RETURNC 100 FORMAT (1HO, 20X, 8H AT STEP,I4,16HDIAGONAL ENTRY = F12.4)
END

SUBROUTINE UDMEAS (U, N, R, A, F, G, ALPHA)

C IMPLICIT DOUBLE PRECISION (A-H, O-Z)

C DIMENSION U(1), A(1), F(1), G(1)
C DOUBLE PRECISION SUM, BETA, GAMMA
LOGICAL ITESTC ZERO = 0.E0
IEST = .FALSE.
ONE = 1.E0
NP1 = N + 1
NP2 = N + 2
NTOT = N*NP1/2
IF (ALPHA.LT.ZERO) GO TO 3
SUM = A(NP1)
DO 1 J = 1, N
1 SUM = SUM - A(J)*U(NTOT+J)
IEST = .TRUE.C 3 JJN = NTOT
DO 10 L = 2, N
J = NP2 -ORIGINAL PAGE IS
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      JJ = JN
      SUM = A(J)
      JN1 = J - 1
      DO 5 K = 1, JM1
      SUM = SUM + U(JJ+K)*A(K)
      5   G(J) = SUM*U(JJN)
      F(J) = SUM
      G(1) = U(1)*F(1)

      C   SUM = R + G(1)*F(1)
          GAMMA = 0
          IF ( SUM.GT.ZERO ) GAMMA = ONE/SUM
          IF ( F(1).NE.ZERO ) U(1) = U(1)*R*GAMMA

      C   KJ = 2
          DO 20 J = 2, N
              BETA = SUM
              TEMP = G(J)
              SUM = SUM + TEMP*F(J)
              P = -F(J)*GAMMA
              JM1 = J - 1
              DO 15 K = 1, JM1
                  S = U(KJ)
                  U(KJ) = S + P*G(K)
                  G(K) = G(K) + TEMP*S
                  KJ = KJ + 1
              15   IF ( TEMP.EQ.ZERO ) GO TO 20
                  GAMMA = ONE/SUM
                  U(KJ) = U(KJ)*BETA*GAMMA
              20   KJ = KJ + 1
          ALPHA = SUM

      C   IF ( .NOT.IEST ) RETURN
          F(NP1) = U(NTOT+NP1)*GAMMA
          DO 30 J = 1, N
          30   U(NTOT+J) = U(NTOT+J) + G(J)*F(NP1)

      C   RETURN
      END

      SUBROUTINE UD2COV ( UIN, POUT, N )
      C   IMPLICIT DOUBLE PRECISION ( A-H, O-Z )
      C   DIMENSION UIN(1), POUT(1)

      C   POUT(1) = UIN(1)
      JJ = 1
      DO 20 J = 2, N
      20   JJL = JJ
      JJ = JJ + J
      POUT(JJ) = UIN(JJ)
      S = POUT(JJ)
      II = 0

      JM1 = J - 1
      DO 20 I = 1, JM1
      II = II + I
      ALPHA = S*UIN(JJL+I)
      IK = II
      DO 10 K = I, JM1
      POUT(IK) = POUT(IK) + ALPHA*UIN(JJL+K)
      10   IK = IK + K
      20   POUT(JJL+I) = ALPHA

      C   RETURN

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END
SUBROUTINE XPHIU ( PHI, MAXPHI, IRPHI, ICPHI, U, N, PHIU, MPHIU )
C
C IMPLICIT DOUBLE PRECISION ( A-H, O-Z )
C
C DIMENSION PHI(MAXPHI, 1), U(1), PHIU(MPHIU, 1)
C DOUBLE PRECISION SUM
C
C DO 10 I = 1, IRPHI
 10 PHIU(I,1) = PHI(I,1)

C
NP2 = N + 2
KJS = N*(N+1)/2
DO 40 L = 2, N
  J = NP2 - L
  KJS = KJS - J
JM1 = J - 1
DO 30 I = 1, IRPHI
  SUM = PHI(I,J)
  IF ( J .LE. ICPHI ) GO TO 15
  SUM = 0.0
  JMJ1 = ICPHI
  15 DO 20 K = 1, JM1
  20 SUM = SUM + PHI(I,K)*U(KJS+K)
  30 PHIU(I,J) = SUM
  40 CONTINUE

C
RETURN
END
SUBROUTINE WGS ( W, IMAXW, IW, JW, DW, U, V )
C
C IMPLICIT DOUBLE PRECISION ( A-H, O-Z )
C
C DIMENSION W(IMAXW, 1), DW(1), U(1), V(1)

C
Z = 0.0
ONE = 1.0
IW2 = IW + 2
DO 100 L = 2, IW
  J = IW2 - L
  SUM = Z
  DO 40 K = 1, JW
    V(K) = W(J,K)
    U(K) = DW(K)*V(K)
    SUM = V(K)*U(K) + SUM
    W(J,K) = SUM
  DINV = SUM
  JM1 = J - 1
  IF ( SUM.GT.Z ) GO TO 45
  C
  W(J,.) = 0.0 WHEN DINV = 0.0 ( DINV = NORM(W(J, .) ** 2) )
  DO 44 K = 1, JM1
    44 W(J,K) = Z
    GO TO 100
  45 DO 70 K = 1, JM1
    SUM = Z
    DO 50 I = 1, JW
      SUM = W(K,I)*U(I) + SUM
    50 SUM = SUM/DINV
    DIVIDE HERE (IN PLACE OF RECIPROCAL MULTIPLY) TO AVOID
    C
    POSSIBLE OVERFLOW
    C
    DO 60 I = 1, JW
      W(K,I) = W(K,I) - SUM*V(I)
    60 W(J,K) = SUM
    70 CONTINUE
    C
    DO 80 I = 1, JW
      W(K,I) = W(K,I) - SUM*V(I)
    80 W(J,K) = SUM
    100 CONTINUE
  
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```
C
      SUM = Z
      DO 105 K = 1, JW
      SUM = DW(K)*W(1,K)**2 + SUM
105    U(1) = SUM
      IJ = 1
      DO 110 J = 2, IW
      DO 110 I = 1, J
      IJ = IJ + 1
      U(IJ) = W(J,I)
110
      C
      RETURN
      END
```

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SUBROUTINE REFRAC ( IRDR, EL, RNGH, DELEL, DELRNG )

COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2
COMMON / RDRDAT / XKNO(5), RLAT(5), RLONG(5), SALT(5), NRDR
      DATA A, B, C / 17590., 30.55, 0.0 /
      DATA RO / 6378165. /
      DATA CRAD / 57.295779 /

C     RANGE = .3048*RNGH
C     HSTA = .3048*SALT( IRDR )
C     XNO = XKNO( IRDR )
C
C     ALT = SQRT( RO**2 + RANGE**2 + 2.*RO*RANGE*SIN( EL/CRAD ) ) - RO
C
C     HS0 = 7000.
C
C     DO 10 I = 1, 50
C
C     HS = A - B*(XNO*1.E+6)*EXP( ( HSTA - C )/HS0 )
C     WRITE(*, 901) HS, HS0
C     FORMAT ( 10X, 2E12.5 )
C
C     IF ( ABS( HS - HS0 ) .LE. 1.0 ) GO TO 20
C
C     HS0 = HS
C
C     WRITE(*, 902) I
C     FORMAT ( 22H FAILED TO CONVERGE IN, I, 18H STEPS IN "REFRAC" )
C
10   CONTINUE
C
20   CONTINUE
C
C     IF ( ALT.LT.6000. ) THEN
C
C       RRNG = RANGE/RO
C       RR2 = RRNG*RRNG
C
C       RALT = ALT/HS
C       RA2 = RALT*RAALT
C       RA3 = RA2*RALT
C
C       DELRNG = XNO*RANGE*( 1. + 67.*RR2 )*
C1      ( 1. - .49939*RALT + .17472*RA2 - .04344*RA3 )
C1      DELEL = XNO*RANGE*COS(EL/CRAD)/(2.*HS)*( 1. + 46.*RR2 )*
C1      ( 1.-.333324*RALT + .08558*RA2 - .01681*RA3 )
C
C       ELSE
C
C         IF ( ALT.LT.1.E+5 ) THEN
C
C           HSTR = ( 1. - EXP( -ALT/HS ) )*HS
C
C           END IF
C
C           HSTR = HS
C
C           ELSE
C
C             XNO2 = XNO*XNO
C             RALT = ALT/RO
C             RA2 = RALT*RALT
C             RHS = HSTR/RO
C
C             A1 = .394 + 1.16E+5*XNO2

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C      =  [REDACTED] + 7 [REDACTED] * XNO2
A3   =  .004 + 1.E+5*XNO2
B1   =  59.9 + 1.14E+4*XNO - 1.9E+7*XNO2
B2   =  -3.379 - 1.E+3*XNO + 6.E+6*XNO2
B3   =  .007
C1   =  .7181 - 246.*XNO + 2.1E+4*XNO2
C2   =  27.5 - 7.8E+3*XNO - 9.96E+7*XNO2
C3   =  -4.2 - 2.3E+3*XNO - 4.32E+7*XNO2
C4   =  141.1 - 1.1E+4*XNO + 4.03E+8*XNO2
C5   =  -20.4 - 9.E+4*XNO - 3.1E+7*XNO2

C     AA = ( A1 + A2*RALT )/( 1. + A3*RALT )
      BB = ( B1 + B2*RALT )/( 1. + B3*RALT )
      CC = ( C1 + C2*RALT + C3 * RA2 )/( 1. + C4*RALT + C5*RA2 )

C     SEL = SIN( EL/CRAD )
      CEL = COS( EL/CRAD )

C     ROOT = SQRT( SEL**2 + 2.*RHS )
C
      DELEL = XNO*CEL*( 1.+AA*EXP( -BB*SEL ) )/( ( 1.-CC ) *ROOT+CE*SEL )
      DELEL = DELEL*( 1.- 2.*RHS/( ROOT + SEL ) )
      DELRNG = 2.*XNO*HSTR/( ROOT + SEL )
      DELRNG = DELRNG*( 1.-2.7E+7*(XNO**1.5)*RHS*(CEL**1.4E+6*XNO) ) )

C     END IF

C     DELRNG = DELRNG/.3048
      DELEL = DELEL*CRAD

C     RETURN
END
```

SUBROUTINE COOR (RXE, RYE, RZE, PHI, LAMDA, HTI)
REAL LAT, LONG, LAMDA

C COMMON / EDATA / RE, FLAT, OMEG, XMU, XJ2
COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
C DATA EPS / 1.0E-5 /
C
C LAMDA = CRAD*ATAN2(RYE, RXE)
C CLAM = COS(LAMDA/CRAD)
C E = 1.0/FLAT
C OMES = (1.0 - E)**2
C
C DO 100 I = 1, 50
C
C PHI = PHI
C
C CPHI = COS(PHI/CRAD)
C SPHI = SIN(PHI/CRAD)
C
C ASQ = CPHI**2 + OMES*SPHI**2
C A = SQRT(ASQ)
C ASQSQ = ASQ*ASQ
C
C HTI = RXE/(CPHI*CLAM) - RE/A
C
C FPHI = RZE - SPHI*(RE*OMES/A + HTI)
C DFDP = -CPHI*((RE*OMES/A)*(1.0 + (E*(E-2.0)**2)/ASQSQ)+HTI)
C DFDP=CPHI*((RE*OMES/A)*(E*(E-2.0)**2/ASQ -1.)-HTI)
C DPHI = (FPHI/DFDP)*CRAD
C
C PHI = FPHI - DPHI
C
C IF (ABS(DPHI) - EPS) 200, 200, 100
C
C 100 CONTINUE
C
C WRITE(*, 901) I
901 FORMAT(23H FAILED TO CONVERGE IN , I2, 16H STEPS IN "COOR")
C
C 200 CONTINUE
C
C RETURN
END
SUBROUTINE ECPOS (LAT, LONG, HT, RXE, RYE, RZE)
REAL LAT, LONG
C
C COMMON / EDATA / RE, FLAT, OMEG, XMU, XJ2
COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
C
C CLAT = COS(LAT/CRAD)
C SLAT = SIN(LAT/CRAD)
C LONG = COS(LONG/CRAD)
C SLONG = SIN(LONG/CRAD)
C
C E = 1.0/FLAT
C OMES = (1.0 - E)**2
C ASQ = CLAT**2 + OMES*SLAT**2
C A = SQRT(ASQ)
C
C R = RE/A + HT
C S = RE*OMES/A + HT
C
C RXE = R*CLAT*CLONG

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C   E = [REDACTED] AT*
C   RZE = S*SLAT
C
C   RETURN
C   END
C   SUBROUTINE AGRAV ( R )
C   DIMENSION R(3)
C
C   COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2
C   COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
C   COMMON / EARTH / GRAVI(3), AGMX(3,3)
C
C   RMAGS = R(1)*R(1) + R(2)*R(2) + R(3)*R(3)
C   RMAG = SQRT( RMAGS )
C   RMAGQ = RMAGS * RMAG
C
C   RRS = (RE/RMAG)**2
C   RZS = (R(3)/RMAG)**2
C   XMUX = XMU*(1.0+1.5*XJ2*RRS*(1.0-5.0*RZS))
C   XMUY = XMUX
C   XMUZ = XMUX + 3.0*XJ2*RRS*XMU
C
C   GRAVI(1) = -XMUX*R(1)/RMAGQ
C   GRAVI(2) = -XMUY*R(2)/RMAGQ
C   GRAVI(3) = -XMUZ*R(3)/RMAGQ
C
C   FAC1 = XMU*XJ2*RRS*( 2.*(1.-5.*RZS) - 1. )/RMAGQ
C   FAC4 = XMU*XJ2*RRS*( 2.*(1.-5.*RZS) + 4. )/RMAGQ
C
C   AGMX(1,1) = -XMUX/RMAGQ + 3.0*(R(1)/RMAG)**2*(XMUX/RMAGQ + FAC1)
C   AGMX(2,1) = 3.0*(R(1)*R(2)/RMAG)*(XMUX/RMAGQ + FAC1)
C   AGMX(3,1) = 3.0*(R(1)*R(3)/RMAG)*(XMUX/RMAGQ + FAC4)
C
C   AGMX(1,2) = AGMX(2,1)
C   AGMX(2,2) = -XMUY/RMAGQ + 3.0*(R(2)/RMAG)**2*(XMUY/RMAGQ + FAC1)
C   AGMX(3,2) = 3.0*(R(2)*R(3)/RMAG)*(XMUY/RMAGQ + FAC4)
C
C   AGMX(1,3) = AGMX(3,1)
C   AGMX(2,3) = AGMX(3,2)
C   AGMX(3,3) = -AGMX(1,1) - AGMX(2,2)
C
C   RETURN
C   END
C   SUBROUTINE CIEFMX ( TIME, CIEF )
C   DIMENSION CIEF(3,3)
C
C   COMMON / EDATA / RE, FLAT, OMEGAE, XMU, XJ2
C   COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
C
C   THTE = OMEGAE*CRAD*TIME
C   STHT = SIN(THTE/CRAD)
C   CHTT = COS(THTE/CRAD)
C
C   CIEF(1,1) = CHTT
C   CIEF(2,1) = -STHT
C   CIEF(3,1) = 0.0
C   CIEF(1,2) = STHT
C   CIEF(2,2) = CHTT
C   CIEF(3,2) = 0.0
C   CIEF(1,3) = 0.0
C   CIEF(2,3) = 0.0
C   CIEF(3,3) = 1.0
C
C   RETURN
C   END

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SUBROUTINE AXCBIQ ( Q, V, P )
C
DIMENSION Q(4), V(3), P(3,4)
C
P(1,1) = Q(1)*V(1) - Q(4)*V(2) + Q(3)*V(3)
P(2,1) = Q(4)*V(1) + Q(1)*V(2) - Q(2)*V(3)
P(3,1) = -Q(3)*V(1) + Q(2)*V(2) + Q(1)*V(3)
C
P(1,2) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
P(2,2) = Q(3)*V(1) - Q(2)*V(2) - Q(1)*V(3)
P(3,2) = Q(4)*V(1) + Q(1)*V(2) - Q(2)*V(3)
C
P(1,3) = -Q(3)*V(1) + Q(2)*V(2) + Q(1)*V(3)
P(2,3) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
P(3,3) = -Q(1)*V(1) + Q(4)*V(2) - Q(3)*V(3)
C
P(1,4) = -Q(4)*V(1) - Q(1)*V(2) + Q(2)*V(3)
P(2,4) = Q(1)*V(1) - Q(4)*V(2) + Q(3)*V(3)
P(3,4) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
C
CALL SMLT( 2.0, P, P, 3, 4 )
C
RETURN
END
SUBROUTINE AUXVAB
C
DIMENSION VEC(3), VEC2(3), TMP(3,3)
C
COMMON / VARIAB / VR(3), VW(3), VWGRAD(3)
COMMON / TMAT / CBI(3,3), CLLB(3,3), CEFBRI(3,3)
COMMON / PARTLA / PVMVB(3), PAVB(3), PBVB(3), PVMH, PAH, PBH
1   , PVMW(3), PAVW(3), PBW(3)
C
DATA CRAD / 57.295779 /
C
VMAGS = VR(1)*VR(1) + VR(2)*VR(2) + VR(3)*VR(3)
IF( VMAGS.LT.1.0 ) VMAGS = 1.0
VMAG = SQRT(VMAGS)
C
VMAGQ = VMAGS*VMAG
C
DO 10 I = 1, 3
PVMVB(I) = VR(I)/VMAG
CONTINUE
10
C
VR13S = VMAGS - VR(2)*VR(2)
IF( VR13S.LT.1.0 ) VR13S = 1.0
VR13 = SQRT(VR13S)
C
PAVB(1) = -VR(3)/VR13S
PAVB(2) = 0.0
PAVB(3) = VR(1)/VR13S
CALL SMLT( CRAD, PAVB, PAVB, 3, 1 )
C
PBVB(1) = -VR(1)*VR(2)/(VMAGQ*VR13)
PBVB(2) = VR13/VMAGQ
PBVB(3) = -VR(2)*VR(3)/(VMAGQ*VR13)
CALL SMLT( CRAD, PBVB, PBVB, 3, 1 )
C
CALL MULT( CLLB, VWGRAD, VEC, 3, 3, 1 )
CALL INNER( PVMVB, VEC, PVMH, 3 )
CALL INNER( PAVB, VEC, PAH, 3 )
CALL INNER( PBVB, VEC, PBH, 3 )
C
CALL TRANS( CLLB, TMP, 3, 3 )
CALL MULT( TMP, VR, VEC, 3, 1 )

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C      DO 20 I = 1, 3
C      VEC2(I) = VR(1)*CLLB(3,I) - VR(3)*CLLB(1,I)
C      CONTINUE
C
C      A = -1.0/VR13S
C      CALL SMLT ( A, VEC2, PAVW, 3, 1 )
C      CALL SMLT ( CRAD, PAVW, PAVW, 3, 1 )
C
C      DO 30 I = 1, 3
C      VEC2(I) = VMAG*CLLB(2,I) - VR(2)*PVWVW(I)/(2.*VMAG)
C      CONTINUE
C
C      RETURN
C      END
C      SUBROUTINE AXCIBQ( Q, V, P )
C
C      DIMENSION Q(4), V(3), P(3,4)
C
C      P(1,1) = Q(1)*V(1) + Q(4)*V(2) - Q(3)*V(3)
C      P(2,1) = -Q(4)*V(1) + Q(1)*V(2) + Q(2)*V(3)
C      P(3,1) = Q(3)*V(1) - Q(2)*V(2) + Q(1)*V(3)
C
C      P(1,2) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
C      P(2,2) = Q(3)*V(1) - Q(2)*V(2) + Q(1)*V(3)
C      P(3,2) = Q(4)*V(1) - Q(1)*V(2) - Q(2)*V(3)
C
C      P(1,3) = -Q(3)*V(1) + Q(2)*V(2) - Q(1)*V(3)
C      P(2,3) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
C      P(3,3) = Q(1)*V(1) + Q(4)*V(2) - Q(3)*V(3)
C
C      P(1,4) = -Q(4)*V(1) + Q(1)*V(2) + Q(2)*V(3)
C      P(2,4) = -Q(1)*V(1) - Q(4)*V(2) + Q(3)*V(3)
C      P(3,4) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
C
C      CALL SMLT( 2,0, P, P, 3, 4 )
C
C      RETURN
C      END
C      SUBROUTINE QMTRX( OMEGA, QDMTRX )
C
C      DIMENSION OMEGA(3), QDMTRX(4,4)
C
C      QDMTRX(1,1) = 0.0
C      QDMTRX(1,2) = -0.5*OMEGA(1)
C      QDMTRX(1,3) = -0.5*OMEGA(2)
C      QDMTRX(1,4) = -0.5*OMEGA(3)
C      QDMTRX(2,1) = 0.5*OMEGA(1)
C      QDMTRX(2,2) = 0.0
C      QDMTRX(2,3) = 0.5*OMEGA(3)
C      QDMTRX(2,4) = -0.5*OMEGA(2)
C      QDMTRX(3,1) = 0.5*OMEGA(2)
C      QDMTRX(3,2) = -0.5*OMEGA(3)
C      QDMTRX(3,3) = 0.0
C      QDMTRX(3,4) = 0.5*OMEGA(1)
C      QDMTRX(4,1) = 0.5*OMEGA(3)
C      QDMTRX(4,2) = 0.5*OMEGA(2)
C      QDMTRX(4,3) = -0.5*OMEGA(1)
C      QDMTRX(4,4) = 0.0

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C      RETURN
END
SUBROUTINE PQOMEGG( Q, P )
C      DIMENSION Q(4), P(4,3)
C
C      P(1,1) = -0.5*Q(2)
C      P(1,2) = -0.5*Q(3)
C      P(1,3) = -0.5*Q(4)
C      P(2,1) = 0.5*Q(1)
C      P(2,2) = -0.5*Q(4)
C      P(2,3) = 0.5*Q(3)
C      P(3,1) = 0.5*Q(4)
C      P(3,2) = 0.5*Q(1)
C      P(3,3) = -0.5*Q(2)
C      P(4,1) = -0.5*Q(3)
C      P(4,2) = 0.5*Q(2)
C      P(4,3) = 0.5*Q(1)

C      RETURN
END
SUBROUTINE AXVABQ
C      DIMENSION VEC1(4), VEC2(4), VEC3(4)

C      COMMON / STATES / RI(3), VB(3), Q(4), OMEGA(3)
C      COMMON / VARIAB / VR(3), VW(3), VWGRAD(3)
C      COMMON / PARTLB / PVRQ(3,4), PVHQ(4), PAQ(4), PBQ(4)

C      DATA CRAD / 57.295779 /
C
C      VMS = VR(1)**2 + VR(2)**2 + VR(3)**2
C      VM = SQRT(VMS)
C      VR2VMS = VR(2)**2 + VMS
C      VR1R3S = VR(1)**2 + VR(3)**2
C      IF( VR1R3S.LT.1.0 ) VR1R3S = 1.0
C      IF( VR2VMS.LT.1.0 ) VR2VMS = 1.0
C      IF( VM.LT.1.0 ) VM = 1.0

C      CALL AXCIBQ( Q, VW, PVRQ )
C      CALL SMLT( -1.0, PVRQ, PVRQ, 3, 4 )

C      DO 10 I = 1, 4
C      VEC1(I) = PVRQ(1,I)
C      VEC2(I) = PVRQ(2,I)
C      VEC3(I) = PVRQ(3,I)
C      CONTINUE
C
C      DO 20 I = 1, 4
C      PVHQ(I) = VEC1(I)*VR(1) + VEC2(I)*VR(2) + VEC3(I)*VR(3)
C      PAQ(I) = 0.5*PVHQ(I)/VM
C      PAQ(I) = CRAD*PAQ(I)/VR1R3S
C      CONTINUE
C
C      DO 30 I = 1, 4
C      PBO(I) = VEC3(I)*VR(1) - VEC1(I)*VR(3)
C      PBQ(I) = CRAD*PBQ(I)/VR2VMS
C      CONTINUE
C
C      DO 40 I = 1, 4
C      PBQ(I) = VEC2(I)*VM - PVHQ(I)*VR(2)
C      PBQ(I) = CRAD*PBQ(I)/VR2VMS
C      CONTINUE
C
C      RETURN
END

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C   SUBROUTINE CBIMX( Q, [REDACTED] )
C   DIMENSION Q(4), CBI(3,3)
C
C   CBI(1,1) = Q(1)*Q(1) + Q(2)*Q(2) - Q(3)*Q(3) - Q(4)*Q(4)
C   CBI(2,1) = 2.*( Q(2)*Q(3) + Q(1)*Q(4) )
C   CBI(3,1) = 2.*( Q(2)*Q(4) - Q(1)*Q(3) )
C
C   CBI(1,2) = 2.*( Q(2)*Q(3) - Q(1)*Q(4) )
C   CBI(2,2) = Q(1)*Q(1) - Q(2)*Q(2) + Q(3)*Q(3) - Q(4)*Q(4)
C   CBI(3,2) = 2.*( Q(1)*Q(2) + Q(3)*Q(4) )
C
C   CBI(1,3) = 2.*( Q(2)*Q(4) + Q(1)*Q(3) )
C   CBI(2,3) = 2.*( Q(3)*Q(4) - Q(1)*Q(2) )
C   CBI(3,3) = Q(1)*Q(1) - Q(2)*Q(2) - Q(3)*Q(3) + Q(4)*Q(4)
C
C   RETURN
END
SUBROUTINE CBIMX( THT, CBI )
C
C   DIMENSION THT(3), CBI(3,3)
C
C   DATA CRAD / 57.295779 /
C
C   SPHI = SIN(THT(1)/CRAD)
C   CPHI = COS(THT(1)/CRAD)
C   STHT = SIN(THT(2)/CRAD)
C   CTHT = COS(THT(2)/CRAD)
C   SPSI = SIN(THT(3)/CRAD)
C   CPSI = COS(THT(3)/CRAD)
C
C   CBI(1,1) = CTHT*CPSI
C   CBI(2,1) = CTHT*SPSI
C   CBI(3,1) = -STHT
C   CBI(1,2) = SPHI*STHT*CPSI - CPHI*SPSI
C   CBI(2,2) = SPHI*STHT*SPSI + CPHI*CPSI
C   CBI(3,2) = SPHI*CTHT
C   CBI(1,3) = CPHI*STHT*CPSI + SPHI*SPSI
C   CBI(2,3) = CPHI*STHT*SPSI - SPHI*CPSI
C   CBI(3,3) = CPHI*CTHT
C
C   RETURN
END
SUBROUTINE E2QUAT( THT, Q )
C
C   SUBROUTINE TO CONVERT EULER ANGLES INTO QUATERNIONS REF: PERRY
C
C   DIMENSION THT(3), AM(3,3), V(3), Q(4)
C
C   DATA CRAD / 57.295779 /
C
C   PHI = THT(1)
C   THE = THT(2)
C   PSI = THT(3)
C
C   CPHI = COS( PHI/CRAD )
C   SPHI = SIN( PHI/CRAD )
C   CTHT = COS( THE/CRAD )
C   STHT = SIN( THE/CRAD )
C   CPSI = COS( PSI/CRAD )
C   SPSI = SIN( PSI/CRAD )
C
C   AM(1,1) = CPSI*CTHT
C   AM(1,2) = -SPSI*CPHI + CPSI*STHT*SPHI
C   AM(1,3) = SPSI*SPHI + CPSI*STHT*CPHI
C
C

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AM(2,1) = SPSI*CHT
AM(2,2) = CPSI*CPHI + SPSI*SHT*SPHI
AM(2,3) = -CPSI*SPHI + SPSI*SHT*CPHI

C   AM(3,1) = -SHT
C   AM(3,2) = CHT*SPHI
C   AM(3,3) = CHT*CPHI

C   IF( (ABS(THE-90.).LT.1.) .AND. (ABS(PHI-PSI).LT.1.) ) THEN
C
C   LOOP TO CONVERSION ( SEE PERRY )
C
C   I = 0
C
C   T = AM(1,1) + AM(2,2) + AM(3,3)
C   S = T
C
C   DO 10 II = 1, 3
C   IF( (AM(II,II).GT.S) ) THEN
C   S = AM(II,II)
C   I = II
C   ELSE
C   I = 0
C   END IF
C   10 CONTINUE
C
C   T = SQRT( 1.0 + 2.0*S - T )
C
C   K = 2
C   J = 3
C   N = 1
C
C   20 CONTINUE
C
C   IF( ( I.EQ.0 ) .OR. ( N.EQ.I ) ) THEN
C   S = (AM(J,K) - AM(K,J))/T
C   V(N) = S
C   ELSE
C   V(J+K-I) = (AM(J,K) + AM(K,J))/T
C   END IF
C
C   IF( ( N - 2 ) 30, 40, 50
C   30 CONTINUE
C   K = 3
C   J = 1
C   N = 2
C   GO TO 20
C   40 CONTINUE
C   K = 1
C   J = 2
C   N = 3
C   GO TO 20
C   50 CONTINUE
C
C   IF( I.EQ.0 ) THEN
C   S = T
C   ELSE
C   V(I) = T
C   END IF
C
C   IF( S.GE.0.0 ) T = 0.5
C   IF( S.LT.0.0 ) T = -0.5
C
C   S = T*S
C   DO 60 II = 1, 3
C   V(II) = T*V(II)

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6 CONTINUE
C Q(1) = S
C Q(2) = V(1)
C Q(3) = V(2)
C Q(4) = V(3)
C ELSE
C   Q(1) = SQRT( (AM(1,1)+AM(2,2)+AM(3,3)+1.0)/4.0 )
C   Q(4) = (AM(2,1)-AM(1,2))/(4.*Q(1))
C   Q(3) = (AM(2,3)+AM(3,2))/(4.*Q(4))
C   Q(2) = (AM(1,2)+AM(2,1))/(4.*Q(3))
C END IF
C
C RETURN
END
SUBROUTINE QUAT2E( Q, THT )
C
C DIMENSION Q(4), THT(3)
C
C DATA CRAD / 57.295779 /
C
C TPSI = 2.* (Q(2)*Q(3)+Q(1)*Q(4))
DPSI = Q(1)*2+Q(2)*2-Q(3)*2-Q(4)**2
STHT = -2.* (Q(2)*Q(4)-Q(3)*Q(1))
TPHI = 2.* (Q(3)*Q(4)+Q(1)*Q(2))
DPhi = Q(1)*2+Q(4)*2-Q(2)*2-Q(3)**2
C
IF ( DPhi.NE.0.0 ) THEN
THT(1) = CRAD*ATAN2( TPhi, DPhi )
END IF
IF ( ABS(STHT).LE.1.0 ) THEN
THT(2) = CRAD*ASIN( STHT )
END IF
IF ( DPSI.NE.0.0 ) THEN
THT(3) = CRAD*ATAN2( TPSI, DPSI )
END IF
C
RETURN
END
SUBROUTINE AUKRAT( D, O, A )
C
C DIMENSION D(3), O(3), A(3,3)
C
A(1,1) = O(2)*D(2) + O(3)*D(3)
A(2,1) = O(2)*D(1) - 2.0*O(1)*D(2)
A(3,1) = O(3)*D(1) - 2.0*O(1)*D(3)
C
A(1,2) = O(1)*D(2) - 2.0*O(2)*D(1)
A(2,2) = O(1)*D(1) + O(3)*D(3)
A(3,2) = O(3)*D(2) - 2.0*O(2)*D(3)
C
A(1,3) = O(1)*D(3) - 2.0*O(3)*D(1)
A(2,3) = O(2)*D(3) - 2.0*O(3)*D(2)
A(3,3) = O(1)*D(1) + O(2)*D(2)
C
RETURN
END
SUBROUTINE TMATY( YAW, TYAW )
C
C DIMENSION TYAW(3,3)
C
C DATA CRAD / 57.295779 /
C
SY = SIN( YAW/CRAD )

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```
CY = COS( YAW/CRAD )
C
TYAW(1,1) = CY
TYAW(1,2) = -SY
TYAW(1,3) = 0.0
TYAW(2,1) = SY
TYAW(2,2) = CY
TYAW(2,3) = 0.0
TYAW(3,1) = 0.0
TYAW(3,2) = 0.0
TYAW(3,3) = 1.0

C
RETURN
END
SUBROUTINE TMATP( PITCH, TPITCH )
DIMENSION TPITCH(3,3)

C
DATA CRAD / 57.295779 /
C
SP = SIN( PITCH/CRAD )
CP = COS( PITCH/CRAD )

C
TPITCH(1,1) = CP
TPITCH(1,2) = 0.0
TPITCH(1,3) = SP
TPITCH(2,1) = 0.0
TPITCH(2,2) = 1.0
TPITCH(2,3) = 0.0
TPITCH(3,1) = -SP
TPITCH(3,2) = 0.0
TPITCH(3,3) = CP

C
RETURN
END
?
```

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C      SUBROUTINE ADD ( A, B, NRA, NCA )
C      DIMENSION A(NRA,NCA), B(NRA,NCA), C(NRA,NCA)
C
C      DO 10 J = 1, NRA
C      DO 10 I = 1, NRA
C      C(I,J) = A(I,J) + B(I,J)
C      10 CONTINUE
C
C      RETURN
END
SUBROUTINE SUBT ( A, B, C, NRA, NCA )
DIMENSION A(NRA,NCA), B(NRA,NCA), C(NRA,NCA)
C
C      DO 10 J = 1, NRA
C      DO 10 I = 1, NRA
C      C(I,J) = A(I,J) - B(I,J)
C      10 CONTINUE
C
C      RETURN
END
SUBROUTINE MULT ( A, B, C, NRA, NCA, NCB )
DIMENSION A(NRA,NCA), B(NCA, NCB), C(NRA, NCB)
C
C      DO 20 J = 1, NCB
DO 20 I = 1, NRA
K = 0
TEMP = 0.0
DO 10 L = 1, NCA
K = K + 1
TEMP = TEMP + A(I,K)*B(K,J)
10 CONTINUE
C(I,J) = TEMP
20 CONTINUE
C
C      RETURN
END
SUBROUTINE TRANS ( A, B, NRA, NCA )
DIMENSION A(NRA,NCA), B(NCA,NRA)
C
C      DO 10 I = 1, NRA
DO 10 J = 1, NCA
B(J,I) = A(I,J)
10 CONTINUE
C
C      RETURN
END
SUBROUTINE SMLT ( C, A, B, NRA, NCA )
DIMENSION A(NRA,NCA), B(NRA,NCA)
C
C      DO 10 I = 1, NRA
DO 10 J = 1, NCA
B(I,J) = C*A(I,J)
10 CONTINUE
C
C      RETURN
END
SUBROUTINE SWITCH ( A, B, NRA, NCA )
DIMENSION A(NRA,NCA), B(NRA,NCA)
C
C      DO 10 I = 1, NRA
DO 10 J = 1, NCA
B(I,J) = A(I,J)
10 CONTINUE
C
C      RETURN
END

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SUBROUTINE SKEW ( A, B )
DIMENSION A(3), B(3,3)

C      B(1,1) = 0.0
C      B(1,2) = -A(3)
C      B(1,3) = A(2)
C      B(2,1) = -B(1,2)
C      B(2,2) = 0.0
C      B(2,3) = -A(1)
C      B(3,1) = -B(1,3)
C      B(3,2) = -B(2,3)
C      B(3,3) = 0.0

C      RETURN
END
SUBROUTINE IMBED ( SUB, M, N, BIG, IM, IN, IROW, ICOL )
DIMENSION SUB(1), BIG(1)

C      IF ( (M+IROW-1 .LE. IM) .AND. (N+ICOL-1 .LE. IN) ) GOTO 5
      WRITE(*,6000) IM, IN, M, N, IROW, ICOL
      STOP

C      5 IB = ( ICOL - 1 ) * IM + ( IROW - 1 )
      IS = 0
      IOFFST = IM - M

C      DO 20 I = 1, N
      DO 10 J = 1, M
      IB = IB + 1
      IS = IS + 1
      BIG(IB) = SUB(IS)

      SUBROUTINE INV2X2 ( A, DET, AI )
DIMENSION A(2,2), AI(2,2)

C      DET = A(1,1) * A(2,2) - A(1,2) * A(2,1)
      AI(1,1) = A(2,2) / DET
      AI(1,2) = -A(1,2) / DET
      AI(2,1) = -A(2,1) / DET
      AI(2,2) = A(1,1) / DET

C      RETURN
END
SUBROUTINE ZEROM( A, NROW, NCOL )
DIMENSION A(NROW,NCOL)

C      DO 10 I = 1, NROW
      DO 10 J = 1, NCOL
      A(I,J) = 0.0

C      CONTINUE
C      RETURN
END
SUBROUTINE OC [REDACTED] ( [REDACTED], N, [REDACTED] )

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C      DIMENSION TAU(N), TMP(N,N)
C      DO 20 I = 1, N
C      DO 10 J = 1, N
C      TMP(I,J) = 0.0
C      CONTINUE
C      TMP(I,I) = -1./TAU(I)
C      20 CONTINUE
C
C      RETURN
END
SUBROUTINE DIAG ( V, N, A )
C      DIMENSION V(N), A(N,N)
C      DO 20 I = 1, N
C      DO 10 J = 1, N
C      A(I,J) = 0.0
C      10 CONTINUE
C      A(I,I) = V(I)
C      20 CONTINUE
C
C      RETURN
END
SUBROUTINE SYMTRK ( A, NS, AS )
DIMENSION A(NS,NS), AS(NS,NS)
C      DO 10 I = 1, NS
C      DO 10 J = I, NS
C      AS(I,J) = 0.5*(A(I,J) + A(J,I))
C      AS(J,I) = AS(I,J)
C      10 CONTINUE
C
C      RETURN
END
SUBROUTINE INNER ( A, B, C, NELEM )
DIMENSION A(NELEM), B(NELEM)
C      TEMP = 0.0
C      DO 10 I = 1, NELEM
C      TEMP = TEMP + A(I)*B(I)
C      10 CONTINUE
C      C = TEMP
C
C      RETURN
END
SUBROUTINE INTRP1 ( VM, TM, TC, NM, C, SLOPE )
DIMENSION TM(1), TC(1)
C      DO 10 I = 1, NM
C      IF ( VM - TM(I) ) 20, 20, 10
C      10 CONTINUE
C      K = NM
C      20 CONTINUE
C      K = I - 1
C      IF ( K.EQ.0 ) K = 1
SLOPE = ( TC(K+1) - TC(K) )/(TM(K+1) - TM(K))
C = TC(K) + SLOPE*(VM - TM(K))
C
C      RETURN

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DIMENSION TIME (530)

```

C      COMMON / TDATA / TIME, TNEXT, TMAX, TSAMP, TSTOP
COMMON / FILDAT / XKM(30), PKM(30,30), F(30,30), Q(30,30), N, NNEAS
COMMON / SMTHER/PHI(30,30), PHIT(30,30), PKP1M(30,30), PKP1(30,30)
1   ,AK(30,30), XKGN(30), PKGN(30,30), XKPGN(30), PKP1GN(30,30)
COMMON / EARTH / GRAV(3), AGMX(3,3)
COMMON / RSTATE / RBRI(3), VBRI(3), ABRI(3), THTI(3)
1   ,GRAVI(3), CIBRI(3,3), CBRIE(3,3), CEPBRI(3,3)
2   ,RITO(3), VITO(3), REF(3), ANET(3), OMEG(3)
COMMON / METEOR / TALT(400), TSRHO(400), TSP(400), TSSUND(400)
1   ,TVWX(400), TVWY(400), NALT
2   ,USRHO(400), USP(400), USSUND(400)
3   ,UVWX(400), UVWY(400)

C      BLOCK DATA
C      COMMON / EDDATA / RE, FLAT, OMEGE, XMU, XJ2
COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
COMMON / LAUCOR / OLATD, OLONG, OHT

C      OPEN ( UNIT=2, FILE='SMOIFT.DAT', STATUS='OLD',
1 ACCESS='SEQUENTIAL', FORM='UNFORMATTED' )
OPEN ( UNIT=3, FILE='NREFIPT.DAT', STATUS='OLD' )
C      1 ACCESS='SEQUENTIAL', FORM='UNFORMATTED' )
OPEN ( UNIT=4, FILE='METDAT.DAT', STATUS='OLD' )
OPEN ( UNIT=6, FILE='SMOOUT.DAT', STATUS='NEW' )
OPEN ( UNIT=7, FILE='SASSOUT.DAT', STATUS='NEW' )
1   , ACCESS='DIRECT', RECL=90, IOSTAT=IOS )
OPEN ( UNIT=8, FILE='SCRATCH.DAT', STATUS='UNKNOWN',
1 ACCESS='SEQUENTIAL', FORM='UNFORMATTED' )
OPEN ( UNIT=9, FILE='NREFIPT.DAT', STATUS='NEW' )

C      DO 20 I = 1, NALT
READ(4,998) TALT(I), TSRHO(I), TSP(I), TSSUND(I), TVWX(I), TVWY(I)
READ(4,999) USRHO(I), USP(I), USSUND(I), UVWX(I), UVWY(I)
WRITE(*,997) TALT(I), TSRHO(I), TSP(I), TSSUND(I), TVWX(I), TVWY(I)
CONTINUE
20 CONTINUE

C      CLOSE( UNIT=4 )
C      NTMAX = IFIX ( TMAX/TSAMP )

C      DO 50 I = 1, NTMAX
IT = NTMAX - I + 1
TME(I) = IT*TSAMP
50 CONTINUE

C      TSRCH = TME(1)
CALL RTSIPT ( TSRCH )
C      CALL RTSINT

C      DO 1000 K = 2, NTMAX
C      TSRCH = TME(K)
CALL RTSIPT ( TSRCH )
C      IF ( K.EQ.NTMAX ) THEN
ELSE
DT = TIME - TNEXT
END IF
CALL RTSPRP ( DT )

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```
CALL RTSUPD
C   WRITE(6,901) TSRCH
C   WRITE(6,901) (XKM(I),PKM(I,I),XKGN(I),PKGN(I,I), I = 1, N)
C   CALL ASSESS
C   1000 CONTINUE
C     CLOSE ( UNIT=2 )
C     CLOSE ( UNIT=3 )
C     CLOSE ( UNIT=6 )
REWIND 8
C     DO 2000 J = 1, (NTMAX-1)
C     IT = (NTMAX-1) - J + 2
TSRCH = TME(IT)
C     CALL REVERSE ( TSRCH )
C   2000 CONTINUE
C     CLOSE ( UNIT=7 )
C     CLOSE ( UNIT=8 )
CLOSE ( UNIT=9 )
C     901 FORMAT( 5X, 4E15.7 )
905 FORMAT( 5X, 2F10.2, 15 )
997 FORMAT( 3X, 5E15.8 )
998 FORMAT( 5X, 6E15.8 )
999 FORMAT( 20X, 5E15.8 )
C     STOP
END
```

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```
C COMMON / TDATA / TIME, TNEXT, TMAX, TSAMP, TSTOP
C COMMON / FILDAT / XRM(30),PKM(30,30),F(30,30),Q(30,30),N,NMEAS
C COMMON / SMTHR/PHI(30,30),PHIT(30,30),PKPIM(30,30),PKPI(30,30)
1 ,AK(30,30),XKGN(30),PKGN(30,30),XKP1GN(30),PKP1GN(30,30)
COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2
COMMON / CONST / CRAD, AGRAV, HRSEC, PERCNT, XMRAD
COMMON / LAUCOR / OLATD, OLONG, OHT
COMMON / METEOR / TALT(400),TSRHO(400),TSP(400),TSSUND(400)
1 ,TVWX(400),TVWY(400),NALT
2 ,USRHO(400),USP(400),USSUND(400)
3 ,UVWX(400),UVWY(400)

C DATA TIME, TMAX, TSAMP / 0.0, 520., 1.0 /
C DATA NALT / 400 /
C DATA N / 30 /
C DATA PHI / 900*0.0 /
C DATA PHIT / 900*0.0 /
C DATA PKPIM / 900*0.0 /
C DATA PKPI / 900*0.0 /
C DATA AK / 900*0.0 /
C DATA XKGN / 30*0.0 /
C DATA PKGN / 900*0.0 /
C DATA XKP1GN / 30*0.0 /
C DATA PKP1GN / 900*0.0 /
C DATA CRAD / 57.295779 /
C DATA AGRAV, HRSEC, PERCNT, XMRAD / 32.174, 3600., 100., 1000. /
C DATA RE, FLAT, OMEGE, XMU, XJ2 / 20925604., 298.257224, .7292115E-4
C FISCHDATA RE, FLAT, OMEGE, XMU, XJ2 / 20925741., 298.3, 0.7292115E-4
1 , 1.4076468E+16, .10827E-2 /
C DATA OLATD, Olong, OHT / 28.62721, -80.62079, 0.0 /
C C39AFEDATA OLATD, OLONG, OHT / 28.608420, -80.604089, 60.0 /
C END
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SUBROUTINE RTSIPT ( TSRCH )

C      DIMENSION RHO(30,30)

C      COMMON / TDATA / TIME, TNEXT, TMAX, TSAMP, TSTOP
C      COMMON / FILDAT / XKM(30), PKM(30,30), F(30,30), Q(30,30), N, NMEAS
C      COMMON / RSTATE / RBRI(3), VBRI(3), ABRI(3), THTI(3)
C      1           , GRAVI(3), CIBRI(3,3), CBRIEF(3,3), CEFBRI(3,3)
C      2           , RITO(3), VITO(3), REF(3), ANET(3), OMEG(3)

C      N = 30

C      CONTINUE
10
C      READ(2) TIME, TNEXT, KO, NMEAS
C      WRITE(*, 901) TIME, TNEXT, KO, NMEAS
C      READ(2) (XKM(I), I = 1, N)
C      READ(2) ((PKM(I,J), J = 1, N), I = 1, N)
C      READ(2) ((F(I,J), J = 1, N), I = 1, N)
C      READ(2) ((Q(I,J), J = 1, N), I = 1, N)
C
C      READ(3, 904) XNTIME
C      READ(3, 904) (ABRI(I), I = 1, 3)
C      READ(3, 904) (THTI(I), I = 1, 3)
C      READ(3, 904) (OMEG(I), I = 1, 3)
C      READ(3, 904) (RBRI(I), I = 1, 3)
C      READ(3, 904) (VBRI(I), I = 1, 3)
C      READ(3, 904) ((CIBRI(I,J), J = 1, 3), I = 1, 3)
C      READ(3, 904) ((CBRIEF(I,J), J = 1, 3), I = 1, 3)

C      IF ( ABS(TIME-TSRCH).LT.1.0E-4 ) THEN
C      WRITE(*, 902) TIME, TNEXT, KO, NMEAS
C
C      DO 50 I = 1, N
C      DO 50 J = 1, N
C
C      RHO(I,J) = PKM(I,J)/(SQRT(PKM(I,I))*SQRT(PKM(J,J)))
C
C      CONTINUE
50
C
C      ELSE
C      REWIND 2
C      REWIND 3
C      RETURN
C
C      END IF
C
C      901 FORMAT( 2E15.8, 2I5 )
C      902 FORMAT( 5X, 2E15.8, 2I5 )
C      903 FORMAT( 5E15.8 )
C      904 FORMAT( 4X, 3E15.8 )
C
C      END

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```
C      SUBROUTINE RTSTAT
C
COMMON / FILDAT / XKMM(30),PKM(30,30),F(30,30),Q(30,30),N,NMEAS
COMMON/SMTHR/PHI(30,30),PHIT(30,30),PKP1M(30,30),PKP1I(30,30)
1 ,AK(30,30),XKGN(30),PKGN(30,30),XKP1GN(30),PKP1GN(30,30)
C
CALL SWITCH ( XKMM, XKGN, N, 1 )
CALL SWITCH ( XKMM, XKP1GN, N, 1 )
C
CALL SWITCH ( PKM, PKGN, N, N )
CALL SWITCH ( PKM, XKP1GN, N, N )
C
WRITE(*, 901) (XKGN(I), I = 1, N)
WRITE(*, 901) (PKGN(I,I), I = 1, N)
C
RETURN
C
901  FORMAT( 5X, 4E15.8 )
C
END
```

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SUBROUTINE RTSUPD
C
C      DIMENSION VEC1(30), VEC2(30), DUMB(30,30)
C
C      COMMON /FILDAT/ XK(30),PKM(30,30),F(30,30),Q(30,30),N,NMEAS
C      COMMON/SMTHER/PHI(30,30),PHIT(30,30),PKP1M(30,30),PKP1(30,30)
C      ,AK(30,30),XKGN(30),PKGN(30,30),XKP1GN(30),PKP1GN(30,30)
C
C      CALL MULT ( PHI, XK, VEC1, N, N, 1 )
C      DO 20 I = 1, N
C      TEMP = 0.0
C      DO 10 J = 1, N
C      TEMP = TEMP + PHI(I,J)*XK(I,J)
C      CONTINUE
C      VEC1(I) = TEMP
C      CONTINUE
C      CALL SUBT ( XKP1GN, VEC1, VEC2, N, 1 )
C      DO 30 I = 1, N
C      VEC2(I) = XKP1GN(I) - VEC1(I)
C      CONTINUE
C      CALL MULT ( AK, VEC2, VEC1, N, N, 1 )
C      DO 50 I = 1, N
C      TEMP = 0.0
C      DO 40 J = 1, N
C      TEMP = TEMP + AK(I,J)*VEC2(J)
C      CONTINUE
C      VEC1(I) = TEMP
C      CONTINUE
C      CALL ADD ( XK, VEC1, XKGN, N, 1 )
C      DO 60 I = 1, N
C      XKGN(I) = XK(I) + VEC1(I)
C      CONTINUE
C      CALL SWITCH ( XKGN, XKP1GN, N, 1 )
C
C      CALL SUBT ( PKP1GN, PKP1M, DUMB, N, N )
C      CALL MULT ( AK, DUMB, PKGN, N, N, N )
C      CALL TRANS ( AK, DUMB, N, N )
C      CALL MULT ( PKGN, DUMB, AK, N, N, N )
C      CALL ADD ( PKM, AK, PKGN, N, N )
C
C      CALL SWITCH ( PKGN, PKP1GN, N, N )
C
C      RETURN
C      901 FORMAT( 5X, 4E15.8 )
C      909 FORMAT( 5X, 15 )
C      END

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```
C      ROUTINE: RT51 ( D1, L1, M1 )
C      DIMENSION DUMB(30,30), L(30), M(30)
C
C      COMMON / FILDAT / XKM(30), PKM(30,30), P(30,30), Q(30,30), N, NMEAS
C      COMMON/SMTHR/PHI(30,30), PHIT(30,30), PKP1M(30,30), PKPI(30,30)
C      , AK(30,30), XKGN(30), PKGN(30,30), XKPGN(30,30), PKP1GN(30,30)
C
C      N = 30
C
C      DO 20 I = 1, N
C      DO 10 J = 1, N
C      PHI(I,J) = F(I,J)*DT
C      CONTINUE
C      PHI(I,I) = 1.0 + PHI(I,I)
C      CONTINUE
C
C      CALL TRANS ( PHI, PHIT, N, N )
C      CALL MULT ( PHI, PKM, DUMB, N, N, N )
C      CALL MULT ( DUMB, PHIT, PKP1M, N, N, N )
C      CALL ADD ( PKP1M, Q, PKP1M, N, N )
C
C      CALL SWITCH ( PKP1M, PKPI, N, N )
C      CALL INVXKN ( PKPI, N, D, L, M )
C      CALL MULT ( PKP1M, PKPI, DUMB, N, N, N )
C      CALL MULT ( PHIT, PKPI, DUMB, N, N, N )
C      CALL MULT ( PKM, DUMB, AK, N, N, N )
C
C      RETURN
C      901   FORMAT( 3X, 4E15.8 )
C      END
```

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SUBROUTINE ASSESS

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C      DIMENSION UNIT(3,3),CBI(3,3),CIB(3,3),VB(3),AB(3)
1      ,VEC1(3),VEC2(3),VEC3(3),VEC4(3),VEC5(3)
2      ,TMP1(3,3),TMP2(3,3),TMP3(3,3),TMP4(3,3),TMP5(3,3)
3      ,VECX(3),VECY(3),VECZ(3),TMPX(3,3),TMPY(3,3),TMPZ(3,3)
4      ,TMPA(3,3),CCIB(3,3),VBR(3),RBR(3),ACC(3)
5      ,VW(3),VR(3),ARRAY(90),Brray(90)
6      ,PVW(3,3),C1(3,3)
7      ,VEC6(6),VEC7(6)

C      COMMON / TDATA / TIME, TNEXT, TMAX, TSAMP, TSTOP
C      COMMON / FILDAT / XKM(30),PKM(30,30),F(30,30),Q(30,30),N, NMEAS
C      COMMON / SMTHER / PHI(30,30),PHIT(30,30),PKP1M(30,30),PKP1I(30,30)
1      ,AK(30,30),XKGN(30),PKGN(30,30),XKF1GN(30),XKF1GN(30,30)
C      COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2
C      COMMON / CONST / CRAD, AGRAD, HRSEC, PERCENT, XNRAD
C      COMMON / LAUCOR / OLATD, OLONG, OHT
C      COMMON / EARTH / GRAV(3), AGMX(3,3)
C      COMMON / RSTATE / RBRI(3), VBRI(3), ABRI(3), THTI(3)
1      ,GRAVI(3), CIBRI(3,3), CBRIEF(3,3), CEFBRI(3,3)
2      ,RITO(3), VITO(3), REF(3), ANET(3), OMEG(3)
C      COMMON / METEOR / TLT(400), TSRHO(400), TSP(400), TSSUND(400)
1      ,TVWX(400), TVWY(400), NALT
2      ,USRHO(400), USP(400), USSUND(400)
3      ,UVWX(400), UVWY(400)

C      DATA UNIT / 1., 3*0., 1., 3*0., 1. /
DATA NR / 16 /
DATA RHO, PS, VSOUND / .002378, 2116., 1117. /
DATA VWX, VWY / 2*0.0 /
DATA PRPH, PSPH, PVSPH / 3*0.0 /
DATA PVWPH, PVWYPH / 2*0.0 /
DATA PVW / 9*0.0 /
DATA C1 / 2*0.0, 1.0, 1.0, 3*0.0, 1.0, 0.0 /
C      CALL ZEROM ( ARRAY, 90, 1 )
C      CALL ZEROM ( Brray, 90, 1 )

C      CALL CBIMX ( THTI, CBI )
C      CALL TRANS ( CBI, CIB, 3, 3 )

C      DO 20 I = 1, 3
DO 10 J = 1, 3
TMP1(I,J) = PKGN(I,J)
TMP2(I,J) = PKGN(I+3,J+3)
TMP3(I,J) = PKGN(I+6,J+6)
TMP4(I,J) = PKGN(I+9,J+9)
TMP5(I,J) = PKGN(I+12,J+12)
CONTINUE
RBR(I) = RBRI(I) + XKGN(I)
VBR(I) = VBRI(I) + XKGN(I+3)
VEC2(I) = VBR(I)
VEC3(I) = XKGN(I+6)
VEC4(I) = XKGN(I+9)
VEC5(I) = XKGN(I+12)
CONTINUE
CALL MULT ( CBIREF, RBR, REF, 3, 3, 1 )

C      CALL SKEW ( VEC3, TMPX )
CALL ADD ( UNIT, TMPX, TMPX, 3, 3 )
CALL MULT ( CIB, TMPX, CCIB, 3, 3 )
ARRAY(1) = TIME
Brray(1) = 0.0
C      VEHICLE POSITION
C      C */

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C   CALL COOR ( REF(1), REF(2), REF(3), XLAT, XLONG, ALT )
      RM = SQRT ( REF(1)*2 + REF(2)*2 + REF(3)*2 )
      ARRAY(2) = RBR(1)
      ARRAY(3) = RBR(2)
      ARRAY(4) = RBR(3)
      BRRAY(2) = SQRT( PKGN(1,1) )
      BRRAY(3) = SQRT( PKGN(2,2) )
      BRRAY(4) = SQRT( PKGN(3,3) )

C   CALL COOR ( REF(1), REF(2), REF(3), XLAT, XLONG, ALT )
      RM = SQRT ( REF(1)*2 + REF(2)*2 + REF(3)*2 )
      ARRAY(49) = XLAT
      ARRAY(50) = XLONG
      ARRAY(51) = ALT
      ARRAY(54) = RM
      BRRAY(49) = CRAD*SQRT( PKGN(2,2) )/(RM*COS( XLAT/CRAD ))
      BRRAY(50) = CRAD*SQRT( PKGN(1,1) )/RM
      RMS = RM*RM

      CALL MULT ( TMP1, RBR, VECX, 3, 3, 1 )
      CALL INNER ( RBR, VECX, SIGRMS, 3 )
      SIGRM = SQRT ( SIGRMS/RMS )
      BRRAY(51) = SIGRM
      BRRAY(54) = SIGRM

C   CALL ECPOS ( OLATD, OLONG, OHT, VECZ(1), VECZ(2), VECZ(3) )
      DO 30 I = 1, 3
      VECX(I) = REF(I) - VECZ(I)
      CONTINUE
      RS = SQRT( VECX(1)**2 + VECX(2)**2 + VECX(3)**2 )
      ARRAY(58) = RS
      CALL MULT ( TMP1, VECX, VECY, 3, 3, 1 )
      CALL INNER ( VECX, VECY, SIGRSS, 3 )
      IF ( RS.NE.0.0 ) THEN
        SIGRSS = SIGRSS/(RS*RS)
      ELSE
        SIGRSS = 0.0
      END IF
      BRRAY(58) = SQRT ( SIGRSS )

C   BOOST REFERENCE VELOCITY AND UNCERTAINTY BOUNDS
      VMI = SQRT ( VEC2(1)**2 + VEC2(2)**2 + VEC2(3)**2 )
      ARRAY(5) = VBR(1)
      ARRAY(6) = VBR(2)
      ARRAY(7) = VBR(3)
      ARRAY(55) = VMI
      BRRAY(5) = SQRT( PKGN(4,4) )
      BRRAY(6) = SQRT( PKGN(5,5) )
      BRRAY(7) = SQRT( PKGN(6,6) )
      VMIS = VMI*VMI
      CALL MULT ( TMP2, VBR, VECX, 3, 3, 1 )
      CALL INNER ( VBR, VECX, SIGVMS, 3 )
      IF ( VMI.NE.0.0 ) THEN
        SIGVM = SQRT ( SIGVMS/VMIS )
      ELSE
        SIGVM = 0.0
      END IF
      BRRAY(55) = SIGVM

C   BODY REFERENCED VELOCITY AND UNCERTAINTY BOUNDS
      CALL ZEROM ( VEC1, 3, 1 )
      VEC1(3) = OMEGE
      CALL SKEW ( VEC1, TMPX )
      CALL MULT ( TMPX, REF, VEC1, 3, 3, 1 )
      CALL MULT ( CIBRI, VEC1, VECX, 3, 3, 1 )
      CALL SUBT ( VEC2, VECX, VECY, 3, 1 )

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CALL MULT ( CCIB, VECY, VB, 3, 3, 1 )

C   VT = SQRT ( VB(1)**2 + VB(2)**2 + VB(3)**2 )
ARRAY(20) = VB(1)
ARRAY(21) = VB(2)
ARRAY(22) = VB(3)

C   C* INERTIAL VELOCITY
C     CALL MULT ( TMP2, CBI, TMPY, 3, 3, 3 )
CALL MULT ( CIB, TMPY, TMPX, 3, 3, 3 )

C   C* PLATFORM TILT
C     CALL SKEW ( VEC2, TMPY )
CALL MULT ( CIB, TMPY, TMPZ, 3, 3, 3 )
CALL TRANS ( TMPZ, TMPA, 3, 3, 3 )
CALL MULT ( TMPZ, TMP3, TMPX, 3, 3, 3 )
CALL MULT ( TMPY, TMPA, TMPZ, 3, 3, 3 )

C     CALL ADD ( TMPX, TMPZ, TMPX, 3, 3, 3 )
BRRAY(20) = SQRT( TMPX(1,1) )
BRRAY(21) = SQRT( TMPX(2,2) )
BRRAY(22) = SQRT( TMPX(3,3) )

C   C** ANGLE OF ATTACK, SIDESLIP AND VELOCITY WRT AIR MASS W/UNCERTAIN
C     IF ( ALT.LT.400000. ) THEN

C       CALL INTRP1 ( ALT, TALT, TSRHO, NALT, RHO, PRHOPH )
CALL INTRP1 ( ALT, TALT, TSP, NALT, PS, PPSPH )
CALL INTRP1 ( ALT, TALT, TSSUND, NALT, VSOUND, PVSPH )
CALL INTRP1 ( ALT, TALT, PVWX, NALT, VWX, PVWPX )
CALL INTRP1 ( ALT, TALT, PVWY, NALT, VWY, PVWPY )
CALL INTRP1 ( ALT, TALT, USRHO, NALT, UNCRHO, SLOPE )
CALL INTRP1 ( ALT, TALT, USP, NALT, UNCSP, SLOPE )
CALL INTRP1 ( ALT, TALT, USSUND, NALT, UNCVS, SLOPE )
CALL INTRP1 ( ALT, TALT, UVWX, NALT, UNCVWX, SLOPE )
CALL INTRP1 ( ALT, TALT, UVWY, NALT, UNCVWY, SLOPE )

C       ELSE
END IF

C       VW(1) = VWX
VW(2) = VVY
VW(3) = 0.0
PVW(1,1) = UNCVWX
PVW(2,2) = UNCVWY

C       ATEMP = (VSOUND/49.02)**2
ARRAY(79) = ATEMP
ARRAY(80) = PS
ARRAY(81) = RHO
BRRAY(79) = UNCVW*SQRT( ATEMP )*(2./49.02)
BRRAY(80) = UNCPS
BRRAY(81) = UNCRHO

C       CALL TMAT ( -XLONG, TMPX )
CALL TMATP ( XLAT, TMPY )
CALL MULT ( TMPY, TMPX, TMPZ, 3, 3, 3 )
CALL TRANS ( TMPZ, TMPX, 3, 3, 3 )
CALL MULT ( CEFBRI, TMPX, TMPY, 3, 3, 3 )
CALL MULT ( TMPY, VW, VECX, 3, 3, 1 )
CALL SUBT ( VB, VECX, VR, 3, 1 )

C       UNA = UNCVW*( UNCVW**2 - VR(2)**2 + VR(3)**2 )

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C CALL TRANS ( TMPY, TMPZ, 3, 3 )
C CALL MULT ( PVW, TMPZ, TMPA, 3, 3, 3 )
C CALL MULT ( TMPY, TMPA, TMPZ, 3, 3, 3 )
C CALL ADD ( TMPX, TMPZ, TMPX, 3, 3, 3 )
BRRAY(68) = SQRT( TMPX(1,1) + TMPX(2,2) + TMPX(3,3) )
V13S = VR(1)*VR(2) + VR(3)**2
V13 = SQRT( V13S )
VECX(1) = -VR(3)/V13S
VECX(2) = 0.0
VECX(3) = VR(1)/V13S
CALL MULT ( TMPX, VECX, VECY, 3, 3, 1 )
CALL INNER ( VECX, VECY, SIGS, 3, 3 )
BRRAY(72) = CRAD*SQRT ( SIGS )
C IF ( V13.NE.0.0 ) THEN
C   VECX(1) = VR(2)*VR(1)/(VMAS*V13)
   VECX(2) = VR(2)*VR(2)/(VMAS*V13)
   VECX(3) = VR(2)*VR(3)/(VMAS*V13)
CALL MULT ( TMPX, VECX, VECY, 3, 3, 1 )
CALL INNER ( VECX, VECY, SIGBS, 3, 3 )
VECX(1) = 0.0
VECX(2) = 1.0/V13
VECX(3) = 0.0
CALL MULT ( TMPX, VECX, VECY, 3, 3, 1 )
CALL INNER ( VECX, VECY, SIGS, 3, 3 )
SIGB = SQRT ( SIGBS + SIGS )
BRRAY(84) = CRAD*SIGB
C ELSE
END IF
C * MACH NUMBER AND DYNAMIC PRESSURE W/UNCERTAINTY BOUNDS
C
PDDYNMC = 0.5*RHO*VMAS
XMACH = VMA/VSOUND
ARRAY(74) = PDDYNMC
ARRAY(77) = XMACH
CALL MULT ( TMPX, VR, VECX, 3, 3, 1 )
CALL INNER ( VR, VECX, SIGVS, 3, 1 )
SIGS = RHO*RHO*SIGVS
SIGS = (0.5*VMAS*PRHOPH*SIGRM)**2
SIGQS = SIGQS + SIGS
BRRAY(74) = SQRT ( SIGQS )
VSS = VSOUND*VSOUND
SIGMS = SIGVS/VSS
SIGS = (VMA*PVSPH*SIGRM/VSS)**2
SIGMS = SIGMS + SIGS
BRRAY(84) = SQRT ( SIGMS )
C * Q-ALPHA AND Q-BETA WITH UNCERTAINTY BOUNDS
C
QALPHA = PDDYNMC*ALPHA
QBETA = PDDYNMC*BETA
ARRAY(75) = QALPHA
ARRAY(76) = QBETA
ALPHAS = ALPHA*ALPHA
BETAS = BETA*BETA
PDYNS = PDDYNMC*PDDYNMC

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BRRAY(75) = SQRT(ALPHAS*BRRAY(74)**2 + PDYNS*BRRAY(72)**2)
BRRAY(76) = SQRT(BETAS*BRRAY(74)**2 + PDYNS*BRRAY(84)**2)

C * VEHICLE ATTITUDE AND UNCERTAINTY BOUNDS
C
CALL SMLT ( CRAD, VEC3, VEC3, 3, 1 )
CALL ADD ( THTI, VEC3, VEC3, 3, 1 )
DO 40 I = 1, 3
  VECZ(I) = CRAD*SQRT(TMP3(I,I))
CONTINUE
 40
  ARRAY(85) = VEC3(3)
  ARRAY(86) = VEC3(2)
  ARRAY(87) = VEC3(1)
BRRAY(85) = VECZ(3)
BRRAY(86) = VECZ(2)
BRRAY(87) = VECZ(1)

C * (B) AND (I) REFERENCED ACCELERATION AND UNCERTAINTY BOUNDS
C
CALL ADD ( ABRI, VEC4, VEC1, 3, 1 )
CALL DIAG ( ABRI, 3, TMPX )
CALL MULT ( TMPX, VEC5, AB, 3, 3, 1 )
CALL ADD ( AB, VEC1, VEC1, 3, 1 )
ARRAY(8) = VEC1(1)
ARRAY(9) = VEC1(2)
ARRAY(10) = VEC1(3)

C CALL MULT ( CCIB, VEC1, AB, 3, 3, 1 )
CRFTSTAT = SQRT( ABRI(1)**2 + ABRI(2)**2 + ABRI(3)**2 )
AT = SQRT ( AB(1)**2 + AB(2)**2 + AB(3)**2 )
ARRAY(23) = AB(1)
ARRAY(24) = AB(2)
ARRAY(25) = AB(3)
ARRAY(83) = AT/AGRAV

C ACCELEROMETER BIAS
C TMP4
C ACCELEROMETER SCALE FACTOR
C
CALL DIAG ( ABRI, 3, TMPZ )
CALL MULT ( TMPZ, TMP5, TMPX, 3, 3, 3 )
C PLATFORM TILT
C
CALL SKEW ( ABRI, TMPZ )
CALL MULT ( TMPZ, TMP3, TMPY, 3, 3, 3 )
C
CALL ADD ( TMP4, TMPX, TMPZ, 3, 3 )
CALL ADD ( TMPY, TMPZ, TMPX, 3, 3, 3 )
BRRAY(8) = SQRT( TMPX(1,1) )
BRRAY(9) = SQRT( TMPX(2,2) )
BRRAY(10) = SQRT( TMPX(3,3) )

C CALL MULT ( CIB, TMPX, TMPY, 3, 3, 3 )
CALL MULT ( TMPY, CIB, TMPX, 3, 3, 3 )
BRRAY(23) = SQRT( TMPX(1,1) )
BRRAY(24) = SQRT( TMPX(2,2) )
BRRAY(25) = SQRT( TMPX(3,3) )
BRRAY(83) = SQRT(BRRAY(23)**2+BRRAY(24)**2+BRRAY(25)**2)/AGRAV

C * FLIGHT PATH ANGLE
C
CALL FPA ( VSP, DDTV )

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      IF ( VEL(NE, J,J) .NE. 0.0 ) THEN
        GAMMA = CRAD*ASIN( RDOTV/(RM*VMI) )
      ELSE
        GAMMA = 0.0
      END IF
      ARRAY(56) = GAMMA

C     B = RM*VMI
      RFAC = RDOTV/B
      RFAC1 = RFAC*VMI/RM
      RFAC2 = RFAC*RM/VMI
      DENO = SQRT( B*B - RDOTV*RDOTV )

DO 50 I = 1, 3
  VEC6(I) = ( VBR(I) + RFAC1*RBR(I) )/DENO
  VEC6(I+3) = ( RBR(I) + RFAC2*VBR(I) )/DENO
CONTINUE

DO 70 I = 1, 6
  TEMP = 0.0
DO 60 J = 1, 6
  TEMP = TEMP + PKGN(I,J)*VEC6(J)
CONTINUE
  VEC7(I) = TEMP
CONTINUE

C     SIGGMS = 0.0
DO 80 I = 1, 6
  SIGGMS = SIGGMS + VEC6(I)*VEC7(I)
CONTINUE
  SIGGM = CRAD*SQRT( SIGGMS )
  BRAY(56) = SIGGM

CALL TMATY ( -XLONG, TMPX )
CALL TMATP ( XLAT, TMPY )
CALL MULT ( TMPY, TMPX, TMPZ, 3, 3, 3 )
CALL MULT ( C1, TMPZ, TMPX, 3, 3, 3 )
CALL MULT ( CBRIEF, VBR, VECX, 3, 3, 1 )
CALL MULT ( TMPX, VECX, VECY, 3, 3, 1 )
IF ( VECY(2).NE.0.0 ) THEN
  SIGMA = CRAD*ATAN2( VECY(1), VECY(2) )
ELSE
  SIGMA = 90.0
END IF
  ARRAY(57) = SIGMA

C     DENO = VECY(1)*VECY(1) + VECY(2)*VECY(2)
  VECX(1) = VECY(2)/DENO
  VECX(2) = VECY(1)/DENO
  VECX(3) = 0.0

CALL TRANS ( TMPX, TMPY, 3, 3 )
CALL MULT ( TMPY, VECX, VECZ, 3, 3, 1 )
CALL MULT ( TMP2, VECZ, VECY, 3, 3, 1 )
CALL INNER ( VECX, VECY, SIGSMS, 3 )
  SIGSM = CRAD*SQRT( SIGSMS )
  BRAY(57) = SIGSM

C ** VEHICLE ROTATION RATE
C     ARRAY(45) = OMEG(3)
      ARRAY(46) = OMEG(2)
      ARRAY(47) = OMEG(1)

C ** OUTPUT COMPUTED QUANTITIES
C

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```
      WRITE(8) (ARRAY(I), I = 1, 90)
      WRITE(8) (Brray(I), I = 1, 90)
      NR = NR + 1
      RETURN
      C
      901  FORMAT ( 7X, 4E15.8 )
      902  FORMAT ( 2X, 6E12.4 )
      C
      END
```

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```
C DIMENSION ARRAY(90), BARRAY(90)
C DATA NARRAY / 90 /
C DATA NR / 16 /
C CONTINUE
10 C READ(8) (ARRAY(I), I = 1, NARRAY)
C TIME = ARRAY(1)
C IF ( ABS(TIME-TSRCH).LT.1.0E-4 ) THEN
C   WRITE(*, 901) TIME
C   WRITE(7,NR) (ARRAY(I), I = 1, NARRAY)
C   NR = NR + 1
C   WRITE(*,901) (ARRAY(I), I = 1, NARRAY)
C   WRITE(9,902) ARRAY(1)
C   WRITE(9,902) (0.96*ARRAY(8)),(0.96*ARRAY(9)),(0.96*ARRAY(10))
C   WRITE(9,902) ARRAY(87),ARRAY(86),ARRAY(85)
C   WRITE(9,902) ARRAY(47),ARRAY(46),ARRAY(45)
C
C   REWIND 8
C   RETURN
C   ELSE
C     GO TO 10
C   END IF
C
C   901 FORMAT( 2X, 6E12.5 )
C   902 FORMAT( 5X, 3E15.8 )
C
C   END
```

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C      PROGRAM FILTER
C      PROGRAM MAIN
C
C      COMMON DER(2700) , VAR(2700) , TEMP(5400) , NDER
C      COMMON / PREUP / XKM(71) , PKM(71,71)
C      COMMON / PROPAG / X(71) , P(71,71)
C      COMMON / DRVITV / XDOT(71) , PD(71,71)
C      COMMON / LINFMT / F(71,71) , NS , NPAR
C      COMMON / LINHMT / H(35,71) , NRMESAS

C      COMMON / NOZDAT / TTIME(500) , TRLD(500) , TTLD(500)
C      ,TRRD(500) , TTRD(500)
1     ,TPL(500) , TPL1(500) , TYL1(500)
2     ,TPL2(500) , TYL2(500)
3     ,TPL3(500) , TYL3(500)
4
5     ,TRATER(500) , TRATEP(500) , TRATEY(500)
6     ,TROLL(500) , TRITCH(500) , TYAW(500)
C      COMMON / SWIND / TALT(400) , TVWX(400) , TVWY(400) , NALT
C      COMMON / SATMOS / TSRHO(400) , TSP(400) , TSSUND(400) , IATMOS
C      COMMON / ATMUNC / UWK(400) , UWY(400) , URHO(400) , USP(400) , USS(400)
C      COMMON / GIMBAL / CCLB1(3,3) , CCLB2(3,3) , CCLB3(3,3) , CCLBA(3,3)
C      ,CCLBB(3,3) , PLN , RATEC(3) , THTC(3)

C      C      BLOCK DATA
C
C      COMMON / CONST / A(71) , S(71) , R(12)
C      COMMON / TIMDAT / TMAX , HSTEP , TS , TSTART , TSTOP , TRINT
C      COMMON / LAYOUT / RS(3) , RA(3) , RT1(3) , RT2(3) , RT3(3) , RT4(3) , RT5(3)
C      COMMON / GEOMET / AREA , DIA , PSMEPS , PSRBPS
C      COMMON / SMETBL / PR(4,3,5) , YN(4,3) , XN(4,2)
1     , PRZ(4,3,3) , PRX(4,2,2) , ZN(4,3)
2     , RPLTAG(3) , WDO2TU(3) , WDH2TU(3) , TVACTU(3)
COMMON/SRBTBL/TFSA(15) TTAU(15) , TPVOL(15) , TAT(15) , TCSTR(15)
1     , TCT(15) , NTAU
2     , CM , G , GAM , PE , ABAR , PBAR , EPBAR , RHOP , XMBAR , TMP , PI
3     , DTSEP

COMMON / STRUCT / PTC1 , YWC1 , PTC2 , YWC2 , PTC3 , YWC3
COMMON / EDATA / RE , FLAT , OMEGE , XMU , XJ2 , CRAD
COMMON / LAUCOR / OLATD , OLONG , OHT
COMMON / ASTRON/CUEDEN(3,3) , RNP(3,3) , CIBRIB(3,3) , TGMMTO
COMMON / RDRDAT / XNO(3) , RLAT(3) , RLONG(3) , RHT(3) , NRDR
COMMON / ATMOSP / THALT(15) , THRHO(15) , THP(15) , THSUND(15)
COMMON / IPROPR / XMASSI , XMASS2
COMMON / APRIOR / ER(3) , EVB(3) , EQ(4) , EO(3)
1     , ESME(9) , ESRB(5)
2     , EAEO(3) , EPLM(3)
3     , EWND(3)
4     , EACH(3) , ERDR(3)
COMMON / NMEASR / NMEAS , IMEAS(5)
COMMON / IPARAM / ISSME , ISRB , IAERO , IPIUME , IWIND , JACB , JRDR
COMMON / TYPE / ITYPE
COMMON / STAGE / ISTAGE

OPEN( UNIT=1, FILE='CONTRL' , STATUS='OLD' , ACCESS='SEQUENTIAL' )
IF ( ITYPE.LT.1 ) THEN

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OPEN( UNIT=2, FILE='SYNTHT', STATUS='OLD', ACCESS='SEQUENTIAL' )
ELSE
OPEN( UNIT=2, FILE='REALME', STATUS='OLD', ACCESS='SEQUENTIAL' )
END IF
OPEN( UNIT=4, FILE='METDAT', STATUS='OLD', ACCESS='SEQUENTIAL' )
OPEN( UNIT=7, FILE='FILOUT', STATUS='NEW', ACCESS='SEQUENTIAL' )
C   OPEN( FORM='UNFORMATTED' )
OPEN( UNIT=8, FILE='SSMEOU', STATUS='NEW', ACCESS='SEQUENTIAL' )
OPEN( UNIT=9, FILE='SRBOUT', STATUS='NEW', ACCESS='SEQUENTIAL' )

DO 10 I = 1, 500
READ(1,998) TTIME(I),TRLD(I),TRD(I),TRD(I)
READ(1,999) TPL(I),TAL(I),TSRHO(I),TSP(I),TSSUND(I),TVWX(I),TVWY(I)
READ(4,996) URHOO(I),USP(I),USS(I),UWX(I),UWY(I)
CONTINUE
C   CLOSE ( UNIT = 1 )

DO 20 I = 1, NALT
READ(4,999) TAL(I),TSRHO(I),TSP(I),TSSUND(I),TVWX(I),TVWY(I)
READ(4,996) URHOO(I),USP(I),USS(I),UWX(I),UWY(I)
CONTINUE
C   CLOSE ( UNIT = 4 )

CALL ZERO
KTEST = TS/HSTEP
DER(1) = HSTEP
CONTINUE
C   CALL INITIL
C   CALL RK4FIL
C   TIME = VAR(1)
C   CALL PROPAF
C   CONTINUE
C   KS = KS + 1
IF( KS - KTEST ) 200, 100, 100
CONTINUE
KS = 0
C   CALL GETDAT( TIME )
C   CALL UPDATE
C   GO TO 700
CONTINUE
C   CONTINUE
C

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C IF( ( TIME - TMAX ) 50, 800, 800
C   CONTINUE
C IF( ( TIME - TSTOP ) 50, 900, 900
C   CONTINUE
C
C   WRITE(6,991) TIME
C   WRITE(6,991) (XKM(I), II = 1, 71)
C   WRITE(6,991) (PKM(I,I), II = 1, 71)
C
C   CLOSE( UNIT=2 )
C   CLOSE( UNIT=7 )
C   CLOSE( UNIT=8 )
C   CLOSE( UNIT=9 )
C
C   991  FORMAT ( 5X, 3E15.8 )
C   995  FORMAT(5X, 2E15.8)
C   996  FORMAT( 20X, 5E15.8 )
C   997  FORMAT(3X, 5E15.8 )
C   998  FORMAT( 5X, 5E15.8 )
C   999  FORMAT( 5X, 7E15.8 )
C
C   STOP
C   END
C   SUBROUTINE GETDAT( TIME )
C
C   COMMON / ACMEAS / ACM(3)
C
C   COMMON / MEMEAS / YMSME(6,3)
C   COMMON / SRMEAS / YMSRB(2)
C   COMMON / RDMEAS / AZM(3), ELM(3), RNGM(3)
C   COMMON / TYPE / ITYPE
C
C   IF( ITYPE.LT.1 ) THEN
C
C   ELSE
C
C   READ( 2, 901 ) (ACM(I), I = 1, 3)
C   READ( 2, 902 ) ((YMSME(I,J), I = 1, 6), J = 1, 3)
C   READ( 2, 901 )(AZM(I), ELM(I), RNGM(I), I = 1, 3)
C   READ( 2, 903 ) YMSRB(1)
C   READ( 2, 903 ) YMSRB(2)
C   DO 10 I = 1, 3
C   ACM(I) = ACM(I)/0.96
C   CONTINUE
C   IF( TIME.LT.20.
C      CALL ZEROM( ACM, 3, 1 )
C   ELSE
C   END IF
C   IF( ( TIME.GT.70. ) THEN
C
C   10
C
C

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```
END IF
C      END IF
C      RETURN
 901   FORMAT( 5X,3E15.8 )
 902   FORMAT( 5X,6E15.8 )
 903   FORMAT( 5X, E15.8 )
END

SUBROUTINE ZERO
COMMON DER(2700), VAR(2700), TEMP(5400), NDER

C      DER(1) = 0.0
C      VAR(1) = 0.0
DO 10 I = 1, 2699
C      DER(I+1) = 0.0
C      VAR(I+1) = 0.0
C      TEMP(I) = 0.0
C      K = I + 2699
C      TEMP(K) = 0.0
10  CONTINUE

C      RETURN
END
```

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BLOCK DATA

```

C      COMMON / CONST / A(71), R(12)
COMMON / TIMDAT / TMAX, HSTEP, TSAMP, TSTART, TSTOP, TRINT
COMMON / LAYOUT / RS(3), RA(3), RT1(3), RT2(3), RT3(3), RT4(3), RT5(3)
COMMON / GEOMET / AREA, DIA, PSMEPS, PSRBPS
COMMON / SNETBL / PR(4, 3, 5), YN(4, 3), XN(4, 2)
1      , PRZ(4, 3, 3), PRX(4, 2, 2), ZN(4, 3)
2      , RPLTAG(3), WDO2TU(3), WDH2TU(3), TVACTU(3)
COMMON/SRBTBL/TFFSA(15), TTAU(15), TPVOL(15), TAT(15), TCSTR(15)
1      , TCT(15), NTAU
2, CM, G, GAM, PE, ABAR, PBAR, EPBAR, RHOP, XLNGTH, RBAR, XMBAR, TEMP, PI
3, DTSEP
COMMON / STRUCT / PTC1, YWC1, PTC2, YWC2, PTC3, YWC3
COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2, CRAD
COMMON / LAUCOR / OLATD, OLONG, OHT
COMMON/ASTRONT/ CUENED(3,3), RNP(3,3), CIBRI(3,3), CBRI(3,3), TGMIIT0
COMMON / RDRDAT / XNO(3), RLAT(3), RLONG(3), RHT(3), NRDR
COMMON / ATMOSP / THALT(15), THRHO(15), THP(15), THSUND(15)
COMMON / IPROPR / XMASSI, XMASS2
COMMON / APRIOR / ER(3), EVB(3), EQ(4), EO(3)
1      , ESME(9), ESRB(5)
2      , EARO(3), EPLM(3)
3      , EWND(3)
4      , EACB(3), ERDR(3)
COMMON / LINHMT / F(71,71), NS, NPAR
COMMON / LINHMT / H(35,71), NRMEAS
COMMON / TYPE / ITYPE
COMMON / NMEASR / NMEAS, IMEAS(5)
COMMON / IPARAM / ISSME, ISRIB, IAERO, IPLUME, IWIND, JACB, JRDR
COMMON / STAGE / ISTANCE
COMMON / STGDAT / R2(3), VB2(3), Q2(4), OMEGA2(3)
COMMON / SATMOS / TSRHO(400), TSP(400), TSSUND(400), IATMOS
COMMON / SWIND / TALT(400), TVWX(400), TVWY(400), NALT

C      DATA ITYPE / 1 /
DATA ISTANCE / 1 /
CSTG2  DATA TMAX, HSTEP, TSAMP, TSTART, TRINT / 515., 0.5, 1.0, 129., 170. /
DATA TMAX, HSTEP, TSAMP, TSTART, TRINT / 0.5, 0.2, 1.0, 0.0, 15. /
DATA TSTOP / 999. /
CSTG2  DATA NMEAS / 5 /
DATA IMEAS / 1, 0, 3, 4, 0 /
DATA NRMEAS / 1 /
DATA LATMOS / 1 /
DATA NALT / 400 /
DATA NS, NPAR / 13, 58 /
DATA F / 5041.0, 0.0 /
CSTG2  DATA NRMEAS / 30 /
DATA IMEAS / 32 /
DATA H / 2485.0, 0.0 /
C      C*** GEOMETRICAL DATA
C      DATA AREA, DIA, PSMEPS, PSRBPS / 2690.0, 107.525, 44.3778, 122.598 /
DATA RT1 / -100.8333, 0.0, -31.625 /

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C *** SRB TABULAR DATA
C
DATA RT2 / -102.7642, -4.4167, -23.2617 /
DATA RT3 / -102.7642, 4.4167, -23.2617 /
1   .3978E+6,.4013E+6,.4115E+6,.4112E+6,.3795E+6,
2   .3534E+6,.3152E+6,.816E+5,0.0/
DATA TPVOL/.15E+7,.3E+7,.45E+7,.52E+7,.116E+8,.181E+8,
1   .266E+8,.335E+8,.435E+8,.523E+8,.751E+8,
2   1.E+8,1.46E+8,3.E+9,3.E+9/
DATA TAT/.2278E+4,.2287E+4,.2296E+4,.2316E+4,.2334E+4,.2351E+4,
1   .2366E+4,.2381E+4,.2458E+4,.2458E+4,.2426E+4,
2   .2439E+4,.2451E+4,.2458E+4,.2458E+4,.2426E+4,
DATA TCSTR/.6044E+5,.6045E+5,.6046E+5,.6046E+5,.6039E+5,.6031E+5,
1   .6024E+5,.6024E+5,.6025E+5,.6025E+5,.6017E+5,
2   .601E+5,.6005E+5,.5903E+5,.5813E+5/
DATA TTAU/0.,1.94,3.96,8.02,12.04,15.94,
1   19.77,23.51,27.27,31.00,34.38,
2   37.94,41.05,42.93,43.2/
DATA TCT / 1.7347,1.7352,1.7345,1.7325,1.7306,1.7283,
1   1.7270,1.7263,1.7252,1.7234,1.7221,
2   1.7210,1.7185,1.6890,1.722/
DATA CM,G,GAM,PE,ABAR,PBAR,EPBAR,RHOP /
1   .987,386.09,1.1382,5.,3680,625..,35.,063456/
DATA XLNGTH,RBAR,XMBAR,TEMP,PI/1350.,1545.4,28.319,6092.6,3.1416/
DATA DTSEP / 4.9 /
C *** SSME TABULAR DATA
C
DATA RPLTAG / 3*3006. /
DATA WDO2TU / 889.59, 892.04, 891.62 /
DATA WDH2TU / 147.68, 148.08, 148.02 /
DATA TVACTU / 468028.,468968.,469079./
C61C DATA WDO2TU / 892.41,892.55,892.29 /
C61C DATA WDH2TU / 148.43,148.45,148.40 /
C61C DATA TVACTU / 469250.,470091.,469741./
C
DATA PR/-450195,-.0717593,.0250795,0.0,-.849847,3*0.0,.206968,
1   -.0596156,.0223651,0.0,1.448318,3*0.0,4*0.0,
2   1.196201,3*0.0,-1.49969,-1.4682,
3   6*0,-.224458,.05352,-.00757568,0.0,1.0,7*0.0,-.0621559,3*0.0,
4   3.11118,-.175361,6*0.0,724.708,-138.313,40.2932,0.0/
DATA YN/-5.29485,918.6935,-45.4427,24.8829,-.98861,153.563,
1   -8.18426,4.4164,-2668.66,479997.,-17680.5,11570.7/
DATA XN/-27717,2.97447,-1.06196,0.0,.00685,.693611,2*0.0/
DATA PRZ/-142009,420972,-.515623,.208368,1.09595E-2,
1   -3.09852E-3,2.46712E-3,-2.80349E-4,-8.86243,5.79738,
2   -4.53574,.993182,210435,-1.10734,.459839,0.0,-8.09872E-2,
3   -394479,-1.160137,0.0,43.7468,-245.92,101.362,0.0,-1.38568,
4   8.41244,-3.11896,0.0,.549916,-3.00494,1.08354,0.0,-277.342,
5   1856.63,-677.963,0.0/

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C*** INITIAL VEHICLE MASS, POSITION, VELOCITY AND ATTITUDES
C
C   DATA PRX/-4.2873,5.52804,-2.64673,0,0,8.35593,-18.3258,
C   1 9.85097,0,0,-6.3079E-3,,3*0.0,2.26311E-4,-5.49228E-4,
C   2 3.19372E-4,0.0/
C   DATA ZN / 400.,15000.,0.0,0.0,-100.0, 350.,
C   1 0.0, 0.0, 37.3, 5.0, 0.0, 0.0/
C
C   DATA R2 ,VB2,Q2,OMEGA2 / 3*0.0,3*0.0
C   1      DATA R2 ,VB2,Q2,OMEGA2 /'4*0.0,3*0.0 /
C   C61C 1      ,4450.,70.,-0.
C   C61C 2      ,4*0.0,3*0.0 /
C   C61A DATA R2 ,VB2,Q2,OMEGA2 /'4*0.0,3*0.0 /
C   C61A 1      ,135991E+6,..279625E+6,-.21062E+8
C   C61A 2      ,4210.,-100.,20.
C   C61A DATA R2 , VB2, Q2, OMEGA2 /'05367,.9174,-.2748,-.2559,3*0.0 /
C   C51B 1      ,4230.,2*0.0
C   C51B 2      ,5367E-1,.9174E+0,.2748E+0,-.2559E+0.3*0.0/
C
C   DATA ISSME,ISRB,IAERO,IPLUME,IWIND,JACB,JRDR/
C   1 1,1,3*1,2*1 /
C   CSTG21 1,0,3*1,2*1 /
C
C   DATA NRDR / 3 /
C   CSTG2 DATA XNO / 0.0, 0.0, 0.0003 /
C
C*** RADAR SITE COORDINATES
C
C   DATA RLAT / 28.226553, 28.528886, 28.626091 /
C   C61C DATA RLONG / -80.599293, -80.590226, -80.682809 /
C   C61C DATA RHT / 65.0, 37.0, 52.0 /
C   DATA RLAT / 28.226391, 28.463168, 28.625932 /
C   DATA RLONG / -80.599287, -80.583111, -80.682805 /
C   DATA RHT / -43.8, -48.6, -58.1 /
C
C*** PROCESS NOISE VARIANCES
C
C   DATA A / 3*0.0, 2*0.05, 0.1, 4*1.E-4, 3*0.0
C   *, 0., 1.E-1, 1.E+0, 2*1.E-1, 1.E+2, 1.E+1, 1.E+0, 1.E+1
C   +, 0., 1.E-1, 1.E+0, 2*1.E-1, 1.E+2, 1.E+1, 1.E+0, 1.E+1
C   1., 0., 1.E-1, 1.E+0, 2*1.E-1, 1.E+2, 1.E+1, 1.E+0, 1.E+1
C   2., 1.E-2, 2*1.E-2, 5.E+4, 2*1.5E+5, 2*1.E+0, 1.E+0, 3*1.E-2
C   3., 1.E-2, 1.E-2, 1.E+2, 1.E-2, 1.E-2, 1.E+2, 1.E-2, 1.E-2, 1.E+2
C   4., 2*0.0, 3.E-4, 4.E-3, 2.E+2, 2*0.0, 3.E-4, 4.E-3, 2.E+2 /
C
C*** MEASUREMENT NOISE VARIANCES
C   DATA R/ 12*1.E+32 /
C   DATA R / .25
C   1 ,1.E+16

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2   1.E+4,1.E+1,1.E+0,1.E+5,1.E+4,1.E+1
3   1.E-3,1.E-3,1.E+4
4   1.E+3 /



C*** INITIAL STATE & PARAMETER UNCERTAINTIES, ONE-SIGMA VALUES

C
C     DATA ER / 3*100. /
C     DATA EVB / 3*1. /
C     DATA EQ / 4*1.E-3 /
C     DATA EO / 3*0.0 /


C
C     DATA ESME / 1.E+2,1.E-1,1.E+0,2*1.E-1,1.E+2,1.E+1,1.E+0,1.E+1 /
C     DATA ESRB / 1.E+3,1.E-2,3.E-4,4.E-3,1.E+2 /
C     DATA EARO / 1.E-2,2*1.E-2 /
C     DATA EPLM / 5.E+4,2*1.5E+5 /
C     DATA EWND / 2*1.E+0,1.E+0 /
C     DATA EACH / 3*1.E-2 /
C     DATA EADR / 1.E-2,1.E-2,1.E+2 /
C     DATA ERDR / 1.E-2,1.E-2,1.E+2 /


C*** BODY REFERENCED COORDINATES OF IMU LOCATION

C
C     DATA RS / -15.387, 0.0, -29.875 /


C*** BODY REFERENCED AERODYNAMIC REFERENCE CENTER

C
C     DATA RA / 3*0.0 /


C*** TABULAR ATMOSPHERIC MODEL DATA FOR ALTITUDE ABOVE 60K FEET

C
C     DATA THALT / 60000.0,70000.0,80000.0,90000.0,100000.0
C     1,110000.0,120000.0,130000.0,140000.0,150000.0
C     2,160000.0,170000.0,180000.0,190000.0,200000.0 /


C
C     DATA THRHO / .2256E-3,.1392E-3,.8571E-4,.5315E-4,.3318E-4
C     1,.2066E-4,.1290E-4,.8191E-5,.5281E-5,.3456E-5
C     2,.2322E-5,.1590E-5,.1105E-5,.7654E-6,.5277E-6 /


C
C     DATA THP / 151.,93.73,58.51,36.78,23.27
C     1,14.84,9.602,6.31,4.206,2.842
C     2,1.942,1.33,.9084,.6155,.4135 /


C
C     DATA THSUND / 967.6,970.4,977.1,983.4,990.4
C     1,1002.,1020.,1038.,1055.,1072.
C     2,1081.,1081.,1072.,1060.,1047. /


C*** EARTH MODEL AND CONSTANT DATA

C
C     DATA RE,FLAT,OMEGE,XMU,XJ2/20925606.,298.257224,.7292115E-4
C     1,1.4076468E+16,.10827E-2 /
C     DATA CRAD / 57.295779 /
C     DATA RNP / -1.0,3*0.0,-1.0,3*0.0,1.0 /
C     DATA TGMMTO / 0.0 /
C     DATA CUENED / 2*0.0,-1.0,0.0,1.0,0.0,2*0.0 /
C     DATA CBRIB / 2*0.0,1.0,0.0,1.0,0.0,-1.0,2*0.0 /


C

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C*** LAUNCH SITE COORDINATES
C
C      DATA OLATD, OLONG, OHT / 28.62666, -80.62162 , 50. /
C
C*** MAIN ENGINE THRUST STRUCTURAL DEFLECTION COEFFICIENTS
C
C      DATA PTC1,YWC1,PTC2,YWC2,PTC3,YNC3/-0.4,0.1,-0.3,-0.4,-1.4,0.8/
C
END

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SUBROUTINE INITIL
C
C      DIMENSION OMEG(3),THT(3),VEC(3),TMP1(3,3),TMP2(3,3),TMP3(3,3)
C
COMMON DER(2700), VAR(2700), TEMP(5400), NDER
COMMON / TIMDAT / TMAX, HSTEP, TS, TSTART, TSTOP, TRINT
COMMON / CONST / A(71), S(71), RR(12)
COMMON / LAUCOR / OLATD, OLONG, OHT
COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2, CRAD
COMMON/ASTRON/CUEDEN(3,3),RNP(3,3),CBRIB(3,3),CBRIB(3,3),TGMMTO
COMMON / APRIOR / ER(3), EVB(3), EQ(4), EO(3)
1      ,ESME(9), ESRB(5)
2      ,EARO(3), EPLM(3)
3      ,EWND(3)
4      COMMON / STATES / R(3), VB(3), Q(4), OMEGA(3)
COMMON / RDOTI / RDI(3)
COMMON / STAGE / ISTAGE
COMMON / STGDAT / R2(3),VB2(3),Q2(4),OMEGA2(3)
COMMON / PREUP / XKM(71), PKM(71,71)
C
CALL ECPOS ( OLATD, OLONG, OHT, VEC(1), VEC(2),
CALL ECPOS ( OLATD, OLONG, 0.0, X0, Y0, Z0 )
C
E = 1.0/FLAT
RDMAG = SQRT( X0**2 + Y0**2 )
RMAG = SQRT( VEC(1)**2 + VEC(2)**2 + VEC(3)**2 )
DEV = CRAD*2.*E*(1.-E/2.)*(RDMAG/RMAG)*SIN((180.0-OLATD)/CRAD)
OLATC = OLATD - DEV
C
CALL CIEFMX ( 0.0, TMP1 )
CALL TMATY ( -OLONG, TMP2 )
CALL MULT ( TMP2, TMP1, TMP3, 3, 3, 3 )
CALL TMATP ( OLATD, TMP1 )
CALL MULT ( TMP1, TMP3, TMP2, 3, 3, 3 )
CALL MULT ( CUENED, TMP2, CIBRI, 3, 3, 3 )
C
RDI(1) = 0.0
RDI(3) = 0.0
RAD = SQRT ( VEC(1)**2 + VEC(2)**2 )
RDI(2) = OMEGE*RAD
C
IF ( ISTAGE.EQ.1 ) THEN
C
CALL MULT ( CIBRI, VEC, R, 3, 3, 1 )
WRITE(*, 901) (R(I), II = 1, 3)
C
CREATE CALL SMLT ( OMEGE, OMEG, VEC, 3, 1 )
CREATE CALL MULT ( TMP1, VEC, OMEGA, 3, 3, 1 )
C
IF( CBRIB(3,3) ) 10, 20, 10
10    CONTINUE
TH(1) = CRAD*ATAN2( CBRIB(2,3), CBRIB(3,3) )
20    CONTINUE
IF( CBRIB(3,3).EQ.0.0 ) THT(1) = 0.0

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      THT(2) = CRAD*ASIN( -CBRIB(1,3)
      IF( CBRIB(1,1) ) 30, 40, 30
      CONTINUE
      THT(3) = CRAD*ATAN2( CBRIB(1,2), CBRIB(1,1) )
      IF( CBRIB(1,1).EQ.0.0 ) THT(3) = 0.0

      C   CALL E2QUAT ( THT, Q )
      C
      C   ELSE
      C     DO 60 I = 1, 3
      C       R(I) = R2(I)
      C       VB(I) = VB2(I)
      C       Q(I) = Q2(I)
      C       CRATE OMEGA(I) = OMEGA2(I)
      C       CONTINUE
      C       Q(4) = Q2(4)
      C       WRITE(*, 901) (R(I), I = 1, 3)
      C       WRITE(*, 901) (VB(I), I = 1, 3)
      C       WRITE(*, 901) (Q(I), I = 1, 4)
      C
      C   END IF

      C   CALL ZEROM( PKM, 71, 71 )
      C   CALL ZEROM( XKM, 71, 1 )
      C   CALL ZEROM( S, 71, 1 )

      C   VAR(1) = TSTART

      C   DO 100 I = 1, 3
      C     XKM(I) = R(I)
      C     VAR(I+1) = R(I)
      C     PKM(I,I) = ER(I)**2
      C     XKM(I+3) = VB(I)
      C     VAR(I+4) = VB(I)
      C     PKM(I+3,I+3) = EVB(I)**2
      C     XKM(I+6) = Q(I)
      C     CTHT VAR(I+7) = Q(I)
      C     PKM(I+6,I+6) = EQ(I)**2
      C     CRATE XKM(I+10) = OMEGA(I)
      C     CRATE VAR(I+11) = OMEGA(I)
      C     CRATE PKM(I+10,I+10) = EO(I)**2
      C     S(I+6) = A(I+6)**2
      C
      C   CONTINUE
      C   XKM(10) = Q(4)
      C   VAR(11) = Q(4)
      C   PKM(10,10) = EQ(4)**2
      C   S(10) = A(10)**2
      C
      C   DO 120 I = 1, 9
      C     IP13 = I + 13
      C     IP13P9 = IP13 + 9
      C     IP22P9 = IP13P9 + 9
      C     PKM(IP13,IP13) = ESME(I)**2

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```
PKM(IP13P9,IP13P9) = ESME(I)**2
PKM(IP22P9,IP22P9) = ESME(I)**2
CONTINUE
C
DO 130 I = 1, 5
IF61 = I + 61
IF61P5 = IP61 + 5
PKM(I+61,I+61) = ESRB(I)**2
PKM(IP61P5,IP61P5) = ESRB(I)**2
CONTINUE
C
DO 140 I = 1, 3
PKM(I+40,I+40) = EARO(I)**2
CONTINUE
C
DO 150 I = 1, 3
PKM(I+43,I+43) = EPLM(I)**2
CONTINUE
C
DO 160 I = 1, 3
PKM(I+46,I+46) = EWND(I)**2
CONTINUE
C
DO 170 I = 1, 3
PKM(I+49,I+49) = EACB(I)**2
CONTINUE
C
DO 180 I = 1, 3
PKM(I+52,I+52) = ERDR(I)**2
PKM(I+55,I+55) = ERDR(I)**2
PKM(I+58,I+58) = ERDR(I)**2
CONTINUE
C
L = 0
DO 200 I = 1, 71
DO 200 J = I, 71
L = L + 1
VAR(71+L+1) = PKM(I,J)
CONTINUE
C
RETURN
C
901 FORMAT( 5X, 3E15.8 )
C
END
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C      SUBROUTINE PROPAF
C
COMMON DER(2700), VAR(2700), TEMP(5400), NDER
COMMON / PROPAG / X(71), P(71,71)
COMMON / DRVITV / XDOT(71), PD(71,71)
COMMON / LINFMT / F(71,71), NS, NPAR
COMMON / TYPE / ITYPE

C      NDERV = NS + NPAR
NMTRX = (NS+NPAR)*( (NS+NPAR+1) )/2
NDER = NDERV
IF ( ITYPE.GT.0 ) NDER = NDERV + NMTRX

C      DO 10 I = 1, (NS+NPAR)
X(I) = VAR(I+1)
CONTINUE
10
C      CALL XDVEC
CALL ZDVEC

C      DO 20 I = 1, (NS+NPAR)
DER(I+1) = XDOT(I)
CONTINUE
20
C      IF ( ITYPE.LT.1 ) GO TO 50
C      L = 0
DO 30 I = 1, (NS+NPAR)
DO 30 J = I, (NS+NPAR)
L = L + 1
P(I,J) = VAR(NS+NPAR+L+1)
P(J,I) = P(I,J)
CONTINUE
30
C      CALL PDMTRX
C      L = 0
DO 40 I = 1, (NS+NPAR)
DO 40 J = I, (NS+NPAR)
L = L + 1
DER(NS+NPAR+L+1) = PD(I,J)
CONTINUE
40
C      CONTINUE
50
C      RETURN
C
901  FORMAT( 5X, 3I5 )
902  FORMAT( 5X, 5E15.8 )
C
END
SUBROUTINE RK4FILE
REAL K1(2700), K2(2700), K3(2700), K4(2700)
COMMON DER(2700), VAR(2700), TEMP(5400), NDER
C

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```
DO 100 I = 1, NDER
TEMP(I) = VAR(I+1)
100 CONTINUE
C
TIME = VAR(1)
DO 10 I = 1, NDER
K1(I) = DER(1)*DER(I+1)
10 CONTINUE
C
DELT = 0.5*DER(1)
TIME = TIME + DELT
VAR(1) = TIME
C
DO 20 I = 1, NDER
K = I + NDER
TEMP(K) = TEMP(I) + 0.5*K1(I)
VAR(I+1) = TEMP(K)
20 CONTINUE
C
CALL PROPAF
C
DO 30 I = 1, NDER
K2(I) = DER(1)*DER(I+1)
K = I + NDER
TEMP(K) = TEMP(I) + 0.5*K2(I)
VAR(I+1) = TEMP(K)
30 CONTINUE
C
CALL PROPAF
C
TIME = TIME + DELT
VAR(1) = TIME
C
DO 40 I = 1, NDER
K3(I) = DER(1)*DER(I+1)
K = I + NDER
TEMP(K) = TEMP(I) + K3(I)
VAR(I+1) = TEMP(K)
40 CONTINUE
C
CALL PROPAF
C
DO 50 I = 1, NDER
K4(I) = DER(1)*DER(I+1)
VAR(I+1) = TEMP(I)+0.16666667*(K1(I)+2.0*K2(I)+2.0*K3(I)+K4(I))
50 CONTINUE
C
CALL PROPAF
C
RETURN
END
```

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```
      SUBROUTINE COOR ( RYE, RYE, RZE, PHI, LAMDA, HTI )
REAL LAT, LONG, LAMDA
C COMMON / EDATA / RE, PLAT, OMEGE, XMU, XJ2, CRAD
C DATA EPS / 1.E-9 /
C
C LAMDA = CRAD*ATAN2( RYE, RZE )
C CLAM = COS( LAMDA/CRAD )
C E = 1.0/FLAT
C OMES = ( 1.0 - E ) **2
C
C DO 100 I = 1, 50
C
C PHII = PHI
C
C CPHI = COS( PHI/CRAD )
C SPHI = SIN( PHI/CRAD )
C
C ASQ = CPHI**2 + OMES*SPHI**2
C A = SQRT( ASQ )
C ASQSQ = ASQ*ASQ
C
C HTI = RYE/(CPHI*CLAM) - RE/A
C
C FPHI = RZE - SPHI*(RE*OMES/A + HTI)
C DFDP = -CPHI*((RE*OMES/A)*(1.0 + (E*(E-2.0)*SPHI**2)/ASQSQ)+HTI)
C DPHI = (FPHI/DFDP)*CRAD
C
C PHI = PHII - DPHI
C
C IF ( ABS( DPHI ) - EPS ) 200, 200, 100
C
C 100 CONTINUE
C
C 200 CONTINUE
C
C RETURN
END
      SUBROUTINE ECPOS ( LAT, LONG, HT, RYE, RYE, RZE )
REAL LAT, LONG
C COMMON / EDATA / RE, PLAT, OMEGE, XMU, XJ2, CRAD
C
C CLAT = COS( LAT/CRAD )
C SLAT = SIN( LAT/CRAD )
C CLONG = COS( LONG/CRAD )
C SLONG = SIN( LONG/CRAD )
C
C E = 1.0/FLAT
C OMES = ( 1.0 - E ) **2
C ASQ = CLAT**2 + OMES*SLAT**2
C A = SQRT( ASQ )
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C      R = RE/A + HT
C      S = RE*OMES/A + HT
C      RXE = R*CLAT*CLONG
C      RYE = R*CLAT*SLONG
C      RZE = S*SLAT

C      RETURN
END
SUBROUTINE AGRAV ( R )
DIMENSION R(3)

C      COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2, CRAD
C      COMMON / EARTH / GRAVI(3), AGMX(3,3)

C      RMAGS = R(1)*R(1) + R(2)*R(2) + R(3)*R(3)
RMAG = SQRT( RMAGS )
RMAGQ = RMAGS*RMAG

C      RRS = (RE/RMAG)*2
RZS = (R(3)/RMAG)**2
XMUX = XMU*(1.0+1.5*XJ2*RRS*(1.0-5.0*RZS))
XMUY = XMU
XMUZ = XMU*(1.0+1.5*XJ2*RRS*(3.0-5.0*RZS))

C      GRAVI(1) = -XMUX*R(1)/RMAGQ
GRAVI(2) = -XMUY*R(2)/RMAGQ
GRAVI(3) = -XMUZ*R(3)/RMAGQ

C      FAC1 = XMU*XJ2*RRS*( 2.*(1.-5.*RZS) - 1. )/RMAGQ
FAC4 = XMU*XJ2*RRS*( 2.*(1.-5.*RZS) + 4. )/RMAGQ

C      AGMX(1,1) = -XMUX/RMAGQ + 3.0*(R(1)/RMAG)*2*(XMUX/RMAGQ + FAC1)
AGMX(2,1) = 3.0*(R(1)*R(2)/RMAGS)*(XMUX/RMAGQ + FAC1)
AGMX(3,1) = 3.0*(R(1)*R(3)/RMAGS)*(XMUX/RMAGQ + FAC4)

C      AGMX(1,2) = AGMX(2,1)
AGMX(2,2) = -XMUY/RMAGQ + 3.0*(R(2)/RMAG)*2*(XMUY/RMAGQ + FAC1)
AGMX(3,2) = 3.0*(R(2)*R(3)/RMAGS)*(XMUY/RMAGQ + FAC4)

C      AGMX(1,3) = AGMX(3,1)
AGMX(2,3) = AGMX(3,2)
AGMX(3,3) = -AGMX(1,1) - AGMX(2,2)

C      RETURN
END
SUBROUTINE CIEFMX ( TIME, CIEF )

C      DIMENSION CIEF(3,3)

C      COMMON / EDATA / RE, FLAT, OMEGAE, XMU, XJ2, CRAD
C      THTE = OMEGAE*CRAD*TIME
STHT = SIN( THTE/CRAD )

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```
C      CTHT = COS( THTE/CRAD )
      CIEF(1,1) = CTHT
      CIEF(2,1) = -STHT
      CIEF(3,1) = 0.0
      CIEF(1,2) = STHT
      CIEF(2,2) = CTHT
      CIEF(3,2) = 0.0
      CIEF(1,3) = 0.0
      CIEF(2,3) = 0.0
      CIEF(3,3) = 1.0
```

```
      RETURN
      END
```

C

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SUBROUTINE XDVEC

```

C      SUBROUTINE XDVEC
C
C      DIMENSION RD(3) , VBD(3) , QD(4) , OCV(3) , QDMTRX(4,4) , TSSME(3) , TSRB(3)
C      , CEFLL(3,3) , CBRIEF(3,3) , VA(3) , AERO(3) , THRSTS(3)
1     , OUT(3) , VEC(3) , TMP1(3,3) , TMP2(3,3) , TMP3(3,3)
2     , OMEGAD(3) , DRT(3) , DRA(3) , DRACFP(3) , DRACCF(3) , TPLUM(3)
3     , OCIO(3) , THRST(3) , TTSME(3) , TTCSR(3)
4     , C
C
C      COMMON DER(2700) , VAR(2700) , TEMP(5400) , NDER
C      COMMON / TIMDAT / TMAX , HSTEP , TSAMP , TSTART , TSTOP , TRINT
C      COMMON / CONST / A(71) , S(71) , RR(12)
C      COMMON / PROPAG / X(71) , P(71,71)
C      COMMON / DRVITV / XDOT(71) , PD(71,71)
C      COMMON / STATES / R(3) , VB(3) , Q(4) , OMEGA(3)
C      COMMON / GIMBAL / CCLB1(3,3) , CCLB2(3,3) , CCLB3(3,3) , CCLBA(3,3)
1     , CCLBB(3,3) , PL , RATEC(3) , THTC(3)
C      COMMON / PROPER / XMASS , OMASST , XIMTRX(3,3) , XIMATI(3,3) , RCG(3)
C      COMMON / FNDOT / RHO , PS , VSOUND , XMACH , PRHOH , PPSH
C      COMMON / LAYOUT / RS(3) , RA(3) , RT1(3) , RT2(3) , RT3(3) , RTA(3) , RTB(3)
C      COMMON / GEOMET / AREA , DIA , PSMEPS , PSRBPS
C      COMMON / AERO / CFO(3) , CFALP(3) , CFBBT(3) , CFQ(3,3) , CM0(3) , CMALP(3)
1     , CMBBT(3) , CMQ(3,3) , CF(3) , CM(3)
C      COMMON / FLUME / FPLUME(3) , FPALP(3) , FPBET(3) , TPALUME(3) , TPALP(3)
1     , TPBET(3) , FPALT(3) , TPALT(3) , FPDP(3) , TPDP(3)
C      COMMON / TMAT / CBI(3,3) , CIB(3,3) , CLLB(3,3) , CEFBRI(3,3)
C      COMMON / VARIAB / VR(3) , VW(3) , VWGRAD(3)
C      COMMON / COMBO / AVSO2M , AVSDO2 , RAV , RAVD , RAVM , QA , QAD , QAOM , OOMASS
1     , RAOM , QOM , QDYN , RHOA , RAD , QODIA
C      COMMON / APARTL / PAMBRI(3,3) , PAMBVB(3,3) , ACC(3) , THRUST(3)
C      COMMON / TESRDY / TSSME1(3) , TSSME2(3) , TSSME3(3) , TSRE(3) , TSRBB(3)
C      COMMON / TTPRDV / TTSME1(3) , TTSME2(3) , TTSME3(3) , TTSSRA(3) , TTCSRBB(3)
C      COMMON / PVECTR / AVEC(3)
C      COMMON / VEHPOS / REF(3)
C      COMMON / SMEDAT / TVACL(3) , XISPL(3) , WDO2H(3) , WDH2H(3) , WD(3)
1     , CVTVCL(3) , CVISPL(3) , CVWD02(3) , CVWDH2(3)
2     , CVWD(3) , CVWDG0(3) , CVWDGH(3) , PCTAG(3) , OMASL(3)
C      COMMON / SRBDAT / TVACS(2) , XISPS(2) , XMD(2) , AEXIT(2)
1     , CVPOH(2) , CVTVCS(2) , CVISPS(2) , CVND(2) , CYAE(2)
2     , OMASS(2)
C      COMMON / EARTH / GRAV(3) , AGMX(3,3)
C      COMMON / EDATA / RE , FLAT , OMEGE , XMU , XJ2 , CRAD
C      COMMON / RDOTI / RDI(3)
C      COMMON / ASTRON / CUENED(3,3) , RNP(3,3) , CIBRI(3,3) , CBRIB(3,3) , TGMTT0
C      COMMON / TYPE / ITYPE
C      COMMON / STAGE / ISTAGE
C
C      DATA JUMP / 0 /
C
C      CALL CONTRL ( TIME , PL )
C
C      DO 100 I = 1 , 3
C      R(I) = X(I)
C      VB(I) = X(I+3)

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```
100      OMEGA(I) = RATEC(I)
        CONTINUE
C       R-DOT EQUATION
C
C       CALL CBIMX ( THTC, CBI )
C
510      IF ( JUMP ) 510, 510, 530
        CONTINUE
C
C       CALL E2QUAT ( THTC, QD )
        DO 520 I = 1, 4
        VAR(I+6+1) = QD(I)
        X(I+6) = QD(I)
        CONTINUE
C
520      CONTINUE
C
530      CONTINUE
C
        IF ( TIME - TRINT ) 580, 540, 540
540      CONTINUE
C
        IF ( JUMP ) 550, 550, 560
550      CONTINUE
C
        WRITE(*, 998) TIME, TRINT
        WRITE(*, 998) (QD(I), I = 1, 4)
        JUMP = 1
C
560      CONTINUE
C
        DO 570 I = 1, 4
        Q(I) = X(I+6)
        CONTINUE
C
570      CONTINUE
C
        CALL CBIMXQ ( Q, CBI )
        CALL QUAT2E ( Q, THTC )
C
580      CONTINUE
C
        CALL MULT ( CBI, VB, RD, 3, 3, 1 )
C
        CALL CIEFMX ( TIME, TMP1 )
        CALL TRANS ( TMP1, TMP2, 3, 3 )
        CALL MULT ( CIBRI, TMP2, CEFBRI, 3, 3 )
        CALL TRANS ( CEFBRI, CBRIF, 3, 3 )
        CALL MULT ( CBRIF, R, REF, 3, 3, 1 )
        CALL COOR ( REF(1), REF(2), REF(3), XLAT, XLONG, ALT )
C
        CALL AGRAV ( REF )
C
        CALL ATMOS ( ALT, RHO, PS, VSOUND, PRHOH, PPSH )
C
        CALL TMATY ( -XLONG, TMP1 )
        CALL TMATP ( XLAT, TMP2 )
        CALL MULT ( TMP2, TMP1, TMP3, 3, 3, 3 )
C
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```

CALL MULT ( CUENED, TMP3, CEFLL, 3, 3, 3 )
CALL MULT ( CEFLL, CBRIEF, TMP1, 3, 3, 3 )
CALL MULT ( TMP1, CBI, TMP2, 3, 3, 3 )
CALL TRANS ( TMP2, CLLB, 3, 3 )
CALL MULT ( CLLB, VW, VA, 3, 3, 1 )
CALL SUBT ( VB, VA, VR, 3, 1 )

C VM = SQRT( VR(1)*VR(1) + VR(2)*VR(2) + VR(3)*VR(3) )
C IF (VR(1))6,7,6
C   ALPHA = CRAD*ATAN2( VR(3), VR(1) )
C   IF (VR(1).EQ.0.0)ALPHA = 0.0
C   IF (VM)8,9,8
C     BETA = CRAD*ASIN ( VR(2)/VM )
C     IF (VM.EQ.0.0) BETA = 0.0
C
C XMACH = VM/V_SOUND
C VMS = VM*VM
C QDYN = 0.5*RHO*VMS
C
C CALL NPPLUME ( ALPHA, BETA, ALT, QDYN, PL )
C
C CALL NASSME
C
C CALL NASSME
C
C THRSTL(1) = TVACL(1) - PSMEPS*PS
C   THRSTL(2) = 0.0
C   THRSTL(3) = 0.0
C
C CALL MULT ( CCLB1, THRSTL, TSSME1, 3, 1 )
C
C THRSTL(1) = TVACL(2) - PSMEPS*PS
C
C CALL MULT ( CCLB2, THRSTL, TSSME2, 3, 1 )
C   CALL ADD ( TSSME1, TSSME2, TSSME, 3, 1 )
C
C THRSTL(1) = TVACL(3) - PSMEPS*PS
C
C CALL MULT ( CCLB3, THRSTL, TSSME3, 3, 1 )
C   CALL ADD ( TSSME, TSSME3, TSSME, 3, 1 )
C
C SRB
C
C IF ( I_STAGE.EQ.1 ) THEN
C
C   CALL NASSRB
C
C   THRSTS(1) = TVACS(1) - PSRBPS*PS
C   THRSTS(2) = 0.0
C   THRSTS(3) = 0.0
C
C   CALL MULT ( CCLBA, THRSTS, TSRBA, 3, 1 )
C
C   THRSTS(1) = TVACS(2) - PSRBPS*PS
C

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C CALL MULT ( CCLBB, THRSTS, TSRBB, 3, 3, 1 )
C CALL ADD ( TSRBA, TSRBB, TSRB, 3, 1 )
C ELSE
C   CALL ZEROM ( TSRB, 3, 1 )
C   CALL ZEROM ( TSRBA, 3, 1 )
C   CALL ZEROM ( TSRBB, 3, 1 )
C   OMASS(1) = 0.0
C   OMASS(2) = 0.0
C END IF
C
C CALL ADD ( TSSME, TSRB, THRUST, 3, 1 )
C
C OMASST = OMASL(1)+OMASL(2)+OMASL(3)+OMASS(1)+OMASS(2)
C
C CALL NMASS
C
C   AVSO2M = AREA*VMS/(2.0*XMASS)
C   AVSDO2 = AREA*VMS*DIA/2.0
C   RAV = RHO*AREA*VM
C   RAVD = RAV*DIA
C   RHOA = RHO*AREA
C   RAD = RHOA*DIA
C   QA = QDYN*AREA
C   QAOM = QA/XMASS
C   QAD = QA*DIA
C   OOMASS = 1.0/XMASS
C   OODIA = 1.0/DIA
C   RAOM = RHO*AREA/XMASS
C   RAVOM = RAOM*VM
C   QOM = QDYN/XMASS
C   IF(VM)11,12,11
C   DO2V = DIA/(2.0*VM)
C   IF ( VM EQ 0.0 ) DO2V = 0.0
C
C   CALL NAERO ( XMACH, ALPHA, BETA, DO2V )
C
C   CALL TRANS ( CBI, CIB, 3, 3 )
C   CALL MULT ( CIB, CEFBI, TMP1, 3, 3 )
C   CALL MULT ( TMP1, GRAV, OUT, 3, 3, 1 )
C
C   CALL CROSS ( OMEGA, VB, OCV )
C   CALL MULT ( CFQ, OMEGA, VEC, 3, 3, 1 )
C   CALL SMLT ( DO2V, VEC, VEC, 3, 1 )
C
C   VB-DOT EQUATION
C
C   DO 200 I = 1, 3
C     CF(I) = CFO(I)
C     1    + ALPHA*CFALP(I) + BETA*CFBET(I)
C     2    + VEC(I)
C   AERO(I) = QAOM*CF(I)
C   ACC(I) = AERO(I) + (FPLUME(I) + THRUST(I))/XMASS

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VBD(I) = ACC(I) + OUT(I)
1      - OCV(I)
CONTINUE

C   CALL ZEROM ( TMP3, 3, 3 )
C   TMP3(1,1) = A(4)**2
C   TMP3(2,2) = A(5)**2
C   TMP3(3,3) = A(6)**2

C   CALL MULT ( CLLB, TMP2, TMP2, 3, 3, 3 )
C   CALL TRANS ( CLLB, TMP3, 3, 3 )
C   CALL MULT ( TMP2, TMP3, TMP1, 3, 3, 3 )

C   CALL QMTRX ( OMEGA, QDMTRX )

C   Q-DOT EQUATION

C   CALL MULT ( QDMTRX, Q, QD, 4, 4, 1 )

C   CALL SUBT ( RA, RCG, DRA, 3, 1 )
C   CALL CROSS ( DRA, CF, DRACCF )
C   CALL SMLT ( OODIA, DRACCF, DRACCF, 3, 1 )
C   CALL MULT ( XIMTRX, OMEGA, VEC, 3, 3, 1 )
C   CALL CROSS ( OMEGA, VEC, OCIO )

C   CALL CROSS ( DRA, FPLUME, DRACFP )

SSME

C   CALL SUBT ( RT1, RCG, DRT, 3, 1 )
C   CALL CROSS ( DRT, TSSME1, TTSME1 )
C   CALL SUBT ( RT2, RCG, DRT, 3, 1 )
C   CALL CROSS ( DRT, TSSME2, TTSME2 )
C   CALL ADD ( TTSME1, TTSME2, TTSME, 3, 1 )

C   CALL SUBT ( RT3, RCG, DRT, 3, 1 )
C   CALL CROSS ( DRT, TSSME3, TTSME3 )
C   CALL ADD ( TTSME, TTSME3, TTSME, 3, 1 )

SRB

C   IF ( IStage.EQ.1 ) THEN
C   CALL SUBT ( RTA, RCG, DRT, 3, 1 )
C   CALL CROSS ( DRT, TSRBA, TTSRBA )
C   CALL SUBT ( RTB, RCG, DRT, 3, 1 )
C   CALL CROSS ( DRT, TSRBB, TTSRBB )
C   CALL ADD ( TSRBA, TTSRBB, TTSRBA, 3, 1 )

ELSE

C   CALL ZEROM ( TTSRBA, 3, 1 )
C

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```
C CALL ADD ( TTSME, TTSRB, TTHRST, 3, 1 )
C CALL MULT ( CMQ, OMEGA, VEC, 3, 3, 1 )
C CALL SMLT ( DO2V, VEC, VEC, 3, 1 )
C
C OMEGA-DOT EQUATION
C
C DO 400 I = 1, 3
C   CM(I) = CM0(I) + ALPHA*CMALP(I) + BETA*CMBET(I)
C   1 + VEC(I)
C   TPLUM(I) = TPPLUME(I) + DRACFP(I)
C   AVEC(I) = QAD*CM(I) + QA*DRACCF(I) + TPPLUM(I)
C   VEC(I) = AVEC(I) + TTHRST(I)
C   VEC(I) = VEC(I) - OCIO(I)
400  CONTINUE
C   CALL MULT ( XIMATI, VEC, OMEGAD, 3, 3, 1 )
C
C DO 500 I = 1, 3
C   XDOT(I) = RD(I) + RDI(I)
C   XDOT(I+3) = VBD(I)
C   S(I+3) = TMP1(I,I)
500  CONTINUE
C
C IF ( TIME - TRINT ) 610, 590, 590
C
C 590  CONTINUE
C
C DO 600 I = 1, 4
C   XDOT(I+6) = QD(I)
600  CONTINUE
C
C 610  CONTINUE
C
C   RETURN
C
997  FORMAT(10X, 3E15.8)
998  FORMAT(7X, 4E15.8 )
999  FORMAT(3X, 5E15.8 )
C
END
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C          SUBROUTINE PDMTRX
C
C          DIMENSION DUMB(71,71), VAR(2700), TMP(5400), NDER
C          COMMON / LINFMT / F(71,71), NS, NPAR
C          COMMON / CONST / A(71), S(71), R(12)
C          COMMON / PROPAG / X(71), P(71,71)
C          COMMON / DRVITV / XDOT(71), PD(71,71)
C
C          NTS = NS + NPAR
C
C          CALL LINFS
C          CALL LINFA
C          CALL LINFB
C
C          DO 20 I = 1, NTS
C          DO 20 J = 1, NTS
C          TEMP = 0.0
C          DO 10 K = 1, NTS
C          IF ( F(I,K) .EQ. 0.0 ) GO TO 10
C          TEMP = TEMP + F(I,K)*P(K,J)
C          CONTINUE
C          PD(I,J) = TEMP
C          DUMB(J,I) = TEMP
C          CONTINUE
C
C          DO 30 I = 1, NTS
C          DO 30 J = 1, NTS
C          PD(I,J) = PD(I,J) + DUMB(I,J)
C          CONTINUE
C
C          DO 40 I = 1, NTS
C          PD(I,I) = PD(I,I) + S(I)
C          CONTINUE
C
C          DO 50 I = 1, NTS
C          PD(I,I) = PD(I,I) + S(I)
C          CONTINUE
C
C          RETURN
C          FORMAT( 5X, SE15.8 )
C          END
C
C          SUBROUTINE LINFS
C
C          902      COMMON DER(2700), VAR(2700), TEMP(5400), NDER
C          COMMON / TIMDAT / TMAX, HSTEP, TSAMP, TSTART, TSTOP, TRINT
C          1        COMMON / STATES / R(3), VEC1(3), VEC2(3), VEC3(3), TMP1(3,3), TMP2(3,3), TMP3(3,3)
C          2        ,TMP2Q(3,4), TMP3Q(3,4)
C          3        ,DRA(3), DRT(3), PQO(4,3)
C          4        ,VEC4(3), VEC5(3), VEC6(3), VEC7(3)
C
C          COMMON DER(2700), VAR(2700), TEMP(5400), NDER
C          COMMON / STATES / R(3), VEC1(3), VEC2(3), VEC3(3), TMP1(3,3), TMP2(3,3), TMP3(3,3)
C          COMMON / VARIAB / VR(3), VW(3), VMGRAD(3)
C          COMMON / ENDOAT / RHO, PS, VSOUND, XMACH, PRHOH, PPSH
C          COMMON / LAYOUT / RS(3), RA(3), RT1(3), RT2(3), RT3(3), RTA(3), RTB(3)
C          COMMON / GEOMET / AREA, DIA, PSMEPS, PSRBPS

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COMMON / PROPER / XMASS, OMASS, XIMTRX(3,3), XIMATT(3,3), RCG(3)
COMMON / GIMBAL / CCLLB1(3,3), CCLLB2(3,3), CCLLB3(3,3), CCLBA(3,3)
1   , CCLBB(3,3), PLN, RATEC(3), THTC(3)
COMMON / AERO / CF0(3), CFALP(3), CFBET(3), CFQ(3,3), CM0(3), CMALP(3)
1   , CMBET(3), CMQ(3,3), CF(3), CM(3)
COMMON / PLUME / PBLUME(3), FPALP(3), FPBET(3), TPLUME(3), TPALP(3)
1   , TPBET(3), FPALT(3), TPALT(3), FPDPL(3), TPDPL(3)
COMMON / TMAT / CBI(3,3), CIB(3,3), CLLB(3,3), CEFBRI(3,3)
COMMON / ASTRON / CUENED(3,3), RNP(3,3), CIBRI(3,3), CIB0(3,3), TGNTT0
COMMON / COMBO / AVSO2M, AVSDO2, RAV, RAVD, RAVOM, QA, QAD, QAOM, OOMASS
1   , RAOM, QOM, QDYN, RHOA, RAD, OODIA

COMMON / PARTLA / PVWV(3), PAVB(3), PBVMH, PAH, PBH
1   , PVWV(3), PAWV(3), PBWV(3)
COMMON / PARTLB / PVWRQ(3,4), PVMO(4), PAQ(4), PBQ(4)
COMMON / APARTL / PAMBRI(3,3), PAMBVB(3,3), ACC(3), THRUST(3)
COMMON / VEHPOS / REF(3)
COMMON / LINFMNT / F(71,71), NS, NPAR
COMMON / EARTH / GRAV(3), AGMX(3,3)

C      TIME = VAR(1)

C      VMAG = SQRT ( VR(1)*VR(1) + VR(2)*VR(2) + VR(3)*VR(3) )
C      RHOVM = RHO*VMAG

C*****POSITION
C      RID WRT VB
C      CALL IMBED ( F, 71, 71, CBI, 3, 3, 1, 4 )
C      RID WRT Q
C      IF ( TIME - TRINT ) 220, 210, 210
C      210  CONTINUE
C      CALL AXCBIQ ( Q, VB, PCBIQ )
C      CALL IMBED ( F, 71, 71, PCBIQ, 3, 4, 1, 7 )
C      220  CONTINUE
C*****VELOCITY
C      VBDOT WRT RI
C      GRAVITY
C      CALL TRANS ( CBI, CIB, 3, 3 )
C      CALL MULT ( CIB, CEFBRI, TMP2, 3, 3, 3 )
C      CALL MULT ( TMP2, AGMX, TMP1, 3, 3, 3 )
C      CALL TRANS ( CEFBRI, TMP3, 3, 3 )
C      CALL MULT ( TMP1, TMP3, TMP2, 3, 3, 3 )
C      CALL SWITCH ( TMP2, TMP1, 3, 3 )
C      ALTITUDE
C

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C CALL AUXVAB
C
C CALL SMLT ( PRHOH, CF, VEC1, 3, 1 )
C CALL SMLT ( AVSO2M, VEC1, VEC1, 3, 1 )
C CALL SMLT ( PVMH, CF, VEC2, 3, 1 )
C CALL SMLT ( RAVOM, VEC2, VEC2, 3, 1 )
C CALL ADD ( VEC1, VEC2, VEC1, 3, 1 )
C CALL SMLT ( PAH, CFALP, VEC2, 3, 1 )
C CALL SMLT ( QAOM, VEC2, VEC2, 3, 1 )
C CALL ADD ( VEC1, VEC2, VEC1, 3, 1 )
C CALL SMLT ( PBH, CFBET, VEC2, 3, 1 )
C CALL SMLT ( QAOM, VEC2, VEC2, 3, 1 )
C CALL ADD ( VEC1, VEC2, VEC1, 3, 1 )
C CALL SMLT ( -1.0, VEC1, VEC1, 3, 1 )

C FOR ALL FIVE DEVICES

C DO 10 I = 1, 3
    VEC3(I) = CCLB1(I,1)*PSMEPS
CONTINUE
DO 20 I = 1, 3
    VEC2(I) = CCLB2(I,1)*PSMEPS
CONTINUE
CALL ADD ( VEC2, VEC3, VEC2, 3, 1 )
DO 30 I = 1, 3
    VEC3(I) = CCLB3(I,1)*PSMEPS
CONTINUE
CALL ADD ( VEC2, VEC3, VEC2, 3, 1 )
DO 40 I = 1, 3
    VEC3(I) = CCLBA(I,1)*PSRBPS
CONTINUE
CALL ADD ( VEC2, VEC3, VEC2, 3, 1 )
DO 50 I = 1, 3
    VEC3(I) = CCLBB(I,1)*PSRBPS
CONTINUE
CALL ADD ( VEC2, VEC3, VEC2, 3, 1 )
CALL SMLT ( PPSH, VEC2, VEC2, 3, 1 )
C
C CALL SMLT ( -1.0, FPALT, FPALT, 3, 1 )
CALL ADD ( VEC2, FPALT, VEC2, 3, 1 )
C CALL SMLT ( PAH, FPALP, VEC3, 3, 1 )
C CALL ADD ( VEC2, VEC3, VEC2, 3, 1 )
C CALL SMLT ( PBH, FPBET, VEC3, 3, 1 )
CALL ADD ( VEC2, VEC3, VEC2, 3, 1 )
C CALL SMLT ( -1.0, VEC2, VEC2, 3, 1 )
C CALL SMLT ( OOMASS, VEC2, VEC2, 3, 1 )
CALL ADD ( VEC1, VEC2, VEC1, 3, 1 )
C
C RMAGS = R(1)*R(1) + R(2)*R(2) + R(3)*R(3)
RMAG = SQRT(RMAGS)
C
RIUNIT(1) = -R(1)/RMAG

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C RIUNIT(2) = -R(2)/RMAG
C RIUNIT(3) = -R(3)/RMAG
C CALL OUTER ( VEC1, RIUNIT, TMP2, 3, 3 )
C CALL SWITCH ( TMP2, PAMBRI, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL IMBED ( F, 71, 71, TMP1, 3, 3, 4, 1 )
C C VBDOT WRT V#  

C CALL OUTER ( CF, PVMVB, TMP1, 3, 3 )
C CALL SMLT ( RAOM, TMP1, TMP1, 3, 3 )
C CALL SMLT ( VMAG, TMP1, TMP1, 3, 3 )
C CALL OUTER ( CFALP, PAVB, TMP2, 3, 3 )
C CALL SMLT ( QAOM, TMP2, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL OUTER ( CFBBET, PBVB, TMP2, 3, 3 )
C CALL SMLT ( QAOM, TMP2, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL OUTER ( FPALP, PAVB, TMP2, 3, 3 )
C CALL SMLT ( OOMASS, TMP2, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL OUTER ( FPBET, PBVB, TMP2, 3, 3 )
C CALL SMLT ( OOMASS, TMP2, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL SWATCH ( TMP1, PAMBVB, 3, 3 )
C CALL SKEW ( OMEGA, TMP2 )
C CALL SUBT ( TMP1, TMP2, TMP1, 3, 3 )
C CALL IMBED ( F, 71, 71, TMP1, 3, 3, 4, 4 )
C C VBDOT WRT Q
C IF ( TIME - TRINT ) 240, 230, 230
C 230 CONTINUE
C CALL MULT ( CEFBRI, GRAV, VEC1, 3, 3, 1 )
C CALL AXCIBQ ( Q, VEC1, PCIBQ )
C CALL MULT ( CLLB, VW, VEC1, 3, 3, 1 )
C CALL AXCBIQ ( Q, VEC1, PVRQ )
C CALL SMLT ( -1.0, PVRQ, PVRQ, 3, 4 )
C CALL OUTER ( CF, PVMVB, TMP1, 3, 3 )
C CALL SMLT ( RAOM, TMP1, TMP1, 3, 3 )
C CALL SMLT ( VMAG, TMP1, TMP1, 3, 3 )
C CALL OUTER ( CFALP, PAVB, TMP2, 3, 3 )
C CALL SMLT ( QAOM, TMP2, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL OUTER ( CFBBET, PBVB, TMP2, 3, 3 )
C CALL SMLT ( QAOM, TMP2, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )

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CALL MULT ( TMP1, PVRQ, TMP2Q, 3, 3, 4 )
C
CALL OUTER ( FPALP, PAVB, TMP2, 3, 3 )
CALL OUTER ( FPBET, PBVB, TMP3, 3, 3 )
CALL ADD ( TMP2, TMP3, TMP2, 3, 3 )
CALL MULT ( TMP2, PVRQ, TMP3Q, 3, 3, 4 )
CALL SMLT ( OOMASS, TMP3Q, TMP3Q, 3, 4 )

C      CALL ADD ( TMP2Q, TMP3Q, TMP2Q, 3, 4 )
C      CALL ADD ( TMP2Q, PCIBQ, TMP2Q, 3, 4 )
C      CALL IMBED ( F, 71, 71, TMP2Q, 3, 4, 7 )

C      240    CONTINUE
C
C      VBDOT WRT OMEGA
C
C      CALL SMLT ( QAQM, CFQ, TMP1, 3, 3 )
C      CALL SKEW ( VB, TMP2 )
C      CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C      CALL IMBED ( F, 71, 71, TMP1, 3, 3, 4, 11 )

C*****ATTITUDE
C
C      QD WRT Q
C
C      IF ( TIME - TRINT ) 260, 250, 250
C
C      250    CONTINUE
C
C      CALL QMTRX( OMEGA, QDMTRX )
C      CALL IMBED ( F, 71, 71, QDMTRX, 4, 4, 7, 7 )
C
C      260    CONTINUE
C
C      QD WRT OMEGA
C
C      CALL PQOMEQ ( Q, PQO )
C      CALL IMBED ( F, 71, 71, PQO, 4, 3, 7, 11 )

C*****ANGULAR RATE
C
C      CALL SUBT ( RA, RCG, DRA, 3, 1 )
C      CALL SMLT ( OODIA, DRA, DRA, 3, 1 )
C
C      OMEGAD WRT RI
C
C      CALL SMLT ( RAVD, CM, VEC1, 3, 1 )
C      CALL CROSS ( DRA, CF, VEC2 )
C      CALL SMLT ( RAV, VEC2, VEC2, 3, 1 )
C      CALL ADD ( VEC1, VEC2, VEC1, 3, 1 )
C      CALL SMLT ( AVSD02, CM, VEC4, 3, 1 )
C      CALL SMLT ( PRHOH, VEC4, VEC4, 3, 1 )
C      CALL ADD ( VEC1, VEC4, VEC4, 3, 1 )
C      CALL SMLT ( PVMH, VEC4, VEC4, 3, 1 )
C      CALL SMLT ( QAD, CMALP, VEC2, 3, 1 )

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C CALL CROSS ( DRA, CFALP, VEC3 )
C CALL SMLT ( QA, VEC3, VEC3, 3, 1 )
C CALL ADD ( VEC2, VEC3, VEC2, 3, 1 )
C CALL SMLT ( PAH, VEC2, VEC5, 3, 1 )
C CALL ADD ( VEC4, VEC5, VEC4, 3, 1 )
C CALL SMLT ( QAD, CMBET, VEC3, 3, 1 )
C CALL CROSS ( DRA, CFBET, VEC5 )
C CALL SMLT ( QA, VEC5, VEC5, 3, 1 )
C CALL ADD ( VEC3, VEC5, VEC3, 3, 1 )
C CALL SMLT ( PBH, VEC3, VEC5, 3, 1 )
C CALL ADD ( VEC4, VEC5, VEC4, 3, 1 )

C DO 110 I = 1, 3
C VEC5(I) = CCLB1(I,1)*PSMEPS
C CONTINUE

C CALL SUBT ( RT1, RCG, DRT, 3, 1 )
C CALL CROSS ( DRT, VEC5, VEC6 )
C DO 120 I = 1, 3
C VEC5(I) = CCLB2(I,1)*PSMEPS
C CONTINUE

C CALL SUBT ( RT2, RCG, DRT, 3, 1 )
C CALL CROSS ( DRT, VEC5, VEC7 )
C CALL ADD ( VEC6, VEC7, VEC6, 3, 1 )
C DO 130 I = 1, 3
C VEC5(I) = CCLB3(I,1)*PSMEPS
C CONTINUE

C CALL SUBT ( RT3, RCG, DRT, 3, 1 )
C CALL CROSS ( DRT, VEC5, VEC7 )
C CALL ADD ( VEC6, VEC7, VEC6, 3, 1 )
C DO 140 I = 1, 3
C VEC5(I) = CCLBA(I,1)*PSRBPS
C CONTINUE

C CALL SUBT ( RTA, RCG, DRT, 3, 1 )
C CALL CROSS ( DRT, VEC5, VEC7 )
C CALL ADD ( VEC6, VEC7, VEC6, 3, 1 )

C CALL SMLT ( PPSH, VEC6, VEC5, 3, 1 )
C CALL ADD ( VEC5, TPALT, VEC5, 3, 1 )
C CALL SMLT ( PAH, TPALP, VEC6, 3, 1 )
C CALL ADD ( VEC5, VEC6, VEC5, 3, 1 )
C CALL SMLT ( PBH, TPBET, VEC6, 3, 1 )
C CALL ADD ( VEC5, VEC6, VEC5, 3, 1 )
C CALL ADD ( VEC4, VEC5, VEC4, 3, 1 )
C CALL OUTER ( VEC4, RIUNIT, TMP2, 3, 3 )
C CALL MULT ( XIMATI, TMP2, TMP1, 3, 3 )
C CALL IMBED ( F, 71, 71, TMP1, 3, 3, 11, 1 )

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C OMEGAD WRT VB
C
C CALL OUTER ( VEC1, PVMVB, TMP1, 3, 3 )
C CALL OUTER ( VEC2, PAVB, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL OUTER ( VEC3, PBVB, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL OUTER ( TPALP, PAVB, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL OUTER ( TPBET, PBVB, TMP2, 3, 3 )
C CALL ADD ( TMP1, TMP2, TMP2, 3, 3 )
C CALL MULT ( XIMAT1, TMP2, TMP1, 3, 3, 3 )
C CALL IMBED ( F, 71, 71, TMP1, 3, 3, 11, 4 )

C OMEGAD WRT Q
C CALL AXVABQ

C CALL OUTER ( VEC1, PVMQ, TMP2Q, 3, 4 )
C CALL OUTER ( VEC2, PAQ, TMP3Q, 3, 4 )
C CALL ADD ( TMP2Q, TMP3Q, TMP2Q, 3, 4 )
C CALL OUTER ( VEC3, PBQ, TMP3Q, TMP2Q, 3, 4 )
C CALL ADD ( TMP2Q, TMP3Q, TMP3Q, 3, 4 )
C CALL OUTER ( TPALP, TMP3Q, PAQ, TMP3Q, 3, 4 )
C CALL ADD ( TMP2Q, TMP3Q, TMP3Q, TMP2Q, 3, 4 )
C CALL OUTER ( TPBET, PBQ, TMP3Q, TMP3Q, 3, 4 )
C CALL ADD ( TMP2Q, TMP3Q, TMP2Q, 3, 4 )
C CALL MULT ( XIMAT1, TMP2Q, TMP3Q, 3, 3, 4 )
C CALL IMBED ( F, 71, 71, TMP3Q, 3, 4, 11, 7 )

C OMEGAD WRT OMEGA
C CALL SMLT ( QAD, CMQ, TMP1, 3, 3 )
C CALL SKEW ( DRA, TMP2 )
C CALL MULT ( TMP2, CFQ, TMP3, 3, 3, 3 )
C CALL SMLT ( QA, TMP3, TMP3, 3, 3 )
C CALL ADD ( TMP1, TMP3, TMP1, 3, 3 )
C CALL MULT ( XIMTRX, OMEGA, VEC1, 3, 3, 1 )
C CALL SKEW ( VEC1, TMP2 )
C CALL ADD ( TMP1, TMP2, TMP1, 3, 3 )
C CALL SKEW ( OMEGA, TMP2 )
C CALL MULT ( TMP2, XIMTRX, TMP3, 3, 3, 3 )
C CALL SUBT ( TMP1, TMP3, TMP2, 3, 3 )
C CALL MULT ( XIMAT1, TMP2, TMP1, 3, 3, 3 )
C CALL IMBED ( F, 71, 71, TMP1, 3, 3, 11, 11 )

C RETURN
C
C 901  FORMAT( 11E7.1 )
C 902  FORMAT( 5X, 3E15.8 )
C
C END
C SUBROUTINE LINFA
C
C DIMENSION UNIT( 3, 3 )

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1   'VEC(3), VEC2(3), TMP(3,3)
2   ,DRT(3)
3   ,TMP2(3,3), TMP3(3,3)

C   COMMON / MEPRTL / PFTMR(3), PFTPC(3), PFTGO(3), PFTGH(3)
C   COMMON / RBRPTL / PFT(2), PFA(2), PFCS(2)
C   COMMON / AERO / CFO(3), CFALP(3), CFBET(3), CFQ(3,3), CM0(3), CMALP(3)
1   COMMON / COMBO / CMET(3), CMQ(3,3), CF(3), CM(3)
C   COMMON / COMBO / AVSO2M, AVSDO2, RAV, RAVD, RAVOM, QA, QAD, QAOM, OOMASS
1   COMMON / PLUME / RAOM, QOM, QDYN, RHOA, RAD, OODIA
C   COMMON / PLUME / TPLUME(3), FPALP(3), TPALP(3), TPALM(3)
1   COMMON / PARTLA / FPBET(3), FPALT(3), FPBET(3), FPDPL(3), TPDPL(3)
1   COMMON / LAYOUT / RS(3), RA(3), RT1(3), RT2(3), RT3(3), RTA(3), RTB(3)
C   COMMON / GIMBAL / CCLBB(3,3), CCLB2(3,3), CCLB3(3,3), CCLBA(3,3)
1   COMMON / PROPER / CCLBB(3,3), PLN, RATEC(3), THTC(3)
C   COMMON / APARTL / XMASS, XIMATR(3,3), XIMATI(3,3), RCG(3)
C   COMMON / PARARO / PAMBRI(3,3), PAMBVB(3,3), ACC(3), THRUST(3)
C   COMMON / PARPLM / PVBDCCF(3,3), PWDCF(3,3), PWDCM(3,3)
C   COMMON / PARRCG / PWDRCG(3,3), PWDFP(3,3), PWDTP(3,3)
C   COMMON / PARVWX / PVBDVW(3,3), PWDVW(3,3)
C   COMMON / LINFMT / F(71,71), NS, NPAR
C   COMMON / IPARAM / ISSME, ISRB, IAERO, IPUME, IWIND, JACB, JRDR

C   DATA UNIT / 1.0,3*0.0,1.0,3*0.0,1.0 /
RHOOM = RHO*OOMASS

C   C VBDOT WRT SSME1 PARAMETERS
C   DO 10 I = 1, 3
      VEC(I) = CCLB1(I,1)/XMASS
      VEC2(I) = CCLB1(I,1)

C   F( (3+I), 14 ) = THRUST(I)/(3.2*1.74*XMASS**2)
      F( (3+I), 15 ) = VEC(I)*PFTMR(1)
      F( (3+I), 16 ) = VEC(I)*PFTPC(1)
      F( (3+I), 17 ) = VEC(I)*PFTGO(1)
      F( (3+I), 18 ) = VEC(I)*PFTGH(1)

C   CONTINUE
10

C   C OMEGAD WRT SSME1 PARAMETERS
C   CALL SUBT( RT1, RCG, DRT, 3, 1 )
C   CALL MULT( XIMATI, DRT, VEC, 3, 3, 1 )
C   CALL CROSS( VEC, VEC2, DRT )

C   DO 20 I = 1, 3
      F( (10+I), 15 ) = DRT(I)*PFTMR(1)
      F( (10+I), 16 ) = DRT(I)*PFTPC(1)
      F( (10+I), 17 ) = DRT(I)*PFTGO(1)
      F( (10+I), 18 ) = DRT(I)*PFTGH(1)

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C      20      CONTINUE
C      C      VBDOT WRT SSME2 PARAMETERS
C
C      DO 30  I = 1, 3
C      VEC(I) = CCLB2(I,1)/XMASS
C      VEC2(I) = CCLB2(I,1)

C      F( ( 3+I), 23 ) = THRUST(I)/(32.174*XMASS**2)
C      F( ( 3+I), 24 ) = VEC(I)*PFTMR(2)
C      F( ( 3+I), 25 ) = VEC(I)*PFTPC(2)
C      F( ( 3+I), 26 ) = VEC(I)*PFTGO(2)
C      F( ( 3+I), 27 ) = VEC(I)*PFTGH(2)

C      30      CONTINUE

C      C      OMEGAD WRT SSME2 PARAMETERS

C      CALL SUBT ( RT2, RCG, DRT, 3, 1 )
C      CALL MULT ( XIMATI, DRT, VEC, 3, 3, 1 )
C      CALL CROSS ( VEC, VEC2, DRT )

C      DO 40  I = 1, 3

C      F( ( 10+I), 24 ) = DRT(I)*PFTMR(2)
C      F( ( 10+I), 25 ) = DRT(I)*PFTPC(2)
C      F( ( 10+I), 26 ) = DRT(I)*PFTGO(2)
C      F( ( 10+I), 27 ) = DRT(I)*PFTGH(2)

C      40      CONTINUE

C      C      VBDOT WRT SSME3 PARAMETERS
C
C      DO 50  I = 1, 3
C      VEC(I) = CCLB3(I,1)/XMASS
C      VEC2(I) = CCLB3(I,1)

C      F( ( 3+I), 32 ) = THRUST(I)/(32.174*XMASS**2)
C      F( ( 3+I), 33 ) = VEC(I)*PFTMR(3)
C      F( ( 3+I), 34 ) = VEC(I)*PFTPC(3)
C      F( ( 3+I), 35 ) = VEC(I)*PFTGO(3)
C      F( ( 3+I), 36 ) = VEC(I)*PFTGH(3)

C      50      CONTINUE

C      C      OMEGAD WRT SSME3 PARAMETERS

C      CALL SUBT ( RT3, RCG, DRT, 3, 1 )
C      CALL MULT ( XIMATI, DRT, VEC, 3, 3, 1 )
C      CALL CROSS ( VEC, VEC2, DRT )

C      DO 60  I = 1, 3
C      F( ( 10+I), 33 ) = DRT(I)*PFTMR(3)

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C   F( ( 10+I) , 34 ) = DRT(I)*PFTPC(3)
C   F( ( 10+I) , 35 ) = DRT(I)*PFTQG(3)
C   F( ( 10+I) , 36 ) = DRT(I)*PFTGH(3)
C
C   CONTINUE
C
C   KSTATE = 61
C   IF (ISRB) 200, 200, 70
C   CONTINUE
C
C   VBDOT WRT SRBA PARAMETERS
C
C   DO 80 I = 1, 3
C     VEC(I) = CCLBA(I,1)/XMASS
C     VEC2(I) = CCLBA(I,1)
C
C     F( ( 3+I) , KSTATE+1 ) = THRUST(I)/(32.174*XMASS**2)
C     F( ( 3+I) , KSTATE+2 ) = VEC(I)*PFT(1)
C     F( ( 3+I) , KSTATE+3 ) = VEC(I)*PFA(1)
C     F( ( 3+I) , KSTATE+4 ) = VEC(I)*PFCS(1)
C
C   CONTINUE
C
C   OMEGAD WRT SRBA PARAMETERS
C
C   CALL SUBT ( RTA, RCG, DRT, 3, 1 )
C   CALL MULT ( XIMATI, DRT, VEC, 3, 3, 1 )
C   CALL CROSS ( VEC, VEC2, DRT )
C
C   DO 90 I = 1, 3
C
C     F( ( 10+I) , KSTATE+2 ) = DRT(I)*PFT(1)
C     F( ( 10+I) , KSTATE+3 ) = DRT(I)*PFA(1)
C     F( ( 10+I) , KSTATE+4 ) = DRT(I)*PFCS(1)
C
C   CONTINUE
C
C   VBDOT WRT SRBB PARAMETERS
C
C   DO 100 I = 1, 3
C     VEC(I) = CCLBB(I,1)/XMASS
C     VEC2(I) = CCLBB(I,1)
C
C     F( ( 3+I) , KSTATE+6 ) = THRUST(I)/(32.174*XMASS**2)
C     F( ( 3+I) , KSTATE+7 ) = VEC(I)*PFT(2)
C     F( ( 3+I) , KSTATE+8 ) = VEC(I)*PFA(2)
C     F( ( 3+I) , KSTATE+9 ) = VEC(I)*PFCS(2)
C
C   CONTINUE
C
C   OMEGAD WRT SRBB PARAMETERS
C
C   CALL SUBT ( RTB, RCG, DRT, 3, 1 )
C   CALL MULT ( XIMATI, DRT, VEC, 3, 3, 1 )
C   CALL CROSS ( VEC, VEC2, DRT )

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C DO 110 I = 1, 3
C
C F( (10+I), KSTATE+7 ) = DRT(I)*PFT(2)
C F( (10+I), KSTATE+8 ) = DRT(I)*PFA(2)
C F( (10+I), KSTATE+9 ) = DRT(I)*PFCS(2)
C
C 110 CONTINUE
C
C 200 CONTINUE
C
C KSTATE = 40
C
C IF( IAERO ) 300, 300, 210
C CONTINUE
C
C CALL SMLT ( QAOM, UNIT, PVBDCF, 3, 3 )
C CALL IMBED ( F, 71, 71, PVBDCF, 3, 3, 4, (KSTATE+1) )
C
C CALL SUBT ( RA, RCG, VEC, 3, 1 )
C CALL SMLT ( OODIA, VEC, VEC, 3, 1 )
C CALL SKEW ( VEC, TMP )
C CALL SMLT ( QA, TMP, TMP, 3, 3 )
C CALL MULT ( XIMATI, TMP, PWDCF, 3, 3, 3 )
C CALL IMBED ( F, 71, 71, PWDCF, 3, 3, 11, (KSTATE+1) )
C
C CALL SMLT ( QAD, XIMATI, PWDCM, 3, 3 )
C CALL IMBED ( F, 71, 71, PWDCM, 3, 3, 11, (KSTATE+4) )
C
C KSTATE = KSTATE + 3
C
C 300 CONTINUE
C
C IF( IPLUME ) 400, 400, 310
C CONTINUE
C
C CALL SMLT ( OOMASS, UNIT, PVBDFF, 3, 3 )
C CALL IMBED ( F, 71, 71, PVBDFF, 3, 3, 4, (KSTATE+1) )
C
C CALL SUBT ( RA, RCG, VEC, 3, 1 )
C CALL SKEW ( VEC, TMP )
C CALL MULT ( XIMATI, TMP, PWDFP, 3, 3, 3 )
C CALL IMBED ( F, 71, 71, PWDFP, 3, 3, 11, (KSTATE+1) )
C
C CALL SWITCH ( XIMATI, PWDTDP, 3, 3 )
C CALL IMBED ( F, 71, 71, PWDTDP, 3, 3, 11, (KSTATE+4) )
C
C KSTATE = KSTATE + 3
C
C 400 CONTINUE
C
C IF( IWIND ) 600, 600, 510
C CONTINUE
C
C CALL OUTER ( CF, PVMMW, TMP, 3, 3 )

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CALL SMLT ( RAOM, TMP, PVBDVW, 3, 3 )
CALL SMLT ( 0.5, PVBDVW, PVBDVW, 3, 3 )
CALL OUTER ( CFALP, PAVW, TMP, 3, 3 )
CALL SMLT ( QAOM, TMP, TMP, 3, 3 )
CALL ADD ( PVBDVW, TMP, PVBDVW, 3, 3 )
CALL OUTER ( CFBET, PBVW, TMP, 3, 3 )
CALL SMLT ( QAOM, TMP, TMP, 3, 3 )
CALL ADD ( PVBDVW, TMP, PVBDVW, 3, 3 )
CALL OUTER ( FPALP, PAVW, TMP, 3, 3 )
CALL SMLT ( OOMASS, TMP, TMP, 3, 3 )
CALL ADD ( PVBDVW, TMP, PVBDVW, 3, 3 )
CALL OUTER ( FPBET, PBVW, TMP, 3, 3 )
CALL SMLT ( OOMASS, TMP, TMP, 3, 3 )
CALL ADD ( PVBDVW, TMP, PVBDVW, 3, 3 )
CALL IMBED ( F, 71, 71, PVBDVW, 3, 3, 4, (KSTATE+1) )

C CALL OUTER ( CM, PVMVW, TMP, 3, 3 )
C CALL SMLT ( RAD, TMP, PWDVW, 3, 3 )
C CALL SMLT ( 0.5, PWDVW, PWDVW, 3, 3 )
C CALL OUTER ( CMALP, PAVW, TMP, 3, 3 )
C CALL SMLT ( QAD, TMP, TMP, 3, 3 )
C CALL ADD ( PWDVW, TMP, PWDVW, 3, 3 )
C CALL OUTER ( CMBET, PBVW, TMP, 3, 3 )
C CALL SMLT ( QAD, TMP, TMP, 3, 3 )
C CALL ADD ( PWDVW, TMP, PWDVW, 3, 3 )
C CALL SUBT ( RA, RCG, VEC, 3, 1 )
C CALL SMLT ( OODIA, VEC, VEC, 3, 1 )
C CALL CROSS ( VEC, CP, VEC2 )
C CALL OUTER ( PVMVW, VEC2, TMP, 3, 3 )
C CALL SMLT ( PWDVW, TMP, TMP, 3, 3 )
C CALL ADD ( PWDVW, TMP, PWDVW, 3, 3 )
C CALL SMLT ( 0.5, PWDVW, PWDVW, 3, 3 )
C CALL OUTER ( CFALP, PAVW, TMP, 3, 3 )
C CALL SKEW ( VEC, TMP2 )
C CALL MULT ( TMP2, TMP, TMP3, 3, 3, 3 )
C CALL SMLT ( QA, TMP3, TMP3, 3, 3 )
C CALL ADD ( PWDVW, TMP3, PWDVW, 3, 3 )
C CALL OUTER ( CFBET, PBVW, TMP, 3, 3 )
C CALL MULT ( TMP2, TMP, TMP3, 3, 3, 3 )
C CALL SMLT ( QA, TMP3, TMP3, 3, 3 )
C CALL ADD ( PWDVW, TMP, PWDVW, 3, 3 )
C CALL CROSS ( FPALP, PAVW, TMP, 3, 3 )
C CALL CROSS ( FPBET, PBVW, TMP3, 3, 3 )
C CALL ADD ( TMP, TMP3, TMP, 3, 3 )
C CALL MULT ( TMP2, TMP, TMP3, 3, 3, 3 )
C CALL ADD ( PWDVW, TMP3, TMP, 3, 3 )
C CALL MULT ( XIMATI, TMP, PWDVW, 3, 3, 3 )
C CALL IMBED ( F, 71, 71, PWDVW, 3, 3, 11, (KSTATE+1) )

KSTATE = KSTATE + 3

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C 600 CONTINUE
C RETURN
C 902 FORMAT(5X, 9E8.1)
C 903 FORMAT(7X, 3E12.5)
END

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```

C      SUBROUTINE ATMOS( ALT, RHO, PS, SOUND, PRHOH, PPH )
C
COMMON DER(2700), VAR(2700), TEMP(5400), NDER
COMMON / CONST / A(71), S(71), RR(12)
COMMON / ATMOSP / THALT(15), THRO(15), THP(15), THSUND(15)
COMMON / SWIND / TALT(400), TVWX(400), TVWY(400), NALT
COMMON / SATMOS / TSRHO(400), TSP(400), TSSUND(400), IATMOS
COMMON / PREUP / XKM(71), PKM(71,71)
COMMON / PROPAG / X(71), P(71,71)
COMMON / DRVITV / XDOT(71), PD(71,71)
COMMON / LINFMT / F(71,71), NS, NPAR
COMMON / IPARAM / ISSME, ISRBM, IAERO, IPUME, IWIND, JACB, JRDR
COMMON / VARIAB / VR(3), VW(3), VWGRAD(3)

C      DATA TAUN / 2.E+1 /
DATA RH00,T0,XLAPSE,P0,ZTROP/.0023769,518.7,.00357,2116.2,36089./
DATA G,R/32.174,1715.0/
C      IF ( IATMOS ) 1, 1, 100
C
1     CONTINUE
C      C 1962 STANDARD ATMOSPHERE FOR ALTITUDES UP TO 100000 FT
C
C      IF( ALT ) 2, 4, 4
2     CONTINUE
T = T0
RHO = RH00
PS = P0
PRHOH = 0.0
PPH = 0.0
GO TO 30
C      CONTINUE
4     IF ( ALT - 60000.0 ) 5, 40, 40
5     CONTINUE
C
C      POWER=(G/(XLAPSE*R))-1.0
IF ALT-ZTROP)20,10,10
10    CONTINUE
T=T0-XLAPSE*ZTROP
ZTROP=EXP(-G*(ALT-ZTROP)/(R*T))
TMP=(T/T0)**POWER*TROP
RHO = RH00*TMP
RHOT = RHO/TROP
RRHOT = RHOT/RHO0
ETMPT = T/T0
PZTROP = P0*RRHOT*RTMPT
RRHO = RHO/RHOT
ETMP = 1.0
PS = PZTROP*RRHO*RTMPT
PRHOH = -RHO0*TMP*G/(R*T)
PPH = -P0*TMP*G/(R*T)
GO TO 30
C      CONTINUE
C      20

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```

T=T0-XLAPSE*ALT
RHO=RHO*(T/T0)**POWER
RRHO = RHO/RHO
RTMP = T/T0
PS = P0*RRHO*RTMP
PRHOH = -RHO*POWER*XLAPSE*(T/T0)**(POWER-1.)
PPH = -P0*(POWER+1.)*XLAPSE*(T/T0)**POWER

C CONTINUE
C SOUND=49.02*SQRT(T)
C GO TO 50
C CONTINUE
C CALL INTRP1 ( ALT, THALT, THRHO, 15, RHO, PRHOH )
CALL INTRP1 ( ALT, THALT, THP, 15, PS, PPH )
CALL INTRP1 ( ALT, THALT, THSUND, 15, SOUND, PSH )
C CONTINUE
C GO TO 200
C CONTINUE
C VWZ = 0.0
VWGZ = 0.0

C IF ( ALT.LT.390000. ) THEN
CALL INTRP1 ( ALT, TALT, TSRHO, NALT, RHO, PRHOH )
CALL INTRP1 ( ALT, TALT, TSP, NALT, PS, PPH )
CALL INTRP1 ( ALT, TALT, TSSUND, NALT, SOUND, PSH )
CALL INTRP1 ( ALT, TALT, TVWX, NALT, VWX, VWGX )
CALL INTRP1 ( ALT, TALT, TVWY, NALT, VWy, VWGY )
ELSE
IF ( ALT.LT.100. ) THEN
RHO = .002377
PS = 2116.
SOUND = 1117.
VWX = 0.0
VWy = 0.0
END IF
END IF

C VW(1) = VWX
VW(2) = VWy
VW(3) = VWZ
VWGRAD(1) = VWGX
VWGRAD(2) = VWGY
VWGRAD(3) = VWGZ

C IF( IWIND.GT.0 ) THEN
C OOTAU = 1./TAUW
C

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```
F(47,47) = -OOTAU
F(48,48) = -OOTAU
F(49,49) = -OOTAU

C      S(47) = 2.*A(47)**2/TAUW
      S(48) = 2.*A(48)**2/TAUW
      S(49) = 2.*A(49)**2/TAUW

C      XDOT(47) = -OOTAU*X(47)
      XDOT(48) = -OOTAU*X(48)
      XDOT(49) = -OOTAU*X(49)

C      VW(1) = VW(1) + X(47)
      VW(2) = VW(2) + X(48)
      VW(3) = VW(3) + X(49)

C      ELSE
END IF

C      200  CONTINUE
C      RETURN
      FORMAT(10X, 3E15.8)
END
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C      SUBROUTINE XNOM(5), YRPL(3), VEC1(71), VEC2(71)
C
COMMON DER(2700), VAR(2700), TEMP(5400), NDER
COMMON / CONST / A(71), S(71), R(12)
COMMON / PROPAG / X(71), P(71, 71)
COMMON / DRVITV / XDOT(71), PD(71, 71)
COMMON / SMETBL / PR(4, 3, 5), YN(4, 3), XN(4, 2),
1          PRZ(4, 3, 3), PRX(4, 2, 2), ZN(4, 3)
2          RPLTAG(3), WDO2TU(3), WDH2TU(3), TVACTU(3)
COMMON / SMEDAT / TVACL(3), XISPL(3), WDO2H(3), WDH2H(3), WD(3)
1          CVTVAC(3), CVISPL(3), CVWDO(3), CVWDH(2, 3)
2          CVWD(3), CVWDG0(3), CVWDGH(3), PCTAG(3), OMASE(3)
COMMON / MPRRTL / PFTMR(3), PFTP(3), PFTGO(3), PFTGH(3)
COMMON / GIMBAL / CCLB1(3, 3), CCLB2(3, 3), CCLB3(3, 3), CCLBA(3, 3)
1          CCLBB(3, 3), PLN, RATEC(3), THTC(3)
COMMON / LINFMT / F(71, 71), NS, NPAR
COMMON / SMEMEA / XLH(6, 3)
COMMON / LINHMT / H(35, 71), NMESAS

C      DATA XNOM, YRPL / 6., 1., 1.0114, 1.55, .7, 895.74, 149.168, 471437./

C      DATA TMR, TPC, TWDG02, TWDGH2 / 4*10.0 /
DATA TY8, TPH, TTH, TP0B / 4*100. /

C      ISSME = 9
MSSME = 6

C      FOR EACH SSME

C      DO 1000 I = 1, 3

C      CALL ZEROM ( VEC1, 71, 1 )
CALL ZEROM ( VEC2, 71, 1 )

C      PCTAG(I) = RPLTAG(I)*PLN

C      PCHAT = PCTAG(I) + X( 16+ISSME*(I-1) ) + X( 22+ISSME*(I-1) )
PL = PCHAT/RPLTAG(I)
XLH( 1, I ) = PCHAT

C      WDO2U = POW( YN(1, 1), 1.0, 4 )
WDO2P = POW( YN(1, 1), PLN, 4 )
WDO2 = WDO2TU(I) + ( WDO2P - WDO2U )
WDH2U = POW( YN(1, 2), 1.0, 4 )
WDH2P = POW( YN(1, 2), PLN, 4 )
WDH2 = WDH2TU(I) + ( WDH2P - WDH2U )
TVACU = POW( YN(1, 3), 1.0, 4 )
TVACP = POW( YN(1, 3), PLN, 4 )
TVAC = TVACTU(I) + ( TVACP - TVACU )
WDGO = POW( XN( 1, 1 ), PLN, 4 )
WDGH = POW( XN( 1, 2 ), PLN, 4 )

C      Y8 = POW( ZN( 1, 1 ), PLN, 4 )

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C   PH = POW( ZN( 1, 2), PLN, 4 )
    TH = POW( ZN( 1, 3), PLN, 4 )
    PGHPLN = XN( 2, 2)
    PGOPLN = XN( 2, 1) + XN( 3, 1)*PLN*2.

C   PWOMR = POW( PR(1, 1, 1), PLN, 4 )
    PWOMR = PWOMR*WD02/XNOM(1)
    PWFMR = POW( PR(1, 2, 1), PLN, 4 )
    PWFMR = PWFMR*WDH2/XNOM(1)
    PFTMRI = POW( PR(1, 3, 1), PLN, 4 )
    PFTMRI(I) = PFTMRI*TVACL(I)/XNOM(1)
    PWOPLN = POW( PR(1, 1, 2), PLN, 4 )
    PWOPLN = POW( PR(1, 2, 2), PLN, 4 )
    PFTPLN = POW( PR(1, 3, 2), PLN, 4 )
    PFTPC(I) = PFTPL/PCTAG(I)

    PWOGO = POW( PR(1, 1, 4), PLN, 4 )
    PWFGO = POW( PR(1, 2, 4), PLN, 4 )
    PFTGO(I) = POW( PR(1, 3, 4), PLN, 4 )
    PWOGH = POW( PR(1, 1, 5), PLN, 4 )
    PWFGH = POW( PR(1, 2, 5), PLN, 4 )
    PFTGH(I) = POW( PR(1, 3, 5), PLN, 4 )
    PGHMR = POW( PRX( 1, 2, 1), PLN, 4 )
    PGOMR = POW( PRX( 1, 1, 1), PLN, 4 )
    PWGHGO = POW( PRX( 1, 2, 2), PLN, 4 )
    PWGOGH = POW( PRX( 1, 1, 2), PLN, 4 )

C   PWOY8 = POW( PRZ( 1, 1, 1), PLN, 4 )
    PWFY8 = POW( PRZ( 1, 2, 1), PLN, 4 )
    PFTY8 = POW( PRZ( 1, 3, 1), PLN, 4 )
    PWOPH = POW( PRZ( 1, 1, 2), PLN, 4 )
    PWFPH = POW( PRZ( 1, 2, 2), PLN, 4 )
    PFTPH = POW( PRZ( 1, 3, 2), PLN, 4 )
    PWOTH = POW( PRZ( 1, 1, 3), PLN, 4 )
    PWFTH = POW( PRZ( 1, 2, 3), PLN, 4 )
    PFTTH = POW( PRZ( 1, 3, 3), PLN, 4 )

C   PFTWF = PFTMRI/PWFMR
    PWOPC = PWOPL/PCTAG(I)
    PWOPC = PWOPL/PCTAG(I)
    PWOWF = XNOM(1)

C   PWDMR = PWOMR + PWFMR - PGOMR - PGHMR
    PWDPC = ( PWOPL + PWFPL - PGOPL - PGHPL )/PCTAG(I)
    PWGDO = PWOGO + PWFGO - 1.0 + PWGHGO
    PWDGH = PWOGH + PWFGH - 1.0 + PWGOGH
    PWDWF = PWOMR/PWFMR + 1.0

C   OMASE(I) = X( 14+ISSME*(I-1) )

C   F( ( 14+ISSME*(I-1) ), ( 15+ISSME*(I-1) ) ) = PWDMR
    F( ( 14+ISSME*(I-1) ), ( 16+ISSME*(I-1) ) ) = PWDPC
    F( ( 14+ISSME*(I-1) ), ( 17+ISSME*(I-1) ) ) = PWGDO
    F( ( 14+ISSME*(I-1) ), ( 18+ISSME*(I-1) ) ) = PWDGH
  
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F( (15+ISSME*(I-1)), (15+ISSME*(I-1)) ) = -1./TMR
F( (16+ISSME*(I-1)), (16+ISSME*(I-1)) ) = -1./TPC
F( (17+ISSME*(I-1)), (17+ISSME*(I-1)) ) = -1./TWDGO2
F( (18+ISSME*(I-1)), (18+ISSME*(I-1)) ) = -1./TWDGH2
F( (19+ISSME*(I-1)), (19+ISSME*(I-1)) ) = -1./TY8
F( (20+ISSME*(I-1)), (20+ISSME*(I-1)) ) = -1./TPH
F( (21+ISSME*(I-1)), (21+ISSME*(I-1)) ) = -1./TTH
F( (22+ISSME*(I-1)), (22+ISSME*(I-1)) ) = -1./TPOB

C   S( 15+ISSME*(I-1) ) = 2.* (A( 15+ISSME*(I-1) ) )**2/TMR
S( 16+ISSME*(I-1) ) = 2.* (A( 16+ISSME*(I-1) ) )**2/TPC
S( 17+ISSME*(I-1) ) = 2.* (A( 17+ISSME*(I-1) ) )**2/TWDGO2
S( 18+ISSME*(I-1) ) = 2.* (A( 18+ISSME*(I-1) ) )**2/TWDGH2
S( 19+ISSME*(I-1) ) = 2.* (A( 19+ISSME*(I-1) ) )**2/TY8
S( 20+ISSME*(I-1) ) = 2.* (A( 20+ISSME*(I-1) ) )**2/TPH
S( 21+ISSME*(I-1) ) = 2.* (A( 21+ISSME*(I-1) ) )**2/TTH
S( 22+ISSME*(I-1) ) = 2.* (A( 22+ISSME*(I-1) ) )**2/TPOB

C   H( (7+MSSME*(I-1)), (22+ISSME*(I-1)) ) = 1.0
H( (7+MSSME*(I-1)), (16+ISSME*(I-1)) ) = 1.0
H( (8+MSSME*(I-1)), (17+ISSME*(I-1)) ) = 1.0
H( (9+MSSME*(I-1)), (18+ISSME*(I-1)) ) = 1.0
H( (10+MSSME*(I-1)), (19+ISSME*(I-1)) ) = 1.0
H( (11+MSSME*(I-1)), (20+ISSME*(I-1)) ) = 1.0
H( (12+MSSME*(I-1)), (21+ISSME*(I-1)) ) = 1.0

C   XLH( 2, I ) = WDGO + X( 17+ISSME*(I-1) )
XLH( 3, I ) = WDGH + X( 18+ISSME*(I-1) )
XLH( 4, I ) = Y8 + X( 19+ISSME*(I-1) )
XLH( 5, I ) = PH + X( 20+ISSME*(I-1) )
XLH( 6, I ) = TH + X( 21+ISSME*(I-1) )

C   WDH2H(I) = WDH2 + PWFMR*X( 15+ISSME*(I-1) )
1    + PWFFP*X( 16+ISSME*(I-1) )
2    + PWFGO*X( 17+ISSME*(I-1) )
3    + PWFGH*X( 18+ISSME*(I-1) )

C   WDO2H(I) = WDO2 + PWOMR*X( 15+ISSME*(I-1) )
1    + PWOPC*X( 16+ISSME*(I-1) )
2    + PWOGO*X( 17+ISSME*(I-1) )
3    + PWOGH*X( 18+ISSME*(I-1) )

C   WD(I) = WDH2H(I) + WDO2H(I) - (XLH( 2, I ) + XLH( 3, I ))

C   TVACL(I) = TVAC + PFTMR(I)*X( 15+ISSME*(I-1) )
1    + PFTP(I)*X( 16+ISSME*(I-1) )
2    + PFTGO(I)*X( 17+ISSME*(I-1) )
3    + PFTGH(I)*X( 18+ISSME*(I-1) )

C   XISPL(I) = TVACL(I)/WD(I)

C   XDOT( 14+ISSME*(I-1) ) = WD(I)
XDOT( 15+ISSME*(I-1) ) = -(1./TMR)*X( 15+ISSME*(I-1) )
XDOT( 16+ISSME*(I-1) ) = -(1./TPC)*X( 16+ISSME*(I-1) )
XDOT( 17+ISSME*(I-1) ) = -(1./TWDGO2)*X( 17+ISSME*(I-1) )

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C VACUUM THRUST COVARIANCE
C
C     XDOT( 18+ISSME*(I-1) ) = -(1./TWDGH2)*X( 18+ISSME*(I-1) )
C     XDOT( 19+ISSME*(I-1) ) = -(1./TY8)*X( 19+ISSME*(I-1) )
C     XDOT( 20+ISSME*(I-1) ) = -(1./TPH)*X( 20+ISSME*(I-1) )
C     XDOT( 21+ISSME*(I-1) ) = -(1./TTH)*X( 21+ISSME*(I-1) )
C     XDOT( 22+ISSME*(I-1) ) = -(1./TPOB)*X( 22+ISSME*(I-1) )

C
C     DO 20 II = 1, (NS+NPAR)
C     SUM = 0.0
C     DO 10 JJ = 1, (NS+NPAR)
C     SUM = SUM + P(II,JJ)*VEC1(JJ)
C 10  CONTINUE
C     VEC2(II) = SUM
C 20  CONTINUE

C     CALL INNER ( VEC1, VEC2, COVTVC, (NS+NPAR) )
C     CVTVAC(I) = COVTVC

C SPECIFIC IMPULSE COVARIANCE
C
C     VEC1( 15+ISSME*(I-1) ) = (PFTMR(I)*PWDMR)/WD(I)
C     VEC1( 16+ISSME*(I-1) ) = (PFTPC(I)*PWDPC)/WD(I)
C     VEC1( 17+ISSME*(I-1) ) = (PFTGO(I)*PWDGO)/WD(I)
C     VEC1( 18+ISSME*(I-1) ) = (PFTGH(I)*PWDGH)/WD(I)

C     DO 40 II = 1, (NS+NPAR)
C     SUM = 0.0
C     DO 30 JJ = 1, (NS+NPAR)
C     SUM = SUM + P(II,JJ)*VEC1(JJ)
C 30  CONTINUE
C     VEC2(II) = SUM
C 40  CONTINUE

C     CALL INNER ( VEC1, VEC2, COVISPL, (NS+NPAR) )
C     CVISPL(I) = COVISPL

C LIQUID OXYGEN FLOW RATE COVARIANCE
C
C     VEC1( 15+ISSME*(I-1) ) = PWOMR
C     VEC1( 16+ISSME*(I-1) ) = PWOPC
C     VEC1( 17+ISSME*(I-1) ) = PWOGO
C     VEC1( 18+ISSME*(I-1) ) = PWOGH

C     DO 60 II = 1, (NS+NPAR)
C     SUM = 0.0
C     DO 50 JJ = 1, (NS+NPAR)
C     SUM = SUM + P(II,JJ)*VEC1(JJ)
C 50  CONTINUE
C     VEC2(II) = SUM

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60 CONTINUE
C   CALL INNER ( VEC1, VEC2, COVWDO, (NS+NPAR) )
C   CVWD02(I) = COVWDO
C   C FUEL FLOW RATE COVARIANCE
C
C   VEC1( 15+ISSME*(I-1) ) = PWFNR
C   VEC1( 16+ISSME*(I-1) ) = PWFPC
C   VEC1( 17+ISSME*(I-1) ) = PWFGO
C   VEC1( 18+ISSME*(I-1) ) = PWFGH
C
C   DO 80 II = 1, (NS+NPAR)
C     SUM = 0.0
C     DO 70 JJ = 1, (NS+NPAR)
C       SUM = SUM + P(II,JJ)*VEC1(JJ)
C    70 CONTINUE
C     VEC2(II) = SUM
C  80 CONTINUE
C
C   CALL INNER ( VEC1, VEC2, COVWDH, (NS+NPAR) )
C   CVWDH2(I) = COVWDH
C   C OVERBOARD AND PRESSURANT FLOW RATE COVARIANCES
C
C   CVWD(I) = P( 14+ISSME*(I-1), 14+ISSME*(I-1) )
C   CVWDG0(I) = P( 17+ISSME*(I-1), 17+ISSME*(I-1) )
C   CVWDGH(I) = P( 18+ISSME*(I-1), 18+ISSME*(I-1) )
C
C   1000 CONTINUE
C
C   901  FORMAT( 5X, 3E15.8 )
C
C   RETURN
C   END
C   FUNCTION POW( D, PL, M )
C
C   DIMENSION D(M)
C
C   SUM = 0.0
C   DO 10 I = 2, M
C     J = M - I + 2
C   10 SUM = PL*( D(J) + SUM )
C   POW = D(1) + SUM
C
C   RETURN
C   END

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SUBROUTINE RADAR
 1  DIMENSION C1(3,3),RRDR(3),CEFLLR(3,3),DR(3),DRNG(3),DEL(3)
   VC(3),TMP(3,3),TMP1(3,3)

C COMMON DER(2700), VAR(2700), PMET(5400), NDER
C COMMON / TIMDAT / TMAX, HSTEP, TSAMP, TSTART, TSTOP, TRINT
C COMMON / PROPAG / X(71), P(71,71)
C COMMON / PREUP / XKM(71), PKM(71,71)
C COMMON / LINHMT / H(35,71), NMEAS
C COMMON / LINFMT / F(71,71), NS, NPAR
C COMMON / VEHPOS / REF(3)
C COMMON / RDRDAT / XNO(3), RLAT(3), RLONG(3), RHT(3), NR
C COMMON / ASTRON/CUENED(3,3),RNP(3,3),CBRI(3,3),CBRIB(3,3),TGMMT0
C COMMON / TMAT / CBI(3,3), CIB(3,3), CLLB(3,3), CEFBRI(3,3)
C COMMON / TYPE / ITYPE
C COMMON / CONST / A(71), S(71), R(12)
C COMMON / RDMEAS / AZM(3), ELM(3), RNGM(3)
C COMMON / RDREST / AZHAT(3), ELHAT(3), RNGHAT(3)
C COMMON/UDWORK/RG(71),U(2556),PO(2556),SF(2556),SG(71),RESID,COVZ
C COMMON / QUPDWK / TVEC(71), VEC(71)

C DATA C1 / 2*0.0,1.0,1.0,3*0.0,1.0,0.0 /
DATA CRAD / 57.295779 /

C NTS = NS + NPAR
C TIME = VAR(1)
C KMEAS = 24
C DO 300 IR = 1, NR
C DO 10 I = 1, (NS+NPAR)
X(I) = XKM(I)
CONTINUE
10
C CALL XDVEC
C CALL ECPOS(RLAT(IR),RLONG(IR),RHT(IR),RRDR(1),RRDR(2),RRDR(3))
CALL SUBT ( REF, RRDR, VC, 3, 1 )
CALL TMATY ( -RLONG(IR), TMP1 )
CALL TMATP ( RLAT(IR), CEFLLR )
CALL MULT ( CEFLLR, TMP1, TMP, 3, 3, 3 )
CALL MULT ( C1, TMP, CEFLLR, 3, 3, 3 )
CALL MULT ( CEFLLR, VC, DR, 3, 3, 1 )
CALL TRANS ( CEFBRI, TMP1, 3, 3 )
CALL MULT ( CEFLLR, TMP1, TMP, 3, 3, 3 )
C RNGES = DR(1)*DR(1) + DR(2)*DR(2) + DR(3)*DR(3)
C RGHAT(IR) = SQRT(RNGES) + XKM( 55 + NR*(IR - 1) )
C XYS = RNGES - DR(3)*DR(3)
XY = SQRT(XYS)
C

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AZHAT(IR) = CRAD*ATAN2(DR(1),DR(2)) + XKM( 53 + NR*(IR - 1) )
ELHAT(IR) = CRAD*ATAN(DR(3)/XY) + XKM( 54 + NR*(IR-1) )
CALL_REFAC ( IR, ELHAT(IR), RNGHAT(IR), DEL(IR), DRNG(IR) )
RNGHAT(IR) = RNGHAT(IR) + DRNG(IR)
ELHAT(IR) = ELHAT(IR) + DEL(IR)
WRITE(*, 997) AZHAT(IR), ELHAT(IR), RNGHAT(IR)
WRITE(*, 997) AZM(IR), ELM(IR), RNGM(IR)

C
IF ( ITYPE ) 13, 13, 20
CONTINUE

13
SRNG = SQRT(R(11))
SELE = SQRT(R(10))
SAZI = SQRT(R(9))
CALL_NOISE ( SRNG, VRNG )
CALL_NOISE ( SELE, VELE )
CALL_NOISE ( SAZI, VAZI )
RNGM(IR) = RNGHAT(IR) + VRNG
AZM(IR) = AZHAT(IR) + VAZI
ELM(IR) = ELHAT(IR) + VELE

C
WRITE(2,997) AZM(IR), ELM(IR), RNGM(IR)
GO TO 300

C
CONTINUE

20
VC(1) = CRAD*DR(2)/XYS
VC(2) = -CRAD*DR(1)/XYS
VC(3) = 0.0

C
H((25+NR*(IR-1),1)=VC(1)*TMP(1,1)+VC(2)*TMP(2,1)+VC(3)*TMP(3,1)
H((25+NR*(IR-1),2)=VC(1)*TMP(1,2)+VC(2)*TMP(2,2)+VC(3)*TMP(3,2)
H((25+NR*(IR-1),3)=VC(1)*TMP(1,3)+VC(2)*TMP(2,3)+VC(3)*TMP(3,3)
C
H((25+NR*(IR-1),53+NR*(IR-1)) = 1.0

C
VC(1) = -CRAD*DR(1)*DR(3)/(RNGES*XY)
VC(2) = -CRAD*DR(2)*DR(3)/(RNGES*XY)
VC(3) = CRAD*XY/RNGES

C
H((26+NR*(IR-1),1)=VC(1)*TMP(1,1)+VC(2)*TMP(2,1)+VC(3)*TMP(3,1)
H((26+NR*(IR-1),2)=VC(1)*TMP(1,2)+VC(2)*TMP(2,2)+VC(3)*TMP(3,2)
H((26+NR*(IR-1),3)=VC(1)*TMP(1,3)+VC(2)*TMP(2,3)+VC(3)*TMP(3,3)
C
H((26+NR*(IR-1),54+NR*(IR-1)) = 1.0

C
VC(1) = DR(1)/RNGHAT(IR)
VC(2) = DR(2)/RNGHAT(IR)
VC(3) = DR(3)/RNGHAT(IR)

C
H((27+NR*(IR-1),1)=VC(1)*TMP(1,1)+VC(2)*TMP(2,1)+VC(3)*TMP(3,1)
H((27+NR*(IR-1),2)=VC(1)*TMP(1,2)+VC(2)*TMP(2,2)+VC(3)*TMP(3,2)
H((27+NR*(IR-1),3)=VC(1)*TMP(1,3)+VC(2)*TMP(2,3)+VC(3)*TMP(3,3)
C
H((27+NR*(IR-1),55+NR*(IR-1)) = 1.0

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C DO 200 IM = 1, 3
C KMEAS = KMEAS + 1
C IF ( RNGM(IR).EQ.0.0 ) THEN
  RESID = 0.0
  COVZ = 0.0
  CALL ZEROM( RG, NTS, 1 )
ELSE
C UDU**T FACTORED COVARIANCE UPDATE
C
C KJ = 0
DO 140 J = 1, (NS+NPAR)
  RG(J) = H(KMEAS,J)
DO 140 K = 1, J
  KJ = KJ + 1
  U(KJ) = PKM(J,K)
CONTINUE
C
C CALL COV2UD( U, NTS )
C
C RR = R(8+IM)
C
C ALPHA = -1.0
CALL UDMEAS( U, NTS, RR, RG, SF, SG, ALPHA )
C
C CALL UD2COV( U, PO, NTS )
C
C RESID = AZM(IR) - AZHAT(IR)
IF ( IM.EQ.2 ) RESID = ELM(IR) - ELHAT(IR)
IF ( IM.EQ.3 ) RESID = RNGM(IR) - RNGHAT(IR)
COVZ = ALPHA
C
C IF ( ABS(RESID).GT.(6.*SQRT(COVZ)) ) GO TO 180
C
C DO 150 J = 1, (NS+NPAR)
  X(J) = XKM(J) + (SG(J)/ALPHA)*RESID
CONTINUE
C
C IJ = 0
DO 160 J = 1, (NS+NPAR)
  DO 160 I = 1, J
    IJ = IJ + 1
    PKM(I,J) = PO(IJ)
    PKM(J,I) = PKM(I,J)
CONTINUE
C
C IF ( TIME - TRINT ) 320, 310, 310
C
C 310 CONTINUE
C
C DQ1 = XKM(7) - X(7)
DQ2 = XKM(8) - X(8)
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DQ3 = XKM(9) - X(9)
DQS = XKM(7)**2 + XKM(8)**2 + XKM(9)**2
IF ( DQS.LT.1.0 ) THEN
  DQ4 = -(XKM(7)*DQ1+XKM(8)*DQ2+XKM(9)*DQ3)/SQRT( 1.0 - DQS )
  XKM(10) = X(10) + DQ4
END IF
IF ( ABS((DQS+XKM(10)**2)-1.0).GT.1.E-4 ) THEN
  XKM(7) = X(7)
  XKM(8) = X(8)
  XKM(9) = X(9)
  XKM(10) = X(10)
ELSE
END IF
TVEC(7) = -XKM(7)/X(10)
TVEC(8) = -XKM(8)/X(10)
TVEC(9) = -XKM(9)/X(10)
CALL MULT ( TVEC, PKM, VEC, 1, NTS, NTS )
DO 170 I = 1, (NS+NPAR)
  PKM(10,I) = VEC(I)
  PKM(I,10) = VEC(I)
CONTINUE
CALL INNER ( VEC, TVEC, TEMP, NTS )
  PKM(10,10) = TEMP
C
C
C
180 CONTINUE
C
END IF
C
CALL OUTPUT
C
200 CONTINUE
C
300 CONTINUE
C
RETURN
C
995 FORMAT( 3X, 5E15.8 )
998 FORMAT( 7X, 4E15.8 )
997 FORMAT( 5X, 3E15.8 )
C
END

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SUBROUTINE NASSRB

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C      DIMENSION POHB(2), VEC1(71), VEC2(71)
1      ,K(2), TTTAU(15), TDTSRB(15)

C      COMMON DER(2700), VAR(2700), TMP(5400), NDER
COMMON / TIMDAT / TMAX, HSTEP, TSAMP, TSTART, TSTOP, TRINT
COMMON / CONST / AA(71), S(71), R(12)
COMMON / PROPAG / X(71), P(71,71)
COMMON / DRVITV / XDOT(71), PD(71,71)
COMMON / SRBTBL / TFSA(15), TTAU(15), TPVOL(15), TAT(15), TCSTR(15)
1      ,TCT(15), NTAU
2      ,CMN, G, GAMMA, PE, ABAR, PBAR, EP, RHOP, XLNGTH, RBAR, XMBAR, TEMP, PI
3      ,DTSEP

COMMON / SRBDAT / TVACS(2), XISPS(2), XMD(2), AEXIT(2)
1      ,CVPOH(2), CVTVAC(2), CVISPS(2), CVMD(2), CVAE(2)
2      ,OMASS(2)
COMMON / RBPRTL / PFT(2), PFA(2), PFPM(2)
COMMON / LINFMT / F(71,71), NS, NPAR
COMMON / SRBMEA / POHHAT(2)
COMMON / PONOZZ / PON(2)
COMMON / LINHMT / H(35,71), NMMEAS

C      DATA TTTAU/0.0,-73.1,-73.2,-16,-3,-4.6,-4.75,-6,-4.8,-8,-8.86
1      ,12,-53,-17,-28,-25,-92,-34,-34,-35,-4.2,-40,-61,-43,-2/
DATA TDTSRB/0.,23500.,34000.,20500.,22500.,18000.,17000.,90000.
1      ,500.,-5500.,-5500.,-6500.,-500.,-18500.,0./

DATA NNTAU, TSF / 15, .9925 /
DATA XMDOFS / 12. /
DATA GF / 32.174 /
DATA TAU, TAUCM, TAUPB / 1.E+1, 1.E+2, 1.E+3 /

C      IF ( IJUMP ) 5, 5, 10
5 CONTINUE

C      RT = RBAR*TEMP/(XMBAR*GF)
GM1OG = (GAMMA-1.0)/GAMMA
GP1GM1 = (GAMMA+1.0)/(GAMMA-1.0)
F1GM = ((2.*GAMMA**2)/(GAMMA-1.0)) * ((2. / (GAMMA+1.)) ** GP1GM1)
F2GM = SQRT(F1GM)
AN = ABAR*PBAR**(-EP)
OQMN = 1. / (1.-EP)
XNOOMN = EP*OQMN
AFAC = ( 150.208 - 149.644 )/43.2

C      IJUMP = 1
C      10 CONTINUE
C      10 CONTINUE
C      ISR = 5
C      FOR EACH SRB
C      DO 1000 I = 1, 2

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CALL ZEROM ( VEC1, 71, 1 )
CALL ZEROM ( VEC2, 71, 1 )

C TAU = X(63 + ISRBI*(I-1))

C AEXIT(I) = (PI/4.) * ( 149.644 + AFAC*TAU ) **2

C CALL INTRP1 ( TAU, TTAU, TFSR, NTAU, AB, PABT )
C CALL INTRP1 ( TAU, TTAU, TPVOL, NTAU, PVOL, PPVOLT )
C CALL INTRP1 ( TAU, TTAU, TAT, NTAU, AT, PATT )
C CALL INTRP1 ( TAU, TTAU, TCSTR, NTAU, CSTAR, PCST )
C CALL INTRP1 ( TAU, TTAU, TCT, NTAU, CT, PCTT )
C CALL INTRP1 ( TAU, TTTAU, TDTSRB, NTTAU, DTTSRB, SLOPE )

C IF ( AB.LE.0.0 ) AB = 1.0

C C OMASS(I) = X(62 + ISRBI*(I-1))
C A = AN + X(64 + ISRBI*(I-1))
C CMN = CMN + X(65 + ISRBI*(I-1))

C PO = (CSTAR*RHOP*A*AB/(G*AT)) * OOMN

C PON(I) = PO

C GEO = 16.*PI*RT*(AT*G/(CSTAR*AB)) **2
C GEO = GEO*XLENGTH**3/PVOL
DP = ( 1.0 + SQRT( 1.0 + GEO ) )/2.0
POH = PO*DP
TAUD = A*PO**EP
XMD(I) = RHOP*TAUD*AB + XMDOFS

C TVACS(I) = CM*CT*AT*PO*TSF + DTTSRB

C PPOT = OOMN*TAUD*(RHOP/G)*((CSTAR/AT)*PABT+(AB/AT)*PCST
1 -(CSTAR*AB/(AT**2))*PATT)
PTDT = A*EP*(PO**EP-1.)*PPOT
PTDA = OOMN*PO*EP
PFT(I) = CM*(CT*PPOT*AT+CT*PO*PATT+PO*AT*PCTT)
PMDA = +RHOP*AB*PTDA
PPOA = OOMN*((CSTAR*RHOP*AB/(G*AT))*OOMN)*(A**XNOOMN)
PPOHA = PPOA*DP
PMDT = +RHOP*(PABT*TAUD + AB*PTDT)
FPEPO = (PE/PO)**GM10G
PCTPO = 0.5*(F2GM/SQRT(1.0-FPEPO))*(GM10G+FPEPO)/PO
1 -(PE - PA)*AE/(AT*PO**2)
PCTPO = 0.0
PFA(I) = CM*CSTAR*(PCTPO*PPOA*XMD(I) + PMDA*CT)/G
PFCM(I) = CT*PO*AT
PPOCS = OOMN*((RHOP*A*AB/(G*AT))*OOMN)*CSTAR**XNOOMN
PFCS = CM*CT*AT*GF*PPOCS
PTDCS = A*XNOOMN*((RHOP*A*AB/(G*AT))*XNOOMN)*CSTAR**XNOOMN-1.)
PMDCS = +RHOP*AB*PTDCS
PMDAT = +XNOOMN*XMD(I)/AT
PTDAT = -XNOOMN*TAUD/AT
PPOAT = -OOMN*PO/AT

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C PPOHT = PPOT*DP
1 +GEO*(-PPVOLT/PVOL-2.*PABT/AB+2.*PATT/AT-2.*PCST/CSTAR)/DP
PPOHA = PPOA*DP
PPOHCS = PPOCS*DP
1 -GEO/(2.*CSTAR*DP)
PPOHAT = PPOAT*DP
1 +GEO/(2.*AT*DP)

C F( (62+ISRB*(I-1)), (63+ISRB*(I-1)) ) = PMDT
F( (62+ISRB*(I-1)), (64+ISRB*(I-1)) ) = PMDA
F( (63+ISRB*(I-1)), (63+ISRB*(I-1)) ) = PTDT
F( (63+ISRB*(I-1)), (64+ISRB*(I-1)) ) = PTDA

C F( (64+ISRB*(I-1)), (64+ISRB*(I-1)) ) = -1./TAUA
F( (65+ISRB*(I-1)), (65+ISRB*(I-1)) ) = -1./TAUCM
F( (66+ISRB*(I-1)), (66+ISRB*(I-1)) ) = -1./TAUPB

C S( 64+ISRB*(I-1) ) = 2.* (AA( 64+ISRB*(I-1) ) ) **2./TAUA
S( 65+ISRB*(I-1) ) = 2.* (AA( 65+ISRB*(I-1) ) ) **2./TAUCM
S( 66+ISRB*(I-1) ) = 2.* (AA( 66+ISRB*(I-1) ) ) **2./TAUPB

C H( (33+I), (62+ISRB*(I-1)) ) = 0.0
H( (33+I), (63+ISRB*(I-1)) ) = PPOT
H( (33+I), (64+ISRB*(I-1)) ) = PPOHA
H( (33+I), (65+ISRB*(I-1)) ) = 0.0
H( (33+I), (66+ISRB*(I-1)) ) = 1.0

C POHHAT(I) = POH + X( 66+ISRB*(I-1) )

C XISPS(I) = TVACS(I)/XMD(I)

C XDOT( 62+ISRB*(I-1) ) = XMD(I)
XDOT( 63+ISRB*(I-1) ) = TAUD
XDOT( 64+ISRB*(I-1) ) = -1./TAUA)*X( 64+ISRB*(I-1) )
XDOT( 65+ISRB*(I-1) ) = -(1./TAUCM)*X( 65+ISRB*(I-1) )
XDOT( 66+ISRB*(I-1) ) = -(1./TAUPB)*X( 66+ISRB*(I-1) )

C IF ( POHHAT(I).LT.50. ) THEN
K(I) = 1
ELSE
END IF

C IF ( KJUMP ) 15, 15, 20
15 CONTINUE
KK = K(1)*K(2)
IF ( KK.GT.0 ) THEN
TSTOP = VAR(1) + DTSEP
WRITE(*, 901) TSTOP, (POHHAT(II), II = 1, 2)
KJUMP = 1
ELSE
END IF
CONTINUE
C
20

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C HEAD PRESSURE COVARIANCE
C
C VEC1( 63+ISRB*(I-1) ) = PPOHT
C VEC1( 64+ISRB*(I-1) ) = PPOHA
C VEC1( 65+ISRB*(I-1) ) = 0.0
C VEC1( 66+ISRB*(I-1) ) = 1.0
C
C DO 40 II = 1, (NS+NPAR)
C SUM = 0.0
C DO 30 JJ = 1, (NS+NPAR)
C SUM = SUM + P(II,JJ) * VEC1(JJ)
C 30 CONTINUE
C VEC2(II) = SUM
C 40 CONTINUE

C CALL INNER ( VEC1, VEC2, COVPOH, (NS+NPAR) )
C CVPOH(I) = COVPOH

C VACUUM THRUST COVARIANCE
C
C VEC1( 63+ISRB*(I-1) ) = 0.0
C VEC1( 64+ISRB*(I-1) ) = PFA(I)
C VEC1( 65+ISRB*(I-1) ) = PFCM(I)
C VEC1( 66+ISRB*(I-1) ) = 0.0
C
C DO 60 II = 1, (NS+NPAR)
C SUM = 0.0
C DO 50 JJ = 1, (NS+NPAR)
C SUM = SUM + P(II,JJ) * VEC1(JJ)
C 50 CONTINUE
C VEC2(II) = SUM
C 60 CONTINUE

C CALL INNER ( VEC1, VEC2, COVTVC, (NS+NPAR) )
C CVTVC(I) = COVTVC

C SPECIFIC IMPULSE COVARIANCE
C
C VEC1( 63+ISRB*(I-1) ) = -( RHOP*XISPS(I)*PABT*TAVL
C 1           + EP*G*AT*XISPS(I)*PPOT/CSTAR
C 2           + CM*CT*AT*PPOT )/XMD(I)
C VEC1( 64+ISRB*(I-1) ) = -( XMD(I)*XISPS(I)/A
C 1           + EP*G*AT*XISPS(I)*PPOA/CSTAR
C 2           + CM*CT*AT*PPOA )/XMD(I)
C CSTAR VEC1( 65+ISRB*(I-1) ) = CM*CT/G
C VEC1( 66+ISRB*(I-1) ) = 0.0
C
C DO 80 II = 1, (NS+NPAR)
C SUM = 0.0
C DO 70 JJ = 1, (NS+NPAR)
C SUM = SUM + P(II,JJ) * VEC1(JJ)
C 70 CONTINUE
C VEC2(II) = SUM
C 80 CONTINUE

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```
C CALL INNER ( VEC1, VEC2, COVISP, (NS+NPAR) )
CVISPS(I) = COVISP

C MASS OVERBOARD RATE COVARIANCE
C
C   VEC1( 63+ISRB*(I-1) ) = 0.0
C   VEC1( 64+ISRB*(I-1) ) = PMDA
C   VEC1( 65+ISRB*(I-1) ) = 0.0
C   VEC1( 66+ISRB*(I-1) ) = 0.0
C
DO 100 II = 1, (NS+NPAR)
SUM = 0.0
DO 90 JJ = 1, (NS+NPAR)
SUM = SUM + P(II,JJ)*VEC1(JJ)
90 CONTINUE
VEC2(II) = SUM
100 CONTINUE

C CALL INNER ( VEC1, VEC2, COVMD, (NS+NPAR) )
COVMD(I) = COVMD

C EXIT AREA COVARIANCE
C
C   VEC1( 63+ISRB*(I-1) ) = (PI/2.)*AFAC*TAU
C   VEC1( 64+ISRB*(I-1) ) = 0.0
C   VEC1( 65+ISRB*(I-1) ) = 0.0
C   VEC1( 66+ISRB*(I-1) ) = 0.0
C
DO 120 II = 1, (NS+NPAR)
SUM = 0.0
DO 110 JJ = 1, (NS+NPAR)
SUM = SUM + P(II,JJ)*VEC1(JJ)
110 CONTINUE
VEC2(II) = SUM
120 CONTINUE

C CALL INNER ( VEC1, VEC2, COVAE, (NS+NPAR) )
COVAE(I) = COVAE

C 1000 CONTINUE
C
901 FORMAT( 5X, 3E15.8 )
902 FORMAT( 5X, 5E15.8 )
991 FORMAT( 2X, 7E10.4 )
992 FORMAT( 12X, 2E10.4 )
C
RETURN
END
```

```

C
C DIMENSION TMACH(15),TCAO(15),TCAA(15),TCAA2(15),TCAAB2(15)
1   ,TCN0(15),TCNA(15),TCNAB2(15),TCAA2(15),TCDAB2(15)
2   ,TCLM0(15),TCLMA(15),TCMAB2(15)
3   ,TCY0(15),TCYB(15),TCYAB(15),TCYA2B(15)
4   ,TCLN0(15),TCLNB(15),TCLNAB(15),TCNA2B(15)
5   ,TCLL0(15),TCLLB(15),TCLLAB(15),TCLA2B(15)
DIMENSION TCYPO(15),TCYPA(15),TCYR0(15),TCYRA(15)
1   ,TCLMQ0(15),TCLMQA(15)
2   ,TCLNP0(15),TCLNPA(15),TCLNRO(15),TCLNRA(15)
3   ,TCLLP0(15),TCLLPA(15),TCLLR0(15),TCLLRA(15)

C
C DIMENSION TMACH2(5),TCA20(5),TCA2A(5),TCA2A2(5)
1   ,TCN20(5),TCN2A(5),TCN2A2(5)
2   ,TCLM20(5),TCLM2A(5),TCLM2A2(5)
3   ,TCY20(5),TCY2B(5),TCY2AB(5),TY2A2B(5)
4   ,TCLN20(5),TCLN2B(5),TLN2AB(5),TN2A2B(5)
5   ,TCLL20(5),TCLL2B(5),TCL2AB(5),TL2A2B(5)

C COMMON DER(2700), VAR(2700), TEMP(5400), NDER
COMMON / CONST / A(71), S(71), RR(12)
COMMON / STATES / RI(3), VB(3), Q(4), OMEGA(3)
COMMON / PROPAG / X(71), PMAT(71,71)
COMMON / DRVITV / XDOT(71), PD(71,71)
COMMON / LINFMT / F(71,71), NS, NPAP
COMMON / AERO / CFO(3), CFALP(3), CPBET(3), CFQ(3,3), CM0(3), CMALP(3)
1   , CMBET(3), CMQ(3,3), CF(3), CM(3)
COMMON / STAGE / IStage
COMMON / IPARAM / ISSME, ISRB, IAERO, IPLUME, IWIND, JACB, JRDR

C DATA CAB2, CAA2, CNAB2, CYA#, CYA2B, CYPA, CYRA / 8*0.0 /

C DATA TAUF / 2.E+1 /

C DATA TMACH / 0.6,0.8,0.9,0.95,1.0,1.1,1.15,1.25,1.4,1.55
1   ,1.8,2,2,2.5,3,5,4,5/
DATA TMACH2 / 3.5,4.5,6,0,8,0,10,0 /
```

```
DATA TAUF / 2.E+1 /
```

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C
C DATA TCLL0/0.55153607E-02,-0.51660468E-02,-0.53059668E-02,
1 0.00102300,0.00255850,0.00142150,0.00088950,0.00162650,
2 0.00162500,0.00160650,0.00164350,0.00175700,0.00078500,
3 -0.00035500/
DATA TCLLB/-0.57055471E-02,-0.65046088E-02,-0.73706545E-02,-0.64209271E-02,
1 -0.61848979E-02,-0.60260380E-02,-0.57253810E-02,-0.55433516E-02,
2 -0.53707338E-02,-0.46027126E-02,-0.38413065E-02,-0.3225023E-02/
DATA TCILAB/-0.18314904E-03,-0.24067984E-03,-0.17415131E-03,
1 -0.18708523E-03,-0.21297160E-03,0.23723571E-04,-0.10909401E-03,
2 -0.15336619E-03,-0.40835867E-03,-0.20703866E-03,-0.17273379E-03,
3 -0.55630488E-04,-0.66665525E-04,-0.45428569E-04,-0.65075328E-04/
DATA TCIA2B/0.25525271E-05,-0.47074923E-05,0.40663767E-6,
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C C
1 0.2640435E-05, 0.71316317E-05, 0.41424133E-04, 0.19684549E-04,
2 0.76067136E-05, -0.20967154E-04, 0.41421335E-05, 0.7140406E-05,
3 0.12803971E-04, 0.22202585E-05, -0.9402070E-05, -0.8505900E-05/
C C
DATA TCLN0/0.00101900,-0.00196700,0.00001700,-0.00033150,
1 -0.00102900,-0.00056750,-0.00357700,-0.00415650,-0.00269050,
2 -0.00395800,-0.00297900,-0.00073950,-0.00348650,-0.00259800,
3 0.00097000/
DATA TCLNB/0.14767525E-01,0.15323062E-01,0.15911508E-01,
1 0.16263550E-01,0.16967123E-01,0.15625395E-01,0.15465586E-01,
2 0.15171567E-01,0.14852828E-01,0.15761562E-01,0.17182207E-01,
3 0.18076595E-01,0.16406817E-01,0.13792288E-01,0.11427909E-01/
DATA TCLNAB/0.56945679E-04,0.11934886E-03,-0.12992905E-04,
1 -0.21390285E-05,0.19518508E-04,0.11725974E-04,0.40781717E-04,
2 0.17625467E-03,0.32387782E-03,0.2374810E-03,0.21290279E-03,
3 0.11312054E-03,-0.58733131E-04,-0.43780621E-03,-0.46182974E-03/
DATA TCNA2B/0.81995468E-05,0.30770094E-04,0.26990148E-04,
1 0.21246726E-04,0.97513848E-05,0.28817041E-04,0.19518948E-04,
2 0.30797459E-04,0.55297049E-04,0.29008272E-04,0.23987936E-05,
3 0.10975672E-04,0.34038654E-04,0.47138979E-05,-0.30127571E-05/
C C

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DATA TCY0/0.00040550,0.00611750,0.00208050,0.00340600,
1 0.00659450,0.00389250,0.00896900,0.01099600,0.00895500,
2 0.006684850,0.00122250,-0.00312350,0.00190050,0.00643500,
3 0.00000500/
DATA TCYB/-0.34736611E-01,-0.35624493E-01,-0.37405483E-01,
1 -0.37516881E-01,-0.37924547E-01,-0.3587856E-01,
2 -0.34745876E-01,-0.33643633E-01,-0.32880556E-01,
3 -0.36689218E-01,-0.37921809E-01,-0.39925124E-01,
4 -0.38449090E-01,-0.34494311E-01,-0.30585317E-01/
DATA TCYAB/-0.24396958E-03,-0.19144324E-03,-0.96200623E-04,
1 -0.16656239E-03,-0.28471148E-03,-0.67672569E-04,
2 -0.10685262E-03,-0.210742E-03,-0.30565454E-03,
3 -0.21161194E-03,0.23066868E-03,0.12333597E-03,
4 0.28201332E-03,0.69754681E-03,0.73324196E-03/
DATA TCYAB/-0.34743120E-04,-0.68390669E-04,-0.65476503E-04,
1 -0.65729291E-04,-0.51625058E-04,-0.67499590E-04,
2 -0.56302903E-04,-0.70274968E-04,-0.94529889E-04,
3 -0.58715108E-04,0.111960622E-04,-0.23788327E-04,
4 -0.50999923E-04,-0.20773427E-04,-0.23277323E-05/
C C
DATA TCA0/0.14888462,0.14096716,0.15895303,0.18570921,
1 0.24431951,0.25983587,0.26992825,0.28716668,0.30411604,
2 0.30857432,0.30735463,0.28761023,0.28410554,0.28069207,
3 0.28001353/
DATA TCAA/-0.14939267E-02,-0.16073198E-02,-0.87178504E-03,
1 -0.80946332E-03,-0.68517815E-03,-0.53749926E-03,
2 -0.20928589E-03,-0.47267828E-03,-0.53303648E-03,
3 -0.51839335E-03,-0.11330346E-02,-0.97124977E-03,
4 -0.12258916E-02,-0.27267837E-02,-0.40642847E-02/
DATA TCAAB2/0.52950736E-05,0.80431100E-05,-0.79241381E-05,
1 -0.97817874E-05,-0.85392085E-05,0.31472900E-05,
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2 -0.46378850E-05,-0.17535077E-05,-0.350931940E-05,
3 -0.30256535E-06,0.91515847E-06,-0.10002519E-04,
4 -0.14255994E-04,-0.18130060E-04,-0.13194465E-04/
DATA TCDAFB2/-0.19513888E-03,-0.15666662E-03,-0.10849207E-03,
1 -0.14827383E-03,-0.20781747E-03,-0.17412701E-03,
2 -0.13521819E-03,-0.124334516E-03,-0.19692448E-03,
3 -0.21642850E-03,-0.18192461E-03,-0.89146888E-04,
4 -0.38432758E-04,0.14365064E-03,0.1593253E-03/
DATA TCAA2/-0.366778764E-03,-0.29035713E-03,-0.17375973E-03,
1 -0.22280747E-03,-0.32113091E-03,-0.28126000E-03,
2 -0.23748010E-03,-0.26166640E-03,-0.16787715E-03,
3 -0.12008918E-03,-0.79305413E-04,-0.40277255E-05,
4 0.16438302E-04,0.11210326E-03,0.14424580E-03/
C C

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DATA TCLM0/-0.08278762,-0.10786715,-0.09791238,-0.08543953,
1 -0.07620762,-0.06862953,-0.07373904,-0.07957237,-0.07712714,
2 -0.06862857,-0.05165952,-0.02029048,0.00235619,0.01028095,
3 0.01356667/
DATA TCLMA/-0.15543575E-01,-0.18000530E-01,-0.19910170E-01,
1 -0.20583043E-01,-0.21927318E-01,-0.20931607E-01,
2 -0.20659992E-01,-0.20311428E-01,-0.20116061E-01,
3 -0.20584987E-01,-0.22142328E-01,-0.19702138E-01,
4 -0.18991778E-01,-0.13785718E-01,-0.111521422E-01/
DATA TCMAB2/0.16693601E-04,0.21230151E-05,-0.26527516E-04,
1 0.85657601E-04,0.21230151E-05,-0.26527516E-04,
2 0.65993113E-05,-0.95234933E-06,-0.17661379E-04,
3 0.12942927E-05,0.42312208E-05,-0.14325634E-04,
4 -0.528894680E-04,-0.24528768E-04,-0.27753043E-04/
C C

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DATA TCNO/0.06175191,0.08705191,0.06880905,0.06304239,
1 0.05150905,0.04629619,0.05327953,0.06288191,0.05508667,
2 0.04784143,0.02033000,-0.00378286,-0.03606287,
3 -0.04565714,-0.05337614/
DATA TCNA/0.47317315E-01,0.51266242E-01,0.55013947E-01,
1 0.55984642E-01,0.57926252E-01,0.58463752E-01,
2 0.56734987E-01,0.56824278E-01,0.56955535E-01,
3 0.56824278E-01,0.57594139E-01,0.52612297E-01,
4 0.51134817E-01,0.39903577E-01,0.36437500E-01/
DATA TCNAB2/-0.34952373E-06,-0.21971118E-04,0.37438092E-05,
1 0.12846999E-04,0.31073960E-04,0.18769655E-04,0.49979085E-05,
2 0.195733176E-04,0.44349854E-04,0.24865894E-04,-0.13175871E-04,
3 0.82223523E-05,0.49027673E-04,0.62995699E-04,0.43675380E-04/
C C

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DATA TCY20/-0.00283400,-0.00476067,-0.00862133,-0.01420600,
1 -0.01559400/
DATA TCY2B/-0.35310987E-01,-0.32411996E-01,-0.28534999E-01,
1 -0.25360515E-01,-0.23243498E-01/
DATA TCY2AB/0.67670009E-03,0.65709988E-03,0.60950016E-03,
1 0.55275002E-03,0.48189994E-03/
DATA TY2A2B/0.41799358E-04,0.32219676E-04,0.41402013E-05,
1 -0.10169592E-04,0.23179970E-04/
C C

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C DATA TCLN20/0.00310133,0.00433133,0.00328200,0.00237733,
1 0.00358800/
C DATA TCLN2B/0.14233000E-01,0.11893496E-01,0.90009952E-02,
1 0.77250013E-02,0.71255034E-02/
C DATA TN2AB/-0.41310006E-03,-0.37830003E-03,-0.31595002E-03,
1 -0.28525002E-03,-0.27645013E-03/
C DATA TN2A2B/-0.87519926E-04,-0.43759825E-04,0.36501278E-05,
1 -0.22901133E-05,-0.23530063E-04/
C
C DATA TCLL20/-0.00099533,-0.00212667,-0.00141267,-0.00262400,
1 -0.00266133/
C DATA TCLL2B/-0.55765007E-02,-0.46779984E-02,-0.38770009E-02,
1 -0.33380005E-02,-0.32379995E-02/
C DATA TCL2AB/0.17604997E-03,-0.11775004E-03,-0.11815000E-03,
1 0.4659998E-04,0.14849989E-04/
C DATA TL2A2B/-0.12449930E-04,0.12530111E-04,0.31110012E-04,
1 -0.91998515E-06,0.11949987E-04/
C
C DATA TCA20/0.17786667,0.168868572,0.16880476,
1 0.17327619,0.16560951/
C DATA TCA2A/-0.38053570E-02,-0.42267856E-02,-0.43714279E-02,
1 -0.46357140E-02,-0.47821430E-02/
C DATA TCA2A2/0.11815455E-03,0.16160712E-03,0.12023804E-03,
1 0.10416679E-03,0.14226201E-03/
C
C DATA TCN20/-0.08282144,-0.07680953,-0.06490477,
1 -0.06376192,-0.06909525/
C DATA TCN2A/0.27379462E-01,0.24214283E-01,0.21875000E-01,
1 0.20946428E-01,0.20232143E-01/
C DATA TCN2A2/0.24330383E-03,0.18452371E-03,0.38690865E-04,
1 -0.32738029E-04,-0.29761522E-05/
C
C DATA TCLM20/0.05514286,0.04723310,0.04276191,0.03900000,
1 0.03719047/
C DATA TCLM2A/-0.10821427E-01,-0.86785713E-02,-0.68392851E-02,
1 -0.56071421E-02,-0.50357138E-02/
C DATA TCM2A2/-0.17857179E-04,0.11904769E-03,0.86309483E-04,
1 0.89285677E-04,0.11309532E-03/
C
C DATA FOR MACH 4.5 ONLY
C
C DATA CLNP20,CLNR20,CLLP20,CLLR20/
1 - .936, .225, -.799, -.145, .195/
C *****
C
C DATA CLMQ0/-2520E1,-2731E1,-2880E1,-2972E1,-3164E1,-3248E1,
1 -.3112E1,-3354E1,-3189E1,-2835E1,-2082E1,-1375E1,
2 -.1300E1,-1031E1,-1069E1/
C

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C      DATA TCLMQA/.375E-2, -.2382E-1, -.2000E-1, -.8209E-2, .2947E-1,
1     .5103E-1, .71509E-1, .10104E0, .11064E0, .90109E-1, .2674E-1,
2     -.1699E-1, .12505E-1, .3607E-1, .3945E-1/
C
C      DATA TCLNP0/.240E0, .271E0, .285E0, .291E0, .302E0, .307E0, .312E0,
1     .320E0, .329E0, .333E0, .325E0, .263E0, .227E0, .234E0, .152E0/
C
C      DATA TCLNPA/-1.23E-1, -.626E-1, -.387E-2, -.292E-2, -.143E-2,
1     -.850E-3, -.340E-3, .550E-3, .168E-2, .259E-2, .350E-2, .337E-2,
2     .560E-2, -.512E-2, -.155E-2/
C
C      DATA TCLNRO/.5000E0, -.9310E0, -.1570E1, -.1746E1, -.1839E1, -.1800E1,
1     -.1733E1, -.1598E1, -.1493E1, -.1481E1, -.1572E1, -.1662E1,
2     -.1580E1, -.1106E1, -.9080E1/
C
C      DATA TCLNRA/-3.750E-1, -.5136E-1, -.4000E-1, -.3331E-1, -.2062E-1,
1     -.1510E-1, -.1045E-1, -.4760E-2, -.4910E-2, -.1168E-1, -.2651E-1,
2     -.2070E-1, -.6900E-2, -.2168E-1, -.7200E-3/
C
C      DATA TCLIIP0/-2.95E0, -.259E0, -.251E0, -.256E0, -.279E0, -.294E0,
1     -.309E0, -.331E0, -.343E0, -.333E0, -.290E0, -.228E0, -.218E0,
2     -.207E0, -.168E0/
C
C      DATA TCLIIR0/.100E-2, -.137E-2, -.162E-2, -.127E-2, -.900E-4,
1     .940E-3, .181E-2, .324E-2, .438E-2, .465E-2, .399E-2, .278E-2,
2     .356E-2, .386E-2, .344E-2/
C
C      DATA TCLILO/.282E0, .438E0, .481E0, .482E0, .449E0, .423E0,
1     .394E0, .342E0, .2944E0, .274E0, .275E0, .250E0, .167E0,
2     .122E0/
C
C      DATA NMACH, NMACH2 / 15, 5 /
C
C      P = OMEGA(1)
C      R = OMEGA(3)
C
C      CALL ZEROM( CFQ, 3, 3 )
C      CALL ZEROM( CFALP, 3, 1 )
C      CALL ZEROM( CFBET, 3, 1 )

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ALPHAS = ALPHA*ALPHA
BETAS = BETA*BETA
PDO2V = P*DO2V
RDO2V = R*DO2V
C
C IF ( XMACH.LT.0.6 ) XMACH = 0.6
C
C AXIAL COEFFICIENT
C
CALL INTRP1 ( XMACH, TMACH, TCA0, NMACH, CA0, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCAA, NMACH, CAA, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCAAB2, NMACH, CAAB2, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCAA2, NMACH, CAA2, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCDAB2, NMACH, CAB2, SLOPE )
C
CF0(1) = -CA0
CAALP = CAA + CAA2*ALPHA + CAAB2*BETAS
CABET = (CAAB2*ALPHA + CAB2)*BETA
CPALP(1) = -CAALP
CPBET(1) = -CABET
C
C NORMAL FORCE COEFFICIENT
C
CALL INTRP1 ( XMACH, TMACH, TCN0, NMACH, CN0, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCNA, NMACH, CNA, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCNAB2, NMACH, CNAB2, SLOPE )
C
CF0(3) = -CN0
CNALP = CNA + CNAB2*BETAS
CNBET = CNAB2*ALPHA*BETA
CPALP(3) = -CNALP
CPBET(3) = -CNBET
C
C PITCH MOMENT COEFFICIENT
C
CALL INTRP1 ( XMACH, TMACH, TCLM0, NMACH, CLM0, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCLMA, NMACH, CLMA, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCMAB2, NMACH, CLMAB2, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCLM0, NMACH, CLM0, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCLMQA, NMACH, CLMQA, SLOPE )
C
CM0(2) = CLM0
CLMALP = CLMA + CLMAB2*BETAS
CLMBET = (CLMAB2*ALPHA + CLMB2)*BETA
CLMQ = CLM0 + CLMQA*ALPHA
CMALP(2) = CLMALP
CMBET(2) = CLMBET
CMQ(2,2) = CLMQ
C
C SIDE FORCE COEFFICIENT
C
CALL INTRP1 ( XMACH, TMACH, TCY0, NMACH, CY0, SLOPE )
CALL INTRP1 ( XMACH, TMACH, TCYB, NMACH, CYB, SLOPE )

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C CALL INTRP1 ( XMACH, TMACH, TCYAB, NMACH, CYAB, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCYAB, NMACH, CYA2B, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCYPO, NMACH, CIP0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCYPA, NMACH, CYPA, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCYR0, NMACH, CYR0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCYRA, NMACH, CYRA, SLOPE )

C CF0(2) = CY0
C CYALP = (CYAB + CYA2B*ALPHA)*BETA + CYP*A*PDO2V + CYRA*RDO2V
C CYBET = CYB + CYAB*ALPHA + CYA2B*ALPHAS
C CYP = CYP0 + CYPA*ALPHA
C CYR = CYR0 + CYRA*ALPHA
C CPALP(2) = CYALP
C CFBET(2) = CYBET
C CFQ(2,1) = CYP
C CFQ(2,3) = CYR

C C YAW MOMENT COEFFICIENT
C CALL INTRP1 ( XMACH, TMACH, TCLN0, NMACH, CLN0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLNB, NMACH, CLNB, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLNAB, NMACH, CLNAB, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCNA2B, NMACH, CLNA2B, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLNP0, NMACH, CLNP0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLNPA, NMACH, CLNPA, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLNRO, NMACH, CLNR0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLNRA, NMACH, CLNRA, SLOPE )

C CM0(3) = CLN0
C CLNBET = CLNB + CLNAB*ALPHA + CLNA2B*ALPHAS
C CLNALP = (CLNAB+CLNA2B*ALPHA)*BETA+CLNPA*PDO2V+CLNRA*RDO2V
C CLNP = CLNP0 + CLNPA*ALPHA
C CLNR = CLNR0 + CLNRA*ALPHA
C CMALP(3) = CLNALP
C CMBET(3) = CLNBET
C CMQ(3,1) = CLNP
C CMQ(3,3) = CLNR

C C ROLL MOMENT COEFFICIENT
C CALL INTRP1 ( XMACH, TMACH, TCLL0, NMACH, CLL0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLLB, NMACH, CLLB, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLLAB, NMACH, CLLAB, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLA2B, NMACH, CLLA2B, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLLP0, NMACH, CLLP0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLLPA, NMACH, CLLPA, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLLR0, NMACH, CLLR0, SLOPE )
C CALL INTRP1 ( XMACH, TMACH, TCLLRA, NMACH, CLLRA, SLOPE )

C CM0(1) = CLL0
C CLLBET = CLLB + CLLAB*ALPHA + CLLA2B*ALPHAS
C CLLALP = (CLLAB+CLLA2B*ALPHA)*BETA+CLLPA*PDO2V+CLLRA*RDO2V
C CLLP = CLLP0 + CLLPA*ALPHA
C CLLR = CLLR0 + CLLRA*ALPHA
C CMALP(1) = CLLALP

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C      CMQBET(1) = CLLBET
C      CMQ(1,1) = CLLP
C      CMQ(1,3) = CLLR
C
C      ELSE
C
C      IF ( XMACH.LT.4.5 ) XMACH=4.5
C
C      AXIAL FORCE COEFFICIENT
C
C      CALL INTRP1 ( XMACH, TMACH2, TCA20, NMACH2, CA20, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCA2A, NMACH2, CA2A, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCA2A2, NMACH2, CA2A2, SLOPE )
C
C      CF0(1) = -CA20
C      CAALP = CA2A + CA2A2*ALPHA
C      CFALP(1) = -CAALP
C
C      NORMAL FORCE COEFFICIENT
C
C      CALL INTRP1 ( XMACH, TMACH2, TCN20, NMACH2, CN20, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCN2A, NMACH2, CN2A, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCN2A2, NMACH2, CN2A2, SLOPE )
C
C      CF0(3) = -CN20
C      CNALP = CN2A + CN2A2*ALPHA
C      CFALP(3) = -CNALP
C
C      PITCH MOMENT COEFFICIENT
C
C      CALL INTRP1 ( XMACH, TMACH2, TCLM20, NMACH2, CLM20, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCLM2A, NMACH2, CLM2A, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCM2A2, NMACH2, CLM2A2, SLOPE )
C
C      CLM0(2) = CLM20
C      CLMALP = CLM2A + CLM2A2*ALPHA
C      CMALP(2) = CLMALP
C      CMQ(2,2) = CLMQ20
C
C      SIDE FORCE COEFFICIENT
C
C      CALL INTRP1 ( XMACH, TMACH2, TCY20, NMACH2, CY20, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCY2B, NMACH2, CY2B, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TCY2AB, NMACH2, CY2AB, SLOPE )
C      CALL INTRP1 ( XMACH, TMACH2, TY2A2B, NMACH2, CY2A2B, SLOPE )
C
C      CF0(2) = CY20
C      CYALP = (CY2AB + CY2A2B*ALPHA)*BETA
C      CYBET = CY2B + CY2AB*ALPHA + CY2A2B*ALPHAS
C      CFALP(2) = CYALP
C      CFBET(2) = CYBET
C
C      YAW MOMENT COEFFICIENT
C
C      CALL INTRP1 ( XMACH, TMACH2, TCLN20, NMACH2, CLN20, SLOPE )

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CALL INTRP1 ( XMACH, TMACH2, TCLN2B, NMACH2, CLN2B, SLOPE )
CALL INTRP1 ( XMACH, TMACH2, TLN2AB, NMACH2, CLN2AB, SLOPE )
CALL INTRP1 ( XMACH, TMACH2, TN2AB, NMACH2, CN2AB, SLOPE )

CM0(3) = CLN20
CLNBET = CLN2B + CLN2AB*ALPHA + CN2AB*ALPHAS
CLNALP = (CLN2AB + CN2AB*ALPHA)*BETA
CMALP(3) = CLNALP
CMBET(3) = CLNBET
CMQ(3,1) = CLNP20
CMQ(3,3) = CLNR20

ROLL MOMENT COEFFICIENT

CALL INTRP1 ( XMACH, TMACH2, TCLL20, NMACH2, CLL20, SLOPE )
CALL INTRP1 ( XMACH, TMACH2, TCLL2B, NMACH2, CLL2B, SLOPE )
CALL INTRP1 ( XMACH, TMACH2, TCL2AB, NMACH2, CLL2AB, SLOPE )
CALL INTRP1 ( XMACH, TMACH2, TL2AB, NMACH2, CL2AB, SLOPE )

CM0(1) = CLL20
CLLBET = CLL2B + CLL2AB*ALPHA + CL2AB*ALPHAS
CLALP = (CLL2AB + CL2AB*ALPHA)*BETA
CMALP(1) = CLLALP
CMBET(2) = CLLBET
CMQ(1,1) = CLLP20
CMQ(1,3) = CLLR20

END IF

IF ( IAERO.GT.0 ) THEN
  OOTAU = 1./TAUF

  F(41,41) = -OOTAU
  F(42,42) = -OOTAU
  F(43,43) = -OOTAU

  S(41) = 2.*A(41)**2./TAUF
  S(42) = 2.*A(42)**2./TAUF
  S(43) = 2.*A(43)**2./TAUF

  XDOT(41) = -OOTAU*X(41)
  XDOT(42) = -OOTAU*X(42)
  XDOT(43) = -OOTAU*X(43)

  ELSE
  END IF
  RETURN
END

901 FORMAT( 10X, 3E15.8 )

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ROGERS ENGINEERING & ASSOCIATES

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END

C

```

C C DIMENSION TALT(50),TK1(50),TK2(50),TKA(50)
1   ,TKB(50),TDFNB(50),TDFAB(50),TDMMB(50),TQREF(50)
2   ,TFAORB(50)

C C DIMENSION TALT2(30),TQREF2(30),TDFNB2(30),TDFAB2(30),TDMMB2(30)

C C COMMON DER(2700), VAR(2700), TEMP(5400), NDER
C C COMMON / CONST / A(71), S(71), R(12)
C C COMMON / PROPAG / X(71), P(71), T(71)
C C COMMON / DRVMT / XDOT(71), PD(71), T(71)
C C COMMON / LINFMT / F(71,71), NS, NPAR
C C COMMON / PLUME / FPPLUME(3),FPALP(3),FPBET(3),TPALP(3)
1   ,TPBET(3),FPALP(3),TPALP(3),TPDPL(3)
C C COMMON / IPARAM / ISSME,ISRB,IAERO,IPLUME,IWIND,JACB,JRDR
C C COMMON / STAGE / ISTANCE

C C DATA TAUF / 2.E+1 /
C C DATA XKB / 0.0 /

C C CALL ZEROM( FPPLUME, 3, 1 )
C C CALL ZEROM( TPALP, 3, 1 )

C C DATA TALT/.519E3,.250E4,.500E4,.750E4,.100E5,.125E5,.150E5,
1   .175E5,.190E5,.200E5,.210E5,.220E5,.225E5,.230E5,.235E5,
2   .240E5,.250E5,.260E5,.270E5,.280E5,.290E5,.300E5,.320E5,
3   .340E5,.360E5,.380E5,.400E5,.420E5,.440E5,.460E5,.480E5,
4   .500E5,.525E5,.550E5,.575E5,.600E5,.650E5,.700E5,.750E5,
5   .800E5,.850E5,.900E5,.950E5,.100E6,.110E6,.120E6,.130E6,
6   .140E6,.145E6,.160E6/

C C CALL ZEROM( FPPLUME, 3, 1 )
C C CALL ZEROM( TPALP, 3, 1 )

C C DATA TDFNB/.00000E4,-.35620E4,-.682230E4,-.88080E4,-.10264E5,
1   .11058E5,-.11343E5,-.11536E5,-.11219E5,-.10883E5,-.10960E5,
2   .11440E5,-.11978E5,-.12575E5,-.13158E5,-.13634E5,-.14185E5,
3   .15697E5,-.15783E5,-.15289E5,-.14357E5,-.13242E5,-.10722E5,
4   .82690E4,-.64340E4,-.49170E4,-.37280E4,-.28310E4,-.19060E4,
5   .10100E4,-.20000E3,-.56699E3,-.14070E4,-.20430E4,-.25840E4,
6   -.30710E4,-.37330E4,-.40780E4,-.39440E4,-.33340E4,-.26700E4,
7   -.22940E4,-.19850E4,-.17050E4,-.14860E4,-.13190E4,-.11490E4,
8   -.10240E4,-.95899E3,-.76399E3/

C C DATA TDMMB/.00000E6,-.126045E6,-.342060E6,-.442584E6,
1   -.512378E6,-.533795E6,-.537157E6,-.545920E6,-.525332E6,
2   -.502047E6,-.496484E6,-.510283E6,-.536406E6,-.565396E6,
3   -.594163E6,-.617065E6,-.645573E6,-.720716E6,-.732389E6,
4   -.718480E6,-.677641E6,-.617735E6,-.474167E6,-.323480E6,
5   -.190900E6,-.786510E6,-.241000E3,-.415890E5,-.764280E5,
6   -.115649E6,-.156796E6,-.201963E6,-.250782E6,-.307795E6,
7   -.327006E6,-.347164E6,-.350765E6,-.324147E6,-.263832E6,-.203965E6,
8   -.170470E6,-.146288E6,-.127146E6,-.114200E6,-.10350736,-.90160E5,
9   .810620E5,.762830E5,.619770E5/

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```

C   DATA TDFAB/. 0000000E5, .303730E5, .518570E5, .730880E5, .882930E5,
1   .985240E5, .102516E6, .101977E6, .100423E6, .987290E5, .986660E5,
2   .999500E5, .101827E6, .104014E6, .106268E6, .108802E6, .113076E6,
3   .118262E6, .118770E6, .115389E6, .108843E6, .100893E6, .827850E5,
4   .653280E5, .509650E5, .383290E5, .270710E5, .173420E5, .799200E4,
5   .249000E3, -.671899E4, -.124840E5, -.189830E5, -.246200E5,
6   -.299630E5, -.349550E5, -.406320E5, -.426450E5, -.419750E5,
7   -.412530E5, -.399940E5, -.380480E5, -.361740E5, -.347590E5,
8   -.314130E5, -.272020E5, -.249430E5, -.229200E5, -.218610E5,
9   -.186830E5/

```

```
C   DATA TKA/-1.00E-4,-.500E-4,-.100E-3,-.300E-3,-.500E-3,
```

```

1   -.770E-3, -.121E-2, -.217E-2, -.246E-2, -.251E-2, -.111E-2,
2   .290E-2, .178E-2, .328E-2, .479E-2, .627E-2, .814E-2, .815E-2,
3   .729E-2, .743E-2, .763E-2, .664E-2, .319E-2, .130E-2, .147E-2,
4   .231E-2, .284E-2, .312E-2, .299E-2, .286E-2, .273E-2, .260E-2,
5   .246E-2, .233E-2, .219E-2, .205E-2, .178E-2, .150E-2, .137E-2,
6   .125E-2, .112E-2, .100E-2, .970E-3, .950E-3, .6* .900E-3/

```

```
DATA TKB/.100E-4,.500E-4,.100E-3,.500E-3,.900E-3,.920E-3,
1   .160E-2,.280E-2,.308E-2,.307E-2,.242E-2,.177E-2,.183E-2,
2   .189E-2,.195E-2,.201E-2,.267E-2,.365E-2,.331E-2,
3   .206E-2,.144E-2,.187E-2,.250E-2,.285E-2,.306E-2,.314E-2,
4   .312E-2,.299E-2,.286E-2,.273E-2,.260E-2,.246E-2,.233E-2,
5   .219E-2,.205E-2,.205E-2,.178E-2,.150E-2,.137E-2,.112E-2,
6   .100E-2,.970E-3,.950E-3,.6* .900E-3/

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```

C   DATA TK1/4*0.0,-.14004E0,-.22038E0,-.18579E0,-.19561E0,
1   -.11937E0,-.39090E0,-.39880E-1,-.42710E-1,-.24110E-1,
2   -.55200E-2,.42030E-1,.102260E0,.24528E0,-.21800E-1,.15058E0,
3   .32297E0,.49535E0,.66774E0,.83920E0,.10106E1,.84838E0,
4   .68609E0,.62891E0,.57173E0,.70384E0,.63939E0,.71203E0,
5   .77934E0,.77717E0,.77500E0,.76750E0,.76000E0,.74299E0,
6   .73860E0,12* .73860E0/

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```

C   DATA TK2/4*0.0,.58160E-1,.88780E-1,.73170E-1,.37260E-1,
1   -.17880E-1,-.62020E-1,-.11063E0,-.24138E0,-.37350E0,-.50562E0,
2   -.67265E0,-.82207E0,-.99600E0,-.70858E0,-.96743E0,-.12263E1,
3   -.148512E1,-.174396E1,-.180346E1,-.186296E1,-.144259E1,
4   -.102222E1,-.636110E0,-.250000E0,-.140000E0,21*0.0/

```

```

C   DATA TFAORB/.00000E0,.922779E4,.14086E5,.18148E5,.21268E5,
1   .24541E5,.24972E5,.24485E5,.24021E5,.24516E5,.25873E5,
2   .27014E5,.282280E5,.29500E5,.30517E5,.31623E5,.34768E5,
3   .34683E5,.33276E5,.31142E5,.28983E5,.24395E5,.20319E5,
4   .20319E5,.17978E5,.16137E5,.14370E5,.12389E5,.10069E5,
5   .80150E5,.63620E5,.50180E5,.352230E5,.22620E5,.10220E4,
6   -.1690E3,-.2001E4,-.3201E4,-.3634E4,-.3435E4,-.3012E4,
7   -.2758E4,-.2430E4,-.2034E4,-.1652E4,-.1390E4,-.1213E4,
8   -.1054E4,-.9740E3,-.7330E3/

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C
C      DATA TQREF/.000E0,-.890E2,.208E3,.308E3,.390E3,.457E3,.511E3,
1   .556E3,.580E3,.592E3,.603E3,.614E3,.619E3,.622E3,.625E3,
2   .629E3,.635E3,.642E3,.643E3,.645E3,.646E3,.648E3,.648E3,
3   .649E3,.649E3,.649E3,.649E3,.644E3,.639E3,.633E3,.623E3,
4   .623E3,.596E3,.577E3,.555E3,.530E3,.480E3,.430E3,.382E3,
5   .339E3,.301E3,.264E3,.231E3,.201E3,.152E3,.114E3,.840E2,
6   .580E2,.490E2,.330E2/
C
C      DATA TALT2 / .231E3,.201E3,.152E3,.114E3,.840E2,.580E2,
1   1130.E3,135.E3,140.E3,145.E3,150.E3,155.E3,160.E3,165.E3,
2   170.E3,175.E3,180.E3,185.E3,190.E3,195.E3,200.E3,205.E3,
3   210.E3,215.E3,220.E3,225.E3,230.E3,235.E3,240.E3/
C
C      DATA TQREF2 / .231E3,.201E3,.152E3,.114E3,.840E2,.580E2,
1   .490E2,.440E2,.390E2,.330E2,.310E2,.290E2,.270E2,.250E2,
2   .23E2,.20E2,.18E2,.15E2,.12E2,.11E2,.10E2,.9E1,.8E1,.7E1,
3   .5E1,.4E1,.3E1,.2E1,.15E1,.1E1/
C
C      DATA TDFNFB2 / 2392.,2061.,1690.,1348.,992.,674.,419.,168.,
1   -69.,-297.,-449.,-579.,-636.,-673.,-652.,-650.,-649.,-626.,
2   -579.,-534.,-523.,-489.,-463.,-446.,-460.,-5*-492./
C
C      DATA TDFA2 / 12029.,10623.,8703.,7135.,5589.,4186.,2961.,
1   1879.,866.,-49.,-813.,-1505.,-2015.,-2436.,-2625.,-2731.,
2   -2685.,-2441.,-2126.,-1783.,-1590.,-1350.,-1150.,-1000.,
3   -940.,5*-900./
C
C      DATA TDMMB2 / -259998.,-224221.,-182865.,-146624.,-106960.,
1   -73303.,-44649.,-18269.,8290.,32311.,48200.,62987.,71038.,
2   73111.,70875.,70679.,70222.,67988.,63584.,58081.,56525.,
3   9*53081./
C
C      DATA NALT, NALT2 / 50, 30 /
C
C      DPL = 1.09 - PL
C      DPLS = DPL*DPL
C      BETAS = BETA*BETA
C
C      ALT = ALT
C      IF( (ALT.LT.520.) OR. (ALT.GT.240000.) ) THEN
C          CALL ZEROM( FPLUME, 3, 1 )
C          CALL ZEROM( TPLUME, 3, 1 )
C          CALL ZEROM( FPALP, 3, 1 )
C          CALL ZEROM( FPBET, 3, 1 )
C          CALL ZEROM( FPALT, 3, 1 )
C          CALL ZEROM( FPDPL, 3, 1 )
C          CALL ZEROM( TPALP, 3, 1 )
C          CALL ZEROM( TPBET, 3, 1 )

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CALL ZEROM( TPALT, 3, 1 )
CALL ZEROM( TPDPL, 3, 1 )
ELSE
C IF ( IStage.eq.1 ) THEN
C CALL INTRP1 ( ALTT, TALT, TQREF, NALT, QREF, PQRFH )
C CALL INTRP1 ( ALTT, TALT, TK1, NALT, XK1, PXK1H )
C CALL INTRP1 ( ALTT, TALT, TK2, NALT, XK2, PXK2H )
C CALL INTRP1 ( ALTT, TALT, TKA, NALT, XKA, PXKAH )
C CALL INTRP1 ( ALTT, TALT, TKB, NALT, XKB, PXKBH )
C CALL INTRP1 ( ALTT, TALT, TDFNB, NALT, DFNB, PFNBH )
C CALL INTRP1 ( ALTT, TALT, TDFAB, NALT, DFAB, PDFABH )
C CALL INTRP1 ( ALTT, TALT, TDMMB, NALT, DMMB, PMMBH )
C CALL INTRP1 ( ALTT, TALT, TFAORB, NALT, FAORB, PFAOH )

C RQ = Q/QREF
C ELSE
C CALL INTRP1 ( ALTT, TALT2, TQREF2, NALT2, QREF, PQRFH )
C CALL INTRP1 ( ALTT, TALT2, TDFNB2, NALT2, DFNB, PFNBH )
C CALL INTRP1 ( ALTT, TALT2, TDFAB2, NALT2, DFAB, PDFABH )
C CALL INTRP1 ( ALTT, TALT2, TDMMB2, NALT2, DMMB, PMMBH )

C FAORB = 0.0
XK1 = 0.0
XK2 = 0.0
XKA = 0.0
XKB = 0.0
PFAOH = 0.0
PXK1H = 0.0
PXK2H = 0.0
PXKAH = 0.0
PXKBH = 0.0
RQ = 1.0
END IF
C
FDP = XK2*DPLS + XK1*DPL + 1.0
FAB = XKB*BETAS + XKA*ALPHA + 1.0
FABHDP = FDP*FAB*RQ
PAPL = XKA*FDP*RQ
PPBET = 2.0*XKB*BETA+FDP*RQ
PFDPH = PXK2H*DPLS + PXK1H*DPL
PFABH = PXKBH*BETAS + PXKAH*ALPHA
PRQH = -Q*PQRFH/(QREF**2)
PABHPH = PFDPH*FAB*RQ+PFABH*RQ+FDP*FAB*PRQH
PPDPL = (2.0*XK2*DPL + XK1)*FAB*RQ
C
FPLUME(1) = -(DFAB - FAORB + FAORB*FDP)*FAB*RQ
FPLUME(2) = 0.0
FPLUME(3) = -DFNB*FABHDP
TPLUME(1) = 0.0

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TPLUME( 2 ) = DMMB * FABHDP
TPLUME( 3 ) = 0 . 0
C
C   FPALP( 1 ) = -DFAB * PPALP
FPALP( 2 ) = 0 . 0
FPALP( 3 ) = -DFNB * PPALP
C
C   PPBET( 1 ) = -DFAB * PPBET
PPBET( 2 ) = 0 . 0
PPBET( 3 ) = -DFNB * PPBET
C
C   TPALP( 1 ) = 0 . 0
TPALP( 2 ) = DMMB * PPALP
TPALP( 3 ) = 0 . 0
C
C   TPBET( 1 ) = 0 . 0
TPBET( 2 ) = DMMB * PPBET
TPBET( 3 ) = 0 . 0
C
C   FPALT( 1 ) = -( PFDABH - PFAOH + PFAOB * FDP + FAORB * PFDPH ) * FAB * RQ
1      -( DFAB - FAORB + FAOB * FDP ) * PFABH * RQ
2      -( DFAB - FAORB + FAOB * FDP ) * FAB * PRQH
FPALT( 2 ) = 0 . 0
FPALT( 3 ) = -PFNBH * FABHDP - DFNB * PAHHPH
C
C   TPALT( 1 ) = 0 . 0
TPALT( 2 ) = PMMBH * FABHDP + DMMB * PAHHPH
TPALT( 3 ) = 0 . 0
C
C   FPDPL( 1 ) = -DFAB * PPDPL
FPDPL( 2 ) = 0 . 0
FPDPL( 3 ) = -DFNB * PPDPL
C
C   TPDPL( 1 ) = 0 . 0
TPDPL( 2 ) = DMMB * PPDPL
TPDPL( 3 ) = 0 . 0
END IF
C
C   IF( IPLUME . GT. 0 ) THEN
C
C     OOTAUF = 1 ./TAUF
C
C     F( 44 , 44 ) = -OOTAUF
F( 45 , 45 ) = -OOTAUF
F( 46 , 46 ) = -OOTAUF
C
C     S( 44 ) = 2 . * A( 44 ) ** 2 /TAUF
S( 45 ) = 2 . * A( 45 ) ** 2 /TAUF
S( 46 ) = 2 . * A( 46 ) ** 2 /TAUF
C
C     XDOT( 44 ) = -OOTAUF * X( 44 )
XDOT( 45 ) = -OOTAUF * X( 45 )
XDOT( 46 ) = -OOTAUF * X( 46 )
C
C     FPLUME( 1 ) = FPLUME( 1 ) + X( 44 )

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PPLUME(2) = FPLUME(2) + X(45)
PPLUME(3) = FPLUME(3) + X(46)
C
ELSE
END IF
C
RETURN
C
FORMAT( 5X, 3E15.8 )
C
END
```

SUBROUTINE NMASS

```

C   SUBROUTINE NMASS PROPERTIES FOR MATED VEHICLE
C
C   DIMENSION DELWT(27),TIX(27),TIY(27),TIZ(27),TIXY(27),
C   1   TIZZ(27),TIYZ(27),TXCG(27),TYCG(27),TZCG(27),
C   2   , RCGF0FS(3)
C
C   DIMENSION WEIGHT(21),DELTWT(21),AIXX(21),AIYY(21),
C   1   AIZZ(21),AIXY(21),AIXZ(21),AIYZ(21)
C   2   ,DELTW2(21),AXCG(21),AYCG(21),AZCG(21)
C
C   COMMON DER(2700), VAR(2700), TEMP(5400), NDER
C   COMMON / CONST / A(71), S(71), R(12)
C   COMMON / IPROPR / XMASSI, XMASS2
C   COMMON / PROPAG / X(71), P(71,71)
C   COMMON / DRVITV / XDOT(71), PD(71,71)
C   COMMON / LINFMT / F(71,71), NS, NPAR
C   COMMON / PROPER / XMASS, OMASS, XIMTRX(3,3), XIMATI(3,3), RCG(3)
C   COMMON / IPARAM / ISSME, ISRB, IAERO, IPUME, IWIND, JACB, JRDR
C   COMMON / STAGE / ISTAGE
C
C   DATA DELWT/,0000000E0, -1240190E6, -2562150E6, -3902000E6,
C   1   -5254230E6, -65955580E6, -7858090E6, -9053790E6, -1017844E7,
C   2   -1126465E7, -123233E7, -1336714E7, -1414331E7, -1554804E7,
C   3   -1667689E7, -1781976E7, -1896941E7, -2008500E7, -2114813E7,
C   4   -2116022E7, -2312411E7, -2401764E7, -2486219E7, -2554876E7,
C   5   -2590745E7, -2612162E7, -3000000E7/
C
C   DATA TIZ/,34571177E9, .33717742E9, .32783875E9, .31822454E9,
C   1   -30834637E9, -29833384E9, -28865425E9, -27925903E9, -27026107E9,
C   2   -215340389E9, -252475448E9, -24366268E9, -2251537E9, -22514319E9,
C   3   -21554077E9, -20585032E9, -19625134E9, -18703819E9, -17834035E9,
C   4   -17039781E9, -16305341E9, -15644651E9, -15081833E9, -14654725E9,
C   5   -144444865E9, -14309413E9, -14252396E9/
C
C   DATA TIY/.31533244E9, .30825736E9, .30048762E9, .29246577E9,
C   1   -28419591E9, -275777624E9, -26757729E9, -25957609E9, -25190968E9,
C   2   -24426837E9, -23664011E9, -22903716E9, -22111858E9, -21301242E9,
C   3   -20470844E9, -19633535E9, -18805845E9, -18011987E9, -17262489E9,
C   4   -16581405E9, -15953335E9, -15391125E9, -14917163E9, -14559313E9,
C   5   -14375563E9, -14247118E9, -14190717E9/
C
C   DATA TIX/-43565352E8, -42035072E8, -40384680E8, -38708230E8,
C   1   -37013454E8, -35333184E8, -33766354E8, -32283937E8, -30866762E8,
C   2   -29504164E8, -28182811E8, -26890217E8, -25573799E8, -2421493E8,
C   3   -22813373E8, -21385839E8, -19943183E8, -18545048E8, -17219038E8,
C   4   -15960817E8, -1476943E8, -13656280E8, -12645017E8, -11850270E8,
C   5   -11541629E8, -11448761E8, -11434923E8/
C
C   DATA TIYX/-1109000E4, -20231000E5, -3311730005, -44269000E5,
C   1   -53301000E5, -60838000E5, -8105000E4, -3177600E5, -5693800E5,
C   2   -6097900E5, -8345100E5, -7652300E5, -7268600E5, -6996800E5,
C   3   -7753200E5, -8290800E5, -5791700E5, -4125200E5, -5736800E5,
C   4   -709200E5, -6496600E5, -5387100E5, -4373700E5, -8698000E4,
C   5   -2583200E5, -34847000E5, -36875000E5/
C
C   DATA TIXZ/-6716835E7, -6723358E7, -6736725E7, -6760808E7,
C   1   -6796678E7, -6843763E7, -6901428E7, -6984498E7, -7094909E7,
C   2   -7224324E7, -7379288E7, -7537877E7, -7702677E7, -7884695E7,
C   3   -8087421E7, -8309431E7, -8549404E7, -8792555E7, -9031727E7,
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C C DATA TXCG/- .36748E2,- .36721E2,- .3666E2,- .3655E2,
 1 - .3638499E2,- .3616700E2,- .3590199E2,- .3551599E2,
 2 - .3498999E2,- .34384999E2,- .32944999E2,
 3 - .321890E2,- .313530E2,- .303990E2,- .293420E2,- .2821500E2,
 4 - .270740E2,- .259490E2,- .248780E2,- .23844000E2,- .22889000E2,
 5 - .220640E2,- .215280E2,- .215690E2,- .2182700E2,- .21996000E2/
 DATA TYCG/- .2167E-1, .2084E-1, .199E-1, .180600E-1, .172800E-1,
 1 .177300E-1, .168900E-1, .173100E-1, .180800E-1, .172800E-1,
 2 .164000E-1, .151600E-1, .133700E-1, .108800E-1, .819999E-2,
 3 .578999E-2, .362000E-2, .201000E-2, .220999E-2, .256000E-2,
 4 .173000E-2, .192000E-2, .404999E-2, .546999E-2, .256300E-1,
 5 .350199E-1, .406599E-1, .415699E-1/

C C DATA TZCG/- .15623E1,- .15623E1,- .16109E1,- .16634E1,
 1 - .172000E1,- .1780200E1,- .1840900E1,- .1902100E1,- .1962900E1,
 2 - .2025899E1,- .2092199E1,- .2162099E1,- .2238999E1,- .2323899E1,
 3 - .2416299E1,- .2517400E1,- .2629299E1,- .2747899E1,- .2871000E1,
 4 - .2999799E1,- .3132899E1,- .3269099E1,- .3405500E1,- .3526500E1,
 5 - .3593100E1,- .3634099E1,- .3651100E1/

SECOND STAGE MASS PROPERTIES

C C DATA WEIGHT/- .1502336E7, .1467900E7, .1402928E7, .1337955E7,
 1 .1272982E7, .1208009E7, .1143036E7, .1078064E7, .1013091E7,
 2 .9481180E6, .8831450E6, .8181720E6, .7531990E6, .6882770E6,
 3 .6232540E6, .558210E6, .4933080E6, .4325670E6, .3792600E6,
 4 .3380360E6, .3378410E6/
 DATA DELTWT/0 0, .344360E5, .994080E5, .164381E6, .229354E6,
 1 .294327E6, .359300E6, .424272E6, .489245E6, .554218E6, .619191E6,
 2 .684164E6, .749137E6, .814109E6, .879082E6, .944055E6, .1009028E7,
 3 .1069769E7, .1123076E7, .1164300E7, .1164495E7/
 DATA AIXX/- .6385328E7, .6361136E7, .6312001E7, .62257807E7,
 1 .619557E7, .6133434E7, .6060237E7, .5977493E7, .588223E7,
 2 .5781466E7, .5659620E7, .5516285E7, .5352096E7, .5516285E7,
 3 .4916627E7, .4612541E7, .4255102E7, .3831761E7, .3322381E7,
 4 .2907861E7, .290698E7/
 DATA AIVY/.112565130E9, .111091340E9, .108383980E9, .105701360E9,
 1 .102924850E9, .100047310E9, .971172750E8, .940918410E8,
 2 .909411020E8, .876503060E8, .841533930E8, .804180780E8,
 3 .765008070E8, .723613170E8, .675720440E8, .62207900E8,
 4 .5666112810E8, .507625200E8, .444636860E8, .399201570E8,
 5 .399081290E8/
 DATA AIZZ/.108275840E9, .106826230E9, .104167990E9,
 1 .101539550E9, .988222770E8, .960098470E8, .931529870E8,
 2 .902102710E8, .871517780E8, .839647140E8, .805796140E8,
 3 .769975940E8, .732444780E8, .692959140E8, .647510930E8,

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4 .596902230E8, .544517600E8, .490261270E8, .432367370E8,
5 .390926310E8, .390822210E8/
DATA AIXY/.71683E5, .70499E5, .67073E5, .62141E5, .57624E5,
1 .53543E5, .48724E5, .43058E5, .38199E5, .34207E5, .26927E5,
2 .16781E5, .93040E4, .48090E4, .-1171E5, .-32714E5, .-36809E5,
3 .-37000E5, .-56732E5, .-26755E5, .-26414E5/
DATA AIXZ/-12700109E8, .-12546131E8, .-12248261E8, .-11939382E8,
1 .-11618950E8, .-11285010E8, .-10930293E8, .-10550928E8,
2 .-10149881E8, .-97224580E7, .-92464110E7, .-87138290E7,
3 .-81352500E7, .-74966560E7, .-67126220E7, .-57799210E7,
4 .-47462130E7, .-35800620E7, .-22568430E7, .-14736020E7,
5 .-14732390E7/
DATA AIZY/.20592E5, .20427E5, .19886E5, .19038E5, .18223E5,
1 .17447E5, .16478E5, .15280E5, .14175E5, .13181E5, .11403E5,
2 .88610E4, .67580E4, .52080E4, .52800E3, .-56966E4, .-78988E4,
3 .-9114E4, .-16078E5, .-10170E5, .-10074E5/
C
DATA DELTW2/0.0, .38834E5, .101257E6, .163669E6, .226072E6,
1 .288467E6, .350857E6, .413243E6, .475626E6, .538008E6,
2 .600388E6, .662769E6, .725150E6, .787532E6, .849916E6,
3 .912299E6, .974685E6, .1036935E7, .1093997E6, .1144084E7,
4 .1165805E7/
DATA AXCG/-1.0733E2, -.11539E2, -.12862E2, -.14228E2, -.15646E2,
1 .-17124E2, .-18679E2, .-2033E2, .-23941E2,
2 .-25956E2, .-28201E2, .-30652E2, .-33356E2, .-36403E2,
3 .-4017E2, .-4444E2, .-49406E2, .-55234E2, .-61756E2,
4 .-63833E2/
DATA AYCG/.563E-2, .572E-2, .598E-2, .637E-2, .675E-2,
1 .712E-2, .754E-2, .810E-2, .862E-2, .910E-2,
2 .969E-2, .1091E-1, .11964E0, .12804E0, .13523E0,
3 .17088E0, .19165E0, .19156E0, .21512E0, .26286E0,
4 .11459E0/
DATA AZCG/-45599E1, .-46809E1, .-489E1, .-51192E1, .-53698E1,
1 .-56451E1, .-5951E1, .-62946E1, .-66777E1, .-71079E1,
2 .-75988E1, .-81747E1, .-88353E1, .-96026E1, .-10511E2,
3 .-11677E2, .-130649E2, .-147601E2, .-168204E2, .-192242E2,
4 .-200905E2/
C
DATA NNMSS, NMASS2 / 27, 21 /
C
C IF ( 1STAGE.EQ.1 ) THEN
C
XMASS = (XMASS1 - OMASS) /32.174
C
C CALL INTRP1 ( OMASS, DELWT, TIX, NNMSS, XIX, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TIY, NNMSS, YIX, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TIZ, NNMSS, ZIX, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TIXY, NNMSS, PIXY, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TIXZ, NNMSS, PIXZ, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TIYZ, NNMSS, PIYZ, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TXCG, NNMSS, XCG, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TYCG, NNMSS, YCG, SLOPE )
C CALL INTRP1 ( OMASS, DELWT, TZCG, NNMSS, ZCG, SLOPE )
C
C ELSE
C

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C XMASS = (XMASS2 - OMASS)/32.174
C
C CALL INTRP1 ( OMASS, DELTW1, AIXX, NMASS2, XIX, SLOPE )
C CALL INTRP1 ( OMASS, DELTW1, AIXY, NMASS2, YIX, SLOPE )
C CALL INTRP1 ( OMASS, DELTW1, AIZZ, NMASS2, ZIZ, SLOPE )
C CALL INTRP1 ( OMASS, DELTW1, AIXY, NMASS2, PIXY, SLOPE )
C CALL INTRP1 ( OMASS, DELTW1, AIXZ, NMASS2, PIXZ, SLOPE )
C CALL INTRP1 ( OMASS, DELTW1, AIZY, NMASS2, PIYZ, SLOPE )
C CALL INTRP1 ( OMASS, DELTW1, AXCG, NMASS2, XCG, SLOPE )
C CALL INTRP1 ( OMASS, DELTW2, AYCG, NMASS2, YCG, SLOPE )
C CALL INTRP1 ( OMASS, DELTW2, AZCG, NMASS2, ZCG, SLOPE )
C
C END IF
C
C XIMTRX(1,1) = XIX
C XIMTRX(2,2) = YIX
C XIMTRX(3,3) = ZIZ
C XIMTRX(1,2) = -PIXY
C XIMTRX(2,1) = XIMTRX(1,2)
C XIMTRX(1,3) = -PIXZ
C XIMTRX(3,1) = XIMTRX(1,3)
C XIMTRX(2,3) = -PIYX
C XIMTRX(3,2) = XIMTRX(2,3)
C
C CALL INV3X3 ( XIMTRX, XIMAT1 )
C
C RCG(1) = XCG
C RCG(2) = YCG
C RCG(3) = ZCG
C
C RETURN
C
C 901 FORMAT( 5X, 3E15.8 )
C
C END

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SUBROUTINE AXCBIQ ( Q, V, P )
DIMENSION Q(4), V(3), P(3,4)

C   P(1,1) = Q(1)*V(1) - Q(4)*V(2) + Q(3)*V(3)
C   P(2,1) = Q(4)*V(1) + Q(1)*V(2) - Q(2)*V(3)
C   P(3,1) = -Q(3)*V(1) + Q(2)*V(2) + Q(1)*V(3)

C   P(1,2) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
C   P(2,2) = Q(3)*V(1) - Q(2)*V(2) - Q(1)*V(3)
C   P(3,2) = -Q(4)*V(1) + Q(1)*V(2) - Q(2)*V(3)

C   P(1,3) = -Q(3)*V(1) + Q(2)*V(2) + Q(1)*V(3)
C   P(2,3) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
C   P(3,3) = -Q(1)*V(1) + Q(4)*V(2) - Q(3)*V(3)

C   P(1,4) = -Q(4)*V(1) - Q(1)*V(2) + Q(2)*V(3)
C   P(2,4) = Q(1)*V(1) - Q(4)*V(2) + Q(3)*V(3)
C   P(3,4) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)

C   CALL SMLT( 2.0, P, P, 3, 4 )

C   RETURN
END
SUBROUTINE AUXVAB

C   DIMENSION VEC(3),VEC2(3),TMP(3,3)

C   COMMON / VARIAB / VR(3), VWGRAD(3)
C   COMMON / TMAT / CBI(3,3), CIB(3,3), CLLB(3,3), CEPBRI(3,3)
C   COMMON / PARTLA / PVMVB(3), PAVB(3), PBVB(3), PVMH, PAH, PBH
1      , PVMW(3), PAVW(3), PBW(3)

C   DATA CRAD / 57.295779 /

C   VMAGS = VR(1)*VR(1) + VR(2)*VR(2) + VR(3)*VR(3)
IF( VMAGS.LT.1.0 ) VMAGS = 1.0
VMAG = SQRT( VMAGS )

C   VMAGQ = VMAGS*VMAG

C   DO 10 I = 1, 3
PVMVB(I) = VR(I)/VMAG
CONTINUE
10

C   VR13S = VMAGS - VR(2)*VR(2)
IF( VR13S.LT.1.0 ) VR13S = 1.0
VR13 = SQRT( VR13S )

C   PAVB(1) = -VR(3)/VR13S
PAVB(2) = 0.0
PAVB(3) = VR(1)/VR13S
CALL SMLT( CRAD, PAVB, PAVB, 3, 1 )

C   PBVB(1) = -VR(1)*VR(2)/(VMAGS*VR13)
PBVB(2) = VR13/VMAGS

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PBVB(3) = -VR(2)*VR(3)/(VMAG*VR13)
CALL SMLT( CRAD, PBVB, PBVB, 3, 1 )
C
CALL MULT( CLLB, VGRAD, VEC, 3, 3, 1 )
CALL SMLT( -1.0, VEC, VEC, 3, 1 )
CALL INNER( PVMVB, VEC, PVMH, 3 )
CALL INNER( PAVB, VEC, PAH, 3 )
CALL INNER( PBVB, VEC, PBH, 3 )
C
CALL TRANS( CLLB, TMP, 3, 3 )
CALL MULT( TMP, VR, VEC, 3, 3, 1 )
CALL SMLT( -2.0, VEC, PVMW, 3, 1 )
C
DO 20 I = 1, 3
VEC2(I) = VR(1)*CLLB(3,I) - VR(3)*CLLB(1,I)
CONTINUE
20
C
A = -1.0/VR13S
CALL SMLT( A, VEC2, PAVW, 3, 1 )
CALL SMLT( CRAD, PAVW, PAVW, 3, 1 )
C
DO 30 I = 1, 3
VEC2(I) = VMAG*CLLB(2,I) - VR(2)*PVMW(I)/(2.*VMAG)
CONTINUE
30
C
A = -1.0/(VMAG*VR13)
CALL SMLT( A, VEC2, PBWV, 3, 1 )
CALL SMLT( CRAD, PBWV, PBWV, 3, 1 )
C
CONTINUE
100
C
RETURN
END
SUBROUTINE AXCIBQ( Q, V, P )
C
DIMENSION Q(4), V(3), P(3,4)
C
P(1,1) = Q(1)*V(1) + Q(4)*V(2) - Q(3)*V(3)
P(2,1) = -Q(4)*V(1) + Q(1)*V(2) + Q(2)*V(3)
P(3,1) = Q(3)*V(1) - Q(2)*V(2) + Q(1)*V(3)
C
P(1,2) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
P(2,2) = Q(3)*V(1) - Q(2)*V(2) + Q(1)*V(3)
P(3,2) = Q(4)*V(1) - Q(1)*V(2) - Q(2)*V(3)
C
P(1,3) = -Q(3)*V(1) + Q(2)*V(2) - Q(1)*V(3)
P(2,3) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
P(3,3) = Q(1)*V(1) + Q(4)*V(2) - Q(3)*V(3)
C
P(1,4) = -Q(4)*V(1) + Q(1)*V(2) + Q(2)*V(3)
P(2,4) = -Q(1)*V(1) - Q(4)*V(2) + Q(3)*V(3)
P(3,4) = Q(2)*V(1) + Q(3)*V(2) + Q(4)*V(3)
C
CALL SMLT( 2.0, P, P, 3, 4 )
C

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RETURN
END
SUBROUTINE QMTRX( OMEGA, QDMTRX )
C
DIMENSION OMEGA( 3 ), QDMTRX( 4, 4 )
C
QDMTRX( 1, 1 ) = 0.0
QDMTRX( 1, 2 ) = -0.5 * OMEGA( 1 )
QDMTRX( 1, 3 ) = -0.5 * OMEGA( 2 )
QDMTRX( 1, 4 ) = -0.5 * OMEGA( 3 )
QDMTRX( 2, 1 ) = 0.5 * OMEGA( 1 )
QDMTRX( 2, 2 ) = 0.0
QDMTRX( 2, 3 ) = 0.5 * OMEGA( 3 )
QDMTRX( 2, 4 ) = -0.5 * OMEGA( 2 )
QDMTRX( 3, 1 ) = 0.5 * OMEGA( 2 )
QDMTRX( 3, 2 ) = -0.5 * OMEGA( 3 )
QDMTRX( 3, 3 ) = 0.0
QDMTRX( 3, 4 ) = 0.5 * OMEGA( 1 )
QDMTRX( 4, 1 ) = 0.5 * OMEGA( 3 )
QDMTRX( 4, 2 ) = 0.5 * OMEGA( 2 )
QDMTRX( 4, 3 ) = -0.5 * OMEGA( 1 )
QDMTRX( 4, 4 ) = 0.0

C
RETURN
END
SUBROUTINE PQOMEG( Q, P )
C
DIMENSION Q( 4 ), P( 4, 3 )
C
P( 1, 1 ) = -0.5 * Q( 2 )
P( 1, 2 ) = -0.5 * Q( 3 )
P( 1, 3 ) = -0.5 * Q( 4 )
P( 2, 1 ) = 0.5 * Q( 1 )
P( 2, 2 ) = -0.5 * Q( 4 )
P( 2, 3 ) = 0.5 * Q( 3 )
P( 3, 1 ) = 0.5 * Q( 4 )
P( 3, 2 ) = 0.5 * Q( 1 )
P( 3, 3 ) = -0.5 * Q( 2 )
P( 4, 1 ) = -0.5 * Q( 3 )
P( 4, 2 ) = 0.5 * Q( 2 )
P( 4, 3 ) = 0.5 * Q( 1 )

C
RETURN
END
SUBROUTINE AXVABQ
C
DIMENSION VEC1( 4 ), VEC2( 4 ), VEC3( 4 )
C
COMMON / STATES / RI( 3 ), VB( 3 ), Q( 4 ), OMEGA( 3 )
COMMON / VARIAB / VR( 3 ), VW( 3 ), VWGRAD( 3 )
COMMON / PARTLB / PVRQ( 3, 4 ), PVHQ( 4 ), PAQ( 4 ), PBQ( 4 )
C
DATA CRAD / 57.295779 /
C
VMS = VR( 1 )**2 + VR( 2 )**2 + VR( 3 )**2

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C      VM = SQRT(VMS)
C      VR2VMS = VR(2)**2 + VMS
C      VR1R3S = VR(1)**2 + VR(3)**2
C      IF( VR1R3S.LT.1.0 ) VR1R3S = 1.0
C      IF( VR2VMS.LT.1.0 ) VR2VMS = 1.0
C      IF( VM.LT.1.0 ) VM = 1.0

C      CALL AXCIBQ( Q, VM, PVRQ )
C      CALL SMLT( -1.0, PVRQ, PVRQ, 3, 4 )

C      DO 10 I = 1, 4
C      VEC1(I) = PVRQ(1,I)
C      VEC2(I) = PVRQ(2,I)
C      VEC3(I) = PVRQ(3,I)
C      CONTINUE

C      DO 20 I = 1, 4
C      PVMQ(I) = VEC1(I)*VR(1) + VEC2(I)*VR(2) + VEC3(I)*VR(3)
C      PVMQ(I) = 0.5*PVMQ(I)/VM
C      CONTINUE

C      DO 30 I = 1, 4
C      PAQ(I) = VEC3(I)*VR(1) - VEC1(I)*VR(3)
C      PAQ(I) = CRAD*PAQ(I)/VR1R3S
C      CONTINUE

C      DO 40 I = 1, 4
C      PBQ(I) = VEC2(I)*VM - PVMQ(I)*VR(2)
C      PBQ(I) = CRAD*PBQ(I)/VR2VMS
C      CONTINUE

C      DO 40 I = 1, 4
C      CBIMXQ( Q, CBI ) = Q(1)*Q(1) + Q(2)*Q(2) - Q(3)*Q(3) - Q(4)*Q(4)
C      CBI(1,1) = 2.*( Q(2)*Q(3) + Q(1)*Q(4) )
C      CBI(2,1) = 2.*( Q(2)*Q(4) - Q(1)*Q(3) )
C      CBI(3,1) = 2.*( Q(1)*Q(2) + Q(3)*Q(4) )

C      CBIMXQ( Q, CBI ) = 2.*( Q(2)*Q(3) - Q(1)*Q(4) )
C      CBI(1,2) = Q(1)*Q(1) - Q(2)*Q(2) + Q(3)*Q(3) - Q(4)*Q(4)
C      CBI(2,2) = 2.*( Q(1)*Q(2) + Q(3)*Q(4) )
C      CBI(3,2) = Q(1)*Q(1) - Q(2)*Q(2) + Q(3)*Q(4)

C      CBIMXQ( Q, CBI ) = 2.*( Q(2)*Q(4) + Q(1)*Q(3) )
C      CBI(1,3) = 2.*( Q(3)*Q(4) - Q(1)*Q(2) )
C      CBI(2,3) = Q(1)*Q(1) - Q(2)*Q(2) - Q(3)*Q(3) + Q(4)*Q(4)
C      CBI(3,3) = Q(1)*Q(1) - Q(2)*Q(2) - Q(3)*Q(3) + Q(4)*Q(4)

C      RETURN
END
SUBROUTINE CBIMX( THT, CBI )
DIMENSION THT(3), CBI(3,3)
C

```

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```

DATA CRAD / 57.295779 /
C
C   SPHI = SIN( THT(1)/CRAD )
C   CPHI = COS( THT(1)/CRAD )
C   STHT = SIN( THT(2)/CRAD )
C   CHTT = COS( THT(2)/CRAD )
C   SPSI = SIN( THT(3)/CRAD )
C   CPSI = COS( THT(3)/CRAD )

C   CBI(1,1) = CHTT*CPSI
C   CBI(2,1) = CHTT*SPSI
C   CBI(3,1) = -STHT
C   CBI(1,2) = SPHI*SHTT*CPSI - CPHI*SPSI
C   CBI(2,2) = SPHI*SHTT*SPSI + CPHI*CPSI
C   CBI(3,2) = SPHI*CHTT
C   CBI(1,3) = CPHI*SHTT*CPSI + SPHI*SPSI
C   CBI(2,3) = CPHI*SHTT*SPSI - SPHI*CPSI
C   CBI(3,3) = CPHI*CHTT

C   RETURN
END

SUBROUTINE E2QUAT( THT, Q )

C   SUBROUTINE TO CONVERT EULER ANGLES INTO QUATERNIONS REF: PERRY

C   DIMENSION THT(3), AM(3,3), V(3), Q(4)

C   DATA CRAD / 57.295779 /

C   PHI = THT(1)
C   THE = THT(2)
C   PSI = THT(3)

C   CPHI = COS( PHI/CRAD )
C   SPHI = SIN( PHI/CRAD )
C   CHTT = COS( THE/CRAD )
C   STHT = SIN( THE/CRAD )
C   CPSI = COS( PSI/CRAD )
C   SPSI = SIN( PSI/CRAD )

C   AM(1,1) = CPSI*CHTT
C   AM(1,2) = -SPSI*CPHI + CPSI*SHTT*SPHI
C   AM(1,3) = SPSI*SPHI + CPSI*SHTT*CPHI

C   AM(2,1) = SPSI*CHTT
C   AM(2,2) = CPSI*CPHI + SPSI*SHTT*SPHI
C   AM(2,3) = -SPSI*SPHI + SPSI*SHTT*CPHI

C   AM(3,1) = -STHT
C   AM(3,2) = CHTT*SPHI
C   AM(3,3) = CHTT*CPHI

C   IF( (ABS(THE-90.) .LT. 1.) .AND. (ABS(PHI-PSI).LT.1.) ) THEN
C   LOOP TO CONVERSION ( SEE PERRY )

```

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```
C      I = 0
C      T = AM(1,1) + AM(2,2) + AM(3,3)
C
C      DO 10 II = 1, 3
C      IF ( AM(II,II).GT.S ) THEN
C          S = AM(II,II)
C          I = II
C      ELSE
C          I = 0
C      END IF
C
C      10 CONTINUE
C
C      T = SQRT( 1.0 + 2.0*S - T )
C
C      K = 2
C      J = 3
C      N = 1
C
C      20 CONTINUE
C
C      IF ( ( I.EQ.0 ).OR.( N.EQ.I ) ) THEN
C          S = (AM(J,K) - AM(K,J))/T
C          V(N) = S
C      ELSE
C          V(J+K-I) = (AM(J,K) + AM(K,J))/T
C      END IF
C
C      IF ( N - 2 ) 30, 40, 50
C
C      30 CONTINUE
C          K = 3
C          J = 1
C          N = 2
C          GO TO 20
C
C      40 CONTINUE
C          K = 1
C          J = 2
C          N = 3
C          GO TO 20
C
C      50 CONTINUE
C
C      IF ( I.EQ.0 ) THEN
C          S = T
C      ELSE
C          V(I) = T
C      END IF
C
C      IF ( S.GE.0.0 ) T = 0.5
C      IF ( S.LT.0.0 ) T = -0.5
C
C      S = T*S
C      DO 60 II = 1, 3
C          V(II) = T*V(II)
```

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```

60 CONTINUE
      Q(1) = S
      Q(2) = V(1)
      Q(3) = V(2)
      Q(4) = V(3)

C      ELSE
      C          Q(1) = SQRT( (AM(1,1)+AM(2,2)+AM(3,3)+1.0)/4.0 )
      C          Q(4) = (AM(2,1)-AM(1,2))/(4.*Q(1))
      C          Q(3) = (AM(1,3)-AM(3,1))/(4.*Q(1))
      C          Q(2) = (AM(3,2)-AM(2,3))/(4.*Q(1))

C      END IF

C      RETURN
END
SUBROUTINE QUAT2E( Q, THT )
C      DIMENSION Q(4), THT(3)

C      DATA CRAD / 57.295779 /
C
      TPSI = 2.* (Q(2)*Q(3)+Q(1)*Q(4))
      DPSI = Q(1)**2+Q(2)**2-Q(3)**2-Q(4)**2
      STHT = -2.* (Q(2)*Q(4)-Q(3)*Q(1))
      TPHI = 2.* (Q(3)*Q(4)+Q(1)*Q(2))
      DPHI = Q(1)**2+Q(4)**2-Q(2)**2-Q(3)**2

C      THT(1) = CRAD*ATAN2( TPHI, DPHI )
      THT(2) = CRAD*ASIN( STHT )
      THT(3) = CRAD*ATAN2( TPSI, DPSI )

C      RETURN
END
SUBROUTINE AUXRAT( D, O, A )
DIMENSION D(3), O(3), A(3,3)

C      A(1,1) = O(2)*D(2) + O(3)*D(3)
      A(2,1) = O(2)*D(1) - 2.0*O(1)*D(2)
      A(3,1) = O(3)*D(1) - 2.0*O(1)*D(3)

C      A(1,2) = O(1)*D(2) - 2.0*O(2)*D(1)
      A(2,2) = O(1)*D(1) + O(3)*D(3)
      A(3,2) = O(3)*D(2) - 2.0*O(2)*D(3)

C      A(1,3) = O(1)*D(3) - 2.0*O(3)*D(1)
      A(2,3) = O(2)*D(3) - 2.0*O(3)*D(2)
      A(3,3) = O(1)*D(1) + O(2)*D(2)

C      RETURN
END
SUBROUTINE TMATY( YAW, TYAW )
C      DIMENSION TYAW(3,3)

```

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```
C DATA CRAD / 57.295779 /
C   SY = SIN( YAW/CRAD )
C   CX = COS( YAW/CRAD )
C
C   TYAW(1,1) = CY
C   TYAW(1,2) = -SY
C   TYAW(1,3) = 0.0
C   TYAW(2,1) = SY
C   TYAW(2,2) = CX
C   TYAW(2,3) = 0.0
C   TYAW(3,1) = 0.0
C   TYAW(3,2) = 0.0
C   TYAW(3,3) = 1.0
C
C   RETURN
END
SUBROUTINE TMATP( PITCH, TPITCH )
C
C   DIMENSION TPITCH(3,3)
C
C DATA CRAD / 57.295779 /
C
C   SP = SIN( PITCH/CRAD )
C   CP = COS( PITCH/CRAD )
C
C   TPITCH(1,1) = CP
C   TPITCH(1,2) = 0.0
C   TPITCH(1,3) = SP
C   TPITCH(2,1) = 0.0
C   TPITCH(2,2) = 1.0
C   TPITCH(2,3) = 0.0
C   TPITCH(3,1) = -SP
C   TPITCH(3,2) = 0.0
C   TPITCH(3,3) = CP
C
C   RETURN
END
```

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C

```
SUBROUTINE INTRP1 ( VM, TM, TC, NM, C, SLOPE )
DIMENSION TM(1), TC(1)

DO 10 I = 1, NM
  IF ( VM - TM(I) ) 20, 20, 10
10 CONTINUE
  K = NM
20 CONTINUE
  K = I - 1
  IF ( K.EQ.0 ) K = 1
  SLOPE = ( TC(K+1) - TC(K) )/(TM(K+1) - TM(K))
  C = TC(K) + SLOPE*(VM - TM(K))
  RETURN
END
```

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```

C SUBROUTINE CONTRL( TIME, PL )
C
C      DIMENSION GIMWVL(3),GIMPTL(3),GIMWWS(2),GIMPTS(2)
C
1      COMMON / NOZDAT / TTIME(500),TRLD(500),TTLD(500)
2          ,TRRD(500),TRD(500)
3          ,TPL(500),TPL1(500),TYL1(500)
4          ,TPL2(500),TYL2(500)
5          ,TPL3(500),TYL3(500)
6          ,TRATER(500),TRATEP(500),TRATEY(500)
7          ,TROLL(500),TPITCH(500),TYAW(500)
8          ,PTC1,YWC1,PTC2,YWC2,PTC3,YWC3
9          ,PON(2)
10         / R(3),VB(3),Q(4),OMEGA(3)
11         / CBI(3,3),CIB(3,3),CLLB(3,3),CEFBR(3,3)
12         / ITYPE
13         / CCLB1(3,3),CCLB2(3,3),CCLB3(3,3),CCLBA(3,3)
14         ,CCLBB(3,3),PLN,RATEC(3),THTC(3)
15
16         DATA GIMWVL,GIMPTL / 3*0.0, 3*0.0 /
17         DATA GKPY, GKR / 0.1, 0.1 /
18
19         CALL INTRPL( TIME, TTIME, TPL, 500, PL, SLOPE )
20             PLN = PL
21
22         CALL INTRPL( TIME, TTIME, TRATER, 500, RATEC(1), SLOPE )
23         CALL INTRPL( TIME, TTIME, TRATEP, 500, RATEC(2), SLOPE )
24         CALL INTRPL( TIME, TTIME, TRATEY, 500, RATEC(3), SLOPE )
25
26         CALL INTRPL( TIME, TTIME, TROLL, 500, THTC(1), SLOPE )
27         CALL INTRPL( TIME, TTIME, TPITCH, 500, THTC(2), SLOPE )
28         CALL INTRPL( TIME, TTIME, TYAW, 500, THTC(3), SLOPE )
29
30         CALL INTRPL( TIME, TTIME, TPL1, 500, GIMPTL(1), SLOPE )
31         CALL INTRPL( TIME, TTIME, TYL1, 500, GIMWVL(1), SLOPE )
32         CALL INTRPL( TIME, TTIME, TPL2, 500, GIMPTL(2), SLOPE )
33         CALL INTRPL( TIME, TTIME, TYL2, 500, GIMWVL(2), SLOPE )
34         CALL INTRPL( TIME, TTIME, TPL3, 500, GIMPTL(3), SLOPE )
35         CALL INTRPL( TIME, TTIME, TYL3, 500, GIMWVL(3), SLOPE )
36
37         CALL CCLBMX( 1,PTC1,YWC1,GIMWVL(1),GIMPTL(1),PL,CCLB1 )
38         CALL CCLBMX( 2,PTC2,YWC2,GIMWVL(2),GIMPTL(2),PL,CCLB2 )
39         CALL CCLBMX( 3,PTC3,YWC3,GIMWVL(3),GIMPTL(3),PL,CCLB3 )
40
41         CALL INTRPL( TIME, TTIME, TRLD, 500, RL, SLOPE )
42         CALL INTRPL( TIME, TTIME, TTLD, 500, TL, SLOPE )
43         CALL INTRPL( TIME, TTIME, TRRD, 500, RR, SLOPE )
44         CALL INTRPL( TIME, TTIME, TTRD, 500, TR, SLOPE )
45
46         RL = .792*RLD + 0.5*( 1.0 - PON(1)/595. )
47         TL = .792*TLD + 0.5*( 1.0 - PON(1)/595. )
48         RR = .792*RRD + 0.5*( 1.0 - PON(2)/595. )
49         TR = .792*TRD + 0.5*( 1.0 - PON(2)/595. )

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```
C      GIMYWS(1) = -.707*RL - .707*TL
C      GIMPTS(1) = .707*RL - .707*TL
C      GIMYWS(2) = .707*RR + .707*TR
C      GIMPTS(2) = -.707*RR + .707*TR
C
C      IF ( ITYPE ) 10, 10, 20
C      CONTINUE
C
C      DO 15 I = 1, 2
C      GIMYWS(I) = GIMYWS(I) + 0.5*GKPY*OMEGA(3)
C      GIMPTS(I) = GIMPTS(I) + 0.5*GKPY*OMEGA(2)
C      CONTINUE
C
C      GIMPTS(1) = GIMPTS(1) - 0.5*GKR*OMEGA(1)
C      GIMPTS(2) = GIMPTS(2) + 0.5*GKR*OMEGA(1)
C
C      CONTINUE
C
C      CALL CCLBMAX( 4,0,0,0,0,GIMYWS(1),GIMPTS(1),0,0,CCLBA )
C      CALL CCLBMAX( 5,0,0,0,0,GIMYWS(2),GIMPTS(2),0,0,CCLBB )
C
C      RETURN
C
C      SUBROUTINE CCLBMAX( IENG,PTC,YWC,GIMYW,GIMPT,PL,TEMP )
C
C      DIMENSION TY(3,3), TP(3,3), TEMP(3,3)
C
C      DEF = -10.0
C      IF(IENG.LT.2) DEF = -16.0
C      IF(IENG.GT.3) DEF = 0.0
C
C      YAW = YWC*PL + GIMYW
C      PITCH = PTC*PL + DEF + GIMPT
C      CALL TMATP( PITCH, TP )
C      CALL TMATY( YAW, TY )
C      CALL MULT( TP, TY, TEMP, 3, 3, 3 )
C
C      RETURN
C      END
```

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C SUBROUTINE UPDATE

C COMMON DER(2700) , VAR(2700) , TEMP(5400) , NDER
COMMON / NMEASR / NMEAS , IMEAS(5)
COMMON / PREUP / XKM(71) , PKM(71,71)
COMMON / LINFMT / F(71,71) , NS , NPAR

C DO 1500 II = 1 , NMEAS

C K = IMEAS(II)
IF(K.EQ.0) GO TO 1000

C DO 10 I = 1, (NS+NPAR)
XKM(I) = VAR(I+1)

10 CONTINUE

C L = 0
DO 20 I = 1, (NS+NPAR)
DO 20 J = I, (NS+NPAR)
L = L + 1
PKM(I,J) = VAR(NS+NPAR+L+1)
PKM(J,I) = PKM(I,J)

20 CONTINUE

C GO TO (100, 200, 300, 400, 500) K

C 100 CONTINUE

C CALL ACCEL
GO TO 1000

C 200 CONTINUE

C CALL ATTIT
GO TO 1000

C 300 CONTINUE

C CALL SSME
GO TO 1000

C 400 CONTINUE

C CALL RADAR
GO TO 1000

C 500 CONTINUE

C CALL SRB

C 1000 CONTINUE

C DO 1010 I = 1, (NS+NPAR)
VAR(I+1) = XKM(I)

1010 CONTINUE

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```

C      L = 0          (NS+NPAR)
C      DO 1020 I = 1, (NS+NPAR)
C      DO 1020 J = I, (NS+NPAR)
C      L = L + 1
C      VAR(NS+NPAR+L+1) = PKM(I,J)
1020  CONTINUE
C      1500  CONTINUE
C      RETURN
END

SUBROUTINE COV2UD ( U, N )
C      IMPLICIT DOUBLE PRECISION ( A-H, O-Z )
C      DIMENSION U(1)
C
Z = 0.E0
ONE = 1.E0
NONE = 1
C
JJ = N*(N+1)/2
NP2 = N + 2
DO 50 L = 2, N
J = NP2 - L
ALPHA = Z
IF ( U(JJ) .GE. Z ) GO TO 10
WRITE(*, 100) J, U(JJ)
C
U(JJ) = Z
10  IF ( U(JJ) .GT. Z ) ALPHA = ONE/U(JJ)
JJ = JJ - J
KK = 0
KJ = JJ
JM1 = J - 1
DO 40 K = 1, JM1
KJ = KJ + 1
BETA = U(KJ)
U(KJ) = ALPHA*U(KJ)
IJ = JJ
IK = KK
DO 30 I = 1, K
IK = IK + 1
IJ = IJ + 1
U(IK) = U(IK) - BETA*U(IJ)
30  IF ( U(I) .GE. Z ) GO TO 60
40  KK = KK + K
50  CONTINUE
IF ( U(1) .GE. Z ) GO TO 60
C      WRITE(*, 100) NONE, U(1)
U(1) = Z
60  RETURN
C      100 FORMAT ( 1H0, 20X, 8H AT STEP, I4, 16HDIAGONAL ENTRY =,F12.4 )
END

```

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```

C      SUBROUTINE UDMEAS ( U, N, R, A, F, G, ALPHA )
C      IMPLICIT DOUBLE PRECISION ( A-H, O-Z )
C
C      DIMENSION U(1), A(1), F(1), G(1)
C      DOUBLE PRECISION SUM, BETA, GAMMA
C      LOGICAL ITEST
C
C      ZERO = 0.E0
C      ITEST = .FALSE.
C      ONE = 1.E0
C      NP1 = N + 1
C      NP2 = N + 2
C      NTOT = N*NP1/2
C      IF ( ALPHA.LT.ZERO ) GO TO 3
C      SUM = A(NP1)
C      DO 1 J = 1, N
C      1 SUM = SUM - A(J)*U(NTOT+J)
C      U(NTOT+NP1) = SUM
C      ITEST = .TRUE.
C
C      3 JJN = NTOT
C      DO 10 L = 2, N
C          J = NP2 - L
C          JJ = JJN - J
C          SUM = A(J)
C          JM1 = J - 1
C          DO 5 K = 1, JM1
C              SUM = SUM + U(JJ+K)*A(K)
C              F(J) = SUM
C              G(J) = SUM+U(JJN)
C
C      10 JJN = JJ
C          F(1) = A(1)
C          G(1) = U(1)*F(1)
C
C          SUM = R + G(1)*F(1)
C          GAMMA = 0
C          IF ( SUM.GT.ZERO ) GAMMA = ONE/SUM
C          IF ( F(1).NE.ZERO ) U(1) = U(1)*R*GAMMA
C
C          KJ = 2
C          DO 20 J = 2, N
C              BETA = SUM
C              TEMP = G(J)
C              SUM = SUM + TEMP*F(J)
C              P = -F(J)*GAMMA
C              JM1 = J - 1
C              DO 15 K = 1, JM1
C                  S = U(KJ)
C                  U(KJ) = S + P*G(K)
C                  G(K) = G(K) + TEMP*S
C                  KJ = KJ + 1
C
C      15 IF ( TEMP.EQ.ZERO ) GO TO 20
C                  GAMMA = ONE/SUM
C                  U(KJ) = U(KJ)*BETA*GAMMA

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```
20 KJ = KJ + 1
ALPHA = SUM
C
IF ( .NOT. IEST ) RETURN
F(NP1) = U(NTOT+NP1)*GAMMA
DO 30 J = 1, N
  U(NTOT+J) = U(NTOT+J) + G(J)*F(NP1)
C
RETURN
END
SUBROUTINE UD2COV ( UIN, POUT, N )
C
IMPLICIT DOUBLE PRECISION ( A-H, O-Z )
C
DIMENSION UIN(1), POUT(1)
C
POUT(1) = UIN(1)
JJ = 1
DO 20 J = 2, N
JJL = JJ
JJ = JJ + J
POUT(JJ) = UIN(JJ)
S = POUT(JJ)
II = 0
JM1 = J - 1
DO 20 I = 1, JM1
  II = II + I
  ALPHA = S*UIN(JJL+I)
  IK = II
  DO 10 K = I, JM1
    POUT(IK) = POUT(IK) + ALPHA*UIN(JJL+K)
    IK = IK + K
  10   POUT(JJL+I) = ALPHA
  20
C
RETURN
END
```

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```
C      SUBROUTINE NOISE ( SIG, V )
C      DATA II / 0.0 /
C      SUM = 0.0
DO 10 I = 1, 12
RV = RANDOM(II)
SUM = SUM + RV
10 CONTINUE
V = SIG*(SUM - 6.0)

C      RETURN
END
REAL FUNCTION RANDOM(I)
INTEGER I, J, K, M
DATA J, K, M / 5243, 55397, 262139 /
C      I = MOD( I+J + K, M )
C      RANDOM = (REAL(I) + 0.5)/REAL(M)
C      RETURN
END
```

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SUBROUTINE ACCEL

```

C      DIMENSION UNIT(3,3),CBS(3,3),DRS(3),ACCM(3),PAMQ(3,4)
2      'VEC1(3),VEC2(3),VEC3(3),TMP1(3,3),TMP2(3,3),
3      ,PAMO(3,3)

C      COMMON DER(2700), VAR(2700), TMP(5400), NDER
COMMON /TMDAT/ TMAX, HSTEP, TSAMP, TSTART, TSTOP, TRINT
COMMON /PROPAG/ X(71), P(71,71)
COMMON /PREUP/ XKM(71), PKM(71,71)
COMMON /LINEMT/ F(71,71), NS, NPAR
COMMON /LNHMT/ H(35,71), NMEAS
COMMON /ACMEAS/ ACM(3)
COMMON /STATES/ RI(3), VB(3), Q(4), OMEGA(3)
COMMON /PROPER/ XMASS, OMASS, XIMTRX(3,3), XIMATI(3,3), RCG(3)
COMMON /MEPRTL/ PFTMR(3),PFTPC(3),PFTGO(3),PFTGH(3)
COMMON /RBRRTL/ PFT(2),PFA(2),PFCS(2)
COMMON /LAYOUT/ RS(3), RA(3), RT1(3), RT2(3), RT3(3), RT4(3), RT5(3)
COMMON /GIMBAL/ CCLBB1(3,3), CCLBB2(3,3), CCLBB3(3,3), CCLBA(3,3)
1      COMMON /APARTL/ PAMBRI(3,3), PAMBVB(3,3), ACC(3), THRUST(3)
COMMON /PARARO/ PVBDGF(3,3), PWDCF(3,3), PWDCM(3,3)
COMMON /PARPLM/ PVBDFFP(3,3), PWDFP(3,3), PWDTFP(3,3)
COMMON /PARVWX/ PVBDWV(3,3), PWDWV(3,3)
COMMON /CONST/ CONST / A(71), S(71), R(12)
COMMON /TYPE/ ITYPE
COMMON /IPARAM/ ISSME, ISRIB, IAERO, IPULSE, IWIND, JACB, JRDR
COMMON /UDWORK/RG(71),U(2556),PO(2556),SF(2556),SG(71),RESID,COVZ
COMMON /QUPDWK/ TVEC(71), VEC(71)
COMMON /ACMHAT/ ACMHAT(3)

C      DATA UNIT / 1.0, 3*0.0, 1.0, 3*0.0, 1.0 /
DATA GF / 32.174 /
DATA CRAD / 57.295779 /

C      TIME = VAR(1)
CALL ZEROM( H, 35, 71 )
CALL ZEROM( TVEC, 71, 1 )

C      NTS = NS + NPAR
DO 990 IMEAS = 1, 3
DO 10 I = 1, (NS+NPAR)
X(I) = XKM(I)
CONTINUE
10
DO 11 I = 1, 3
VEC3(I) = XKM(I+49)
11 CONTINUE

C      CALL XDVEC
CALL ZDVEC
C      CALL CBIMX ( THTC, CBS )

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```
IF ( TIME - TRINT ) 1020, 1010, 1010
C 1010 CONTINUE
C CALL CBIMXQ ( Q, CBS )
C 1020 CONTINUE
C CALL SUBT ( RS, RCG, DRS, 3, 1 )
C CALL CROSS ( OMEGA, DRS, VEC1 )
C CALL CROSS ( OMEGA, VEC1, VEC2 )
C CALL ADD ( ACC, VEC2, VEC1, 3, 1 )
C CALL MULT ( CBS, VEC1, ACM, 3, 3, 1 )
C CALL ADD ( ACM, VEC3, ACMHAT, 3, 1 )
WRITE(*, 997) (ACMHAT(II), II = 1, 3)
WRITE(*, 997) (ACM(II), II = 1, 3)
C IF ( ITYPE ) 13, 13, 20
C 13 CONTINUE
C DO 15 II = 1, 3
SA = SQRT(R(1))
CALL NOISE ( SA, VA )
ACM(II) = ACMHAT(II) + VA
CONTINUE
15
C WRITE(2,997) (ACM(I), I=1,3)
GO TO 1000
C 20 CONTINUE
C CALL LINFS
C C ACCEL WRT RI
C CALL MULT ( CBS, PAMBRI, TMP2, 3, 3, 3 )
CALL IMBED ( H, 35, 71, TMP2, 3, 3, 1, 1 )
C ACCEL WRT VB
C CALL MULT ( CBS, PAMBVB, TMP2, 3, 3, 3 )
CALL IMBED ( H, 35, 71, TMP2, 3, 3, 1, 4 )
C C ACCEL WRT QUATERNIONS
C CALL AXCBIQ ( Q, VEC1, PAMQ )
C DO 25 I = 1, 3
DO 25 J = 1, 3
TMP1(I,J) = PAMQ(I,J)
CONTINUE
25
C
```

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IF ( TIME - TRINT ) 1040, 1030, 1030
      CONTINUE
1030
      CALL IMBED ( H, 35, 71, TMP1, 3, 3, 1, 7 )
      CONTINUE
      ACCEL WRT OMEGA
      CALL SUBT ( RS, RCG, DRS, 3, 1 )
      CALL AUXRAT ( DRS, OMEGA, PAMO )
      CALL MULT ( CBS, PAMO, TMP2, 3, 3, 3 )
      CRATE CALL IMBED ( H, 35, 71, TMP2, 3, 3, 1, 11 )

      ACCEL WRT SSME1 PARAMETERS
      CALL MULT ( CBS, THRUST, VEC3, 3, 3, 1 )
      DO 30 I = 1, 3
      VEC1(I) = CCLB1(I,1)/XMASS
      CONTINUE
      CALL MULT ( CBS, VEC1, VEC2, 3, 3, 1 )
      H(IMEAS, 14) = VEC3(IMEAS)/(GF*XMASS**2)
      H(IMEAS, 15) = VEC2(IMEAS)*PFTMR(1)
      H(IMEAS, 16) = VEC2(IMEAS)*PFTPC(1)
      H(IMEAS, 17) = VEC2(IMEAS)*PFTGO(1)
      H(IMEAS, 18) = VEC2(IMEAS)*PFTGH(1)
      H(IMEAS, 19) = 0.0
      H(IMEAS, 20) = 0.0
      H(IMEAS, 21) = 0.0
      H(IMEAS, 22) = 0.0

      ACCEL WRT SSME2 PARAMETERS
      DO 50 I = 1, 3
      VEC1(I) = CCLB2(I,1)/XMASS
      CONTINUE
      CALL MULT ( CBS, VEC1, VEC2, 3, 3, 1 )
      H(IMEAS, 23) = VEC3(IMEAS)/(GF*XMASS**2)
      H(IMEAS, 24) = VEC2(IMEAS)*PFTMR(2)
      H(IMEAS, 25) = VEC2(IMEAS)*PFTPC(2)
      H(IMEAS, 26) = VEC2(IMEAS)*PFTGO(2)
      H(IMEAS, 27) = VEC2(IMEAS)*PFTGH(2)
      H(IMEAS, 28) = 0.0
      H(IMEAS, 29) = 0.0
      H(IMEAS, 30) = 0.0
      H(IMEAS, 31) = 0.0

      ACCEL WRT SSME3 PARAMETERS
      DO 70 I = 1, 3
      VEC1(I) = CCLB3(I,1)/XMASS
      CONTINUE
      CALL MULT ( CBS, VEC1, VEC2, 3, 3, 1 )

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C      KSTATE = 61
C      IF ( ISRB.LT.1 ) GO TO 200
C
C      ACCEL WRT SRBA PARAMETERS
C
DO 90 I = 1, 3
  VEC1(I) = CCLBA(I,1)/XMASS
CONTINUE
90   CALL MULT ( CBS, VEC1, VEC2, 3, 3, 1 )
H( IMEAS, KSTATE+1 ) = VEC3(IMEAS)/(GF*XMASS**2)
H( IMEAS, KSTATE+2 ) = VEC2(IMEAS)*PFT(1)
H( IMEAS, KSTATE+3 ) = VEC2(IMEAS)*PFT(2)
H( IMEAS, KSTATE+4 ) = VEC2(IMEAS)*PFA(1)
H( IMEAS, KSTATE+5 ) = 0.0
C
C      ACCEL WRT SRBB PARAMETERS
C
DO 110 I = 1, 3
  VEC1(I) = CCLBB(I,1)/XMASS
CONTINUE
110  CALL MULT ( CBS, VEC1, VEC2, 3, 3, 1 )
H( IMEAS, KSTATE+6 ) = VEC3(IMEAS)/(GF*XMASS**2)
H( IMEAS, KSTATE+7 ) = VEC2(IMEAS)*PFT(2)
H( IMEAS, KSTATE+8 ) = VEC2(IMEAS)*PFA(2)
H( IMEAS, KSTATE+9 ) = VEC2(IMEAS)*PFCS(2)
H( IMEAS, KSTATE+10 ) = 0.0
C
200  CONTINUE
C      KSTATE = 40
CALL LINFA
C
210  CONTINUE
C
C      CALL MULT ( CBS, PVBDCE, TMP1, 3, 3, 3 )
CALL IMBED ( H, 35, 71, TMP1, 3, 3, 1, (KSTATE+1) )
C
KSTATE = KSTATE + 3
C
300  CONTINUE
C
C      IF ( IPLUME ) 400, 400, 310
310  CONTINUE
C

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```

CALL MULT ( CBS, PVBDFF, TMP1, 3, 3, 3 )
CALL IMBED ( H, 35, 71, TMP1, 3, 3, 1, (KSTATE+1) )
C
KSTATE = KSTATE + 3
C
CONTINUE
C
IF( IWIND ) 600, 600, 510
510  CONTINUE
C
CALL MULT ( CBS, PVBDVW, TMP1, 3, 3, 3 )
CALL IMBED ( H, 35, 71, TMP1, 3, 3, 1, (KSTATE+1) )
C
KSTATE = KSTATE + 3
C
600  CONTINUE
C
IF ( JACB ) 700, 700, 610
610  CONTINUE
C
CALL IMBED ( H, 35, 71, UNIT, 3, 3, 1, (KSTATE+1) )
C
700  CONTINUE
C
IF ( ACM(IMEAS) .EQ. 0.0 ) THEN
RESID = 0.0
COVZ = 0.0
CALL ZEROM ( RG, (NS+NPAR), 1 )
ELSE
C
UDU**T FACTORED COVARIANCE UPDATE
C
KJ = 0
DO 940 J = 1, (NS+NPAR)
RG(J) = H(IMEAS,J)
DO 940 K = 1, J
KJ = KJ + 1
U(KJ) = PKM(K,J)
CONTINUE
940
C
CALL COV2UD( U, NTS )
C
RACC = R(1)
ALPHA = -1.0
CALL UDMEAS( U, NTS, RACC, RG, SF, SG, ALPHA )
C
CALL UD2COV( U, PO, NTS )
C
RESID = ACM(IMEAS) - ACMHAT(IMEAS)
COVZ = ALPHA
IF ( ABS(RESID).GT.(6.*SQRT(COVZ)) ) GO TO 980
C
DO 950 J = 1, (NS+NPAR)
XKM(J) = X(J) + (SG(J)/ALPHA)*RESID
950
CONTINUE

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IJ = 0
DO 960 J = 1, (NS+NPAR)
DO 960 I = 1, J
IJ = IJ + 1
PKM(I,J) = PO(IJ)
PKM(J,I) = PKM(I,J)

960      CONTINUE
C
C      IF ( TIME - TRINT ) 1060, 1050, 1050
C 1050  CONTINUE
C
C      DQ1 = XKM(7) - X(7)
C      DQ2 = XKM(8) - X(8)
C      DQ3 = XKM(9) - X(9)
C      DQS = XKM(7)**2 + XKM(8)**2 + XKM(9)**2
C      IF ( DQS.LT.1.0 ) THEN
C      DQ4 = -(XKM(7)*DQ1+XKM(8)*DQ2+XKM(9)*DQ3)/SQRT( 1.0 - DQS )
C      XKM(10) = X(10) + DQ4
C      END IF
C      IF( ABS((DQS+XKM(10)**2)-1.0).GT.1.E-4 ) THEN
C      XKM(7) = X(7)
C      XKM(8) = X(8)
C      XKM(9) = X(9)
C      XKM(10) = X(10)
C      ELSE
C      END IF
C      TVEC(7) = -XKM(7)/X(10)
C      TVEC(8) = -XKM(8)/X(10)
C      TVEC(9) = -XKM(9)/X(10)
C      CALL MULT ( TVEC, PKM, VEC, 1, NTS, NTS )
C      DO 970 I = 1, (NS+NPAR)
C      PKM(10,I) = VEC(I)
C      PKM(I,10) = VEC(I)
C      CONTINUE
C      CALL INNER ( VEC, TVEC, TEMP, NTS )
C      PKM(10,10) = TEMP
C
C 1060  CONTINUE
C
C 980  CONTINUE
C
C      END IF
C
C      CALL OUTPUT
C
C 990  CONTINUE
C
C 1000  CONTINUE
C
C      RETURN
C
C      FORMAT( 3X, 5E15.8 )
C      FORMAT( 7X, 4E15.8 )

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```

C END SUBROUTINE SSME
C
COMMON DER(2700), VAR(2700), PMET(5400), NDER
COMMON / TIMDAT / TMAX, HSTEP, TSAMP, TSTART, TSTOP, TRINT
COMMON / MMEAS / YMSME(6,3)
COMMON / CONST / A(71), S(71), R(12)
COMMON / PROPAG / X(71), P(71,71)
COMMON / PREUP / XKM(71), PKM(71,71)
COMMON / LINFMT / F(71,71), NS, NPAR
COMMON / LINHMT / H(35,71), NMEAS
COMMON / SMMEMA / XLH(6,3)
COMMON / TYPE / ITYPE
COMMON /UDWORK/RG(71),U(2556),PO(2556),SF(2556),SG(71),RESID,COVZ
COMMON / QUPDWK / TVEC(71), VEC(71)

C TIME = VAR(1)
C
NTS = NS + NPAR
C
KMEAS = 6
C
DO 200 IENG = 1, 3
DO 200 JMEAS = 1, 6
C
DO 10 I = 1, (NS+NPAR)
X(I) = XKM(I)
CONTINUE
10
C
CALL NASSME
C
IF ( ITYPE ) 13, 13, 20
CONTINUE
13
C
DO 15 II = 1, 3
DO 15 JJ = 1, 6
SME = SQRT(R(2+JJ))
CALL NOISE ( SME, VSME )
YMSME(JJ,II) = XLH(JJ,II) + VSME
CONTINUE
15
C
DO 17 II = 1, 3
WRITE(2,997) (YMSME(JJ,II), JJ=1,6)
CONTINUE
17
GO TO 300
C
20
CONTINUE
C
KMEAS = KMEAS + 1
C
C UDU*T FACTORED COVARIANCE UPDATE
C
C KJ = 0

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DO 140 J = 1, (NS+NPAR)
RG(J) = H(KMEAS, J)
DO 140 K = 1, J
KJ = KJ + 1
U(KJ) = PKM(K, J)
CONTINUE
C   CALL COVZUD( U, NTS )
C   RSSME = R(2+JMEAS)
ALPHA = -1.0
CALL UDMEAS( U, NTS, RSSME, RG, SF, SG, ALPHA )
C   CALL UD2COV( U, PO, NTS )
C   RESID = YMSME( JMEAS, IENG ) - XLH( JMEAS, IENG )
COVZ = ALPHA
IF ( ABS(RESID).GT.(6.*SQRT(COVZ)) ) GO TO 180
C   DO 150 J = 1, (NS+NPAR)
XKM(J) = X(J) + (SG(J)/ALPHA)*RESID
CONTINUE
150
C   IJ = 0
DO 160 J = 1, (NS+NPAR)
DO 160 I = 1, J
IJ = IJ + 1
PKM(I,J) = PO(IJ)
PKM(J,I) = PKM(I,J)
CONTINUE
160
C   IF ( TIME - TRINT ) 320, 310, 310
C   CONTINUE
310
C   DQ1 = XKM(7) - X(7)
DQ2 = XKM(8) - X(8)
DQ3 = XKM(9) - X(9)
DQS = XKM(7)**2 + XKM(8)**2 + XKM(9)**2
IF ( DQS.LT.1.0 ) THEN
DQ4 = -(XKM(7)*DQ1+XKM(8)*DQ2+XKM(9)*DQ3)/SQRT( 1.0 - DQS )
XKM(10) = X(10) + DQ4
END IF
IF ( ABS((DQS+XKM(10)**2)-1.0).GT.1.E-4 ) THEN
XKM(7) = X(7)
XKM(8) = X(8)
XKM(9) = X(9)
XKM(10) = X(10)
ELSE
END IF
TVEC(7) = -XKM(7)/X(10)
TVEC(8) = -XKM(8)/X(10)
TVEC(9) = -XKM(9)/X(10)
CALL MULT ( TVEC, PKM, VEC, 1, NTS, NTS )
DO 170 I = 1, (NS+NPAR)

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PKM(10,I) = VEC(I)
PKM(I,10) = VEC(I)

170      CONTINUE
        CALL INNER ( VEC, TVEC, TEMP, TEMP, NTS )
        PKM(10,10) = TEMP

C       CONTINUE
320      C     180      CONTINUE
C       CALL OUTPUT
C     200      CONTINUE
C     300      CONTINUE
C       RETURN

C   991      FORMAT( 2X, 2I5 )
995      FORMAT( 3X, 5E15.8 )
997      FORMAT( 5X, 6E15.8 )
998      FORMAT( 7X, 4E15.8 )

C   END      SUBROUTINE SRB

C   COMMON DER(2700), VAR(2700), PMET(5400), NDER
COMMON / TIMDAT / TMAX, HSTEP, TSAMP, TSTART, TSTOP, TRINT
COMMON / GMDATS / GIMYW(2), GIMPT(2)
COMMON / SRMEAS / YMSRB(2)
COMMON / SRBMEA / POHHAT(2)
COMMON / PROPAG / X(71), P(71,71)
COMMON / LINFMT / F(71,71), NS, NPAR
COMMON / LINHMT / H(35,71), NMEAS
COMMON / CONST / A(71), S(71), R(12)
COMMON / PREUP / XKM(71), PKM(71,71)
COMMON / TYPE / ITYPE
COMMON / UDWORK / RG(71), U(2556), PO(2556), SF(2556), SG(71), RESID, COVZ
COMMON / QUPDWK / TVEC(71), VEC(71)

C       TIME = VAR(1)
C       NTS = NS + NPAR
C       KMEAS = 33
C       DO 200 IMTR = 1, 2
C         DO 10 I = 1, (NS+NPAR)
          X(I) = XKM(I)
10      CONTINUE
C
        CALL NASSRB
        WRITE(*, 997) POHHAT(IMTR)
        WRITE(*, 997) YMSRB(IMTR)

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C IF ( ITYPE ) 13, 13, 20
C CONTINUE
C DO 15 II = 1, 2
C   SSRB = SORT(R(112))
C   CALL NOISE ( SSRB, VSRB )
C   YMSRB(II) = P0HAT(II) + VSRB
C
C   WRITE(2,997) YMSRB(II)
C   CONTINUE
C   GO TO 300
C
C   CONTINUE
C   KMEAS = KMEAS + 1
C
C   UDU*T FACTORED COVARIANCE UPDATE
C
C   KJ = 0
C   DO 140 J = 1, (NS+NPAR)
C     RG(J) = H(KMEAS, J)
C     DO 140 K = 1, J
C       KJ = KJ + 1
C       U(KJ) = PKM(K,J)
C
C       CONTINUE
C
C       CALL COV2UD( U, NTS )
C
C       RPOH = R(112)
C       ALPHA = -1.0
C       CALL UDMEAS( U, NTS, RPOH, RG, SF, SG, ALPHA )
C
C       CALL UD2COV( U, PO, NTS )
C
C       RESID = YMSRB(IMTR) - P0HAT(IMTR)
C
C       COVZ = ALPHA
C
C       DO 150 J = 1, (NS+NPAR)
C         XKM(J) = X(J) + (SG(J)/ALPHA)*RESID
C
C       CONTINUE
C
C       IJ = 0
C       DO 160 J = 1, (NS+NPAR)
C         DO 160 I = 1, J
C           IJ = IJ + 1
C           PKM(I,J) = PO(IJ)
C           PKM(J,I) = PKM(I,J)
C
C           CONTINUE
C
C           IF ( TIME - TRINT ) 320, 310, 310
C
C           310 CONTINUE
C
C           DQ1 = XKM(7) - X(7)
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```

DQ2 = XKM(8) - X(8)
DQ3 = XKM(9) - X(9)
DQS = XKM(7)**2 + XKM(8)**2 + XKM(9)**2
IF ( DQS.LT.1.0 ) THEN
DQ4 = -(XKM(7)*DQ1+XKM(8)*DQ2+XKM(9)*DQ3)/SQRT( 1.0 - DQS )
XKM(10) = X(10) + DQ4
END IF
IF( ABS((DQS+XKM(10)**2)-1.0).GT.1.E-4 ) THEN
XKM(7) = X(7)
XKM(8) = X(8)
XKM(9) = X(9)
XKM(10) = X(10)
ELSE
END IF
TVEC(7) = -XKM(7)/X(10)
TVEC(8) = -XKM(8)/X(10)
TVEC(9) = -XKM(9)/X(10)
CALL MULT ( TVEC, PKM, VEC, 1, NTS, NTS )
DO 170 I = 1, (NS+NPAR)
PKM(10,I) = VEC(I)
PKM(I,10) = VEC(I)
CONTINUE
CALL INNER ( VEC, TVEC, TEMP, NTS )
PKM(10,10) = TEMP
C
320 CONTINUE
C
180 CONTINUE
C
CALL OUTPUT
C
200 CONTINUE
C
300 CONTINUE
C
RETURN
C
995 FORMAT( 3X, 5E15.8 )
997 FORMAT( 5X, 3E15.8 )
998 FORMAT( 7X, 4E15.8 )
C
END

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C      SUBROUTINE ADD ( A, B, C, NRA, NCA )
DIMENSION A(NRA,NCA), B(NRA,NCA), C(NRA,NCA)
C
DO 10 J = 1, NRA
DO 10 I = 1, NRA
C(I,J) = A(I,J) + B(I,J)
10 CONTINUE
C
RETURN
END
SUBROUTINE SUBT ( A, B, C, NRA, NCA )
DIMENSION A(NRA,NCA), B(NRA,NCA), C(NRA,NCA)
C
DO 10 J = 1, NRA
DO 10 I = 1, NRA
C(I,J) = A(I,J) - B(I,J)
10 CONTINUE
C
RETURN
END
SUBROUTINE MULT ( A, B, C, NRA, NCA, NCB )
DIMENSION A(NRA,NCA), B(NCA, NCB), C(NRA,NCB)
C
DO 20 J = 1, NCB
DO 20 I = 1, NRA
K = 0
TEMP = 0.0
DO 10 L = 1, NCA
K = K + 1
TEMP = TEMP + A(I,K)*B(K,J)
10 CONTINUE
C(I,J) = TEMP
20 CONTINUE
C
RETURN
END
SUBROUTINE TRANS ( A, B, NRA, NCA )
DIMENSION A(NRA,NCA), B(NCA,NRA)
C
DO 10 I = 1, NRA
DO 10 J = 1, NCA
B(J,I) = A(I,J)
10 CONTINUE
C
RETURN
END
SUBROUTINE SMLT ( C, A, B, NRA, NCA )
DIMENSION A(NRA,NCA), B(NRA,NCA)
C
DO 10 I = 1, NRA
DO 10 J = 1, NCA
B(I,J) = C*A(I,J)
10 CONTINUE
C
RETURN
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END
SUBROUTINE SWITCH ( A, B, NRA, NCA )
DIMENSION A(NRA,NCA), B(NRA,NCA)
C
DO 10 I = 1, NRA
DO 10 J = 1, NCA
B(I,J) = A(I,J)
10 CONTINUE
C
RETURN
END
SUBROUTINE SYMTRK ( A, NS, AS )
DIMENSION A(NS,NS), AS(NS,NS)
C
DO 10 I = 1, NS
DO 10 J = I, NS
AS(I,J) = 0.5*(A(I,J) + A(J,I))
AS(J,I) = AS(I,J)
10 CONTINUE
C
RETURN
END
SUBROUTINE OUTER ( A, B, C, NRA, NCB )
DIMENSION A(NRA), B(NCB), C(NRA,NCB)
C
DO 10 I = 1, NRA
DO 10 J = 1, NCB
C(I,J) = A(I)*B(J)
10 CONTINUE
C
RETURN
END
SUBROUTINE INNER ( A, B, C, NELEM )
DIMENSION A(NELEM), B(NELEM)
C
TEMP = 0.0
C
DO 10 I = 1, NELEM
TEMP = TEMP + A(I)*B(I)
10 CONTINUE
C
C = TEMP
C
RETURN
END
SUBROUTINE SKEW ( A, B )
DIMENSION A(3), B(3,3)
C
B(1,1) = 0.0
B(1,2) = -A(3)
B(1,3) = A(2)
B(2,1) = -B(1,2)
B(2,2) = 0.0
B(2,3) = -A(1)
B(3,1) = -B(1,3)

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      B(3,2) = -B(2,3)
      B(3,3) = 0.0
C      RETURN
END
SUBROUTINE IMBED ( BIG, IM, IN, SUB, M, N, IROW, ICOL )
DIMENSION SUB(1), BIG(1)
C
IF ( (M+IROW-1 .LE. IM) .AND. (N+ICOL-1 .LE. IN) ) GOTO 5
WRITE(6,6000) IM, IN, M, N, IROW, ICOL
STOP
C
      5 IB = ( ICOL - 1 ) * IM + ( IROW - 1 )
      IS = 0
IOFFST = IM - M
C
      DO 20 I = 1, N
      DO 10 J = 1, M
      IB = IB + 1
      IS = IS + 1
      BIG(IB) = SUB(IS)
10    CONTINUE
      IB = IB + IOFFST
20    CONTINUE
C
      RETURN
C
      6000 FORMAT ( 5X, 6I10 )
C
END
SUBROUTINE INV2X2 ( A, AI )
DIMENSION A(2,2), AI(2,2)
C
DET = A(1,1)*A(2,2) - A(1,2)*A(2,1)
C
AI(1,1) = A(2,2)/DET
AI(1,2) = -A(1,2)/DET
AI(2,1) = -A(2,1)/DET
AI(2,2) = A(1,1)/DET
C
      RETURN
END
SUBROUTINE INVNN ( A, N, D, L, M )
DIMENSION A(1), L(1), M(1)
C
      D = 1.0
      NK = -N
      DO 80 K = 1, N
      NK = NK + N
      L(K) = K
      M(K) = K
80    KK = NK + K
      BIGA = A(KK)
      DO 20 J = K, N
      IZ = N*(J-1)

```

```

DO 20 I = K, N
IJ = IZ + I
10 IF ( ABS(BIGA) - ABS(A(IJ)) ) 15, 20, 20
15 BIGA = A(IJ)
L(K) = I
M(K) = J
20 CONTINUE
C
      J = L(K)
      IF ( J - K ) 35, 35, 25
25 KI = K - N
      DO 30 I = 1, N
      KI = KI + N
      HOLD = -A(KI)
      JI = KI - K + J
      A(KI) = A(JI)
      30 A(JI) = HOLD
C
      35 I = M(K)
      IF ( I - K ) 45, 45, 38
38 JP = N*(I - 1)
      DO 40 J = 1, N
      JK = NK + J
      JI = JP + J
      HOLD = -A(JK)
      A(JK) = A(JI)
      40 A(JI) = HOLD
C
      45 IF ( BIGA ) 48, 46, 48
46 D = 0.0
      RETURN
48 DO 55 I = 1, N
      IF ( I - K ) 50, 55, 50
50 IK = NK + I
      A(IK) = A(IK)/(-BIGA)
55 CONTINUE
C
      DO 65 I = 1, N
      IK = NK + I
      HOLD = A(IK)
      IJ = I - N
      DO 65 J = 1, N
      IJ = IJ + N
      IF ( I - K ) 60, 65, 60
      60 IF ( J - K ) 62, 65, 62
      62 KJ = IJ - I + K
      A(IJ) = HOLD*A(KJ) + A(IJ)
      65 CONTINUE
C
      KJ = K - N
      DO 75 J = 1, N
      KJ = KJ + N
      IF ( J - K ) 70, 75, 70
      70 A(KJ) = A(KJ)/BIGA
      75 CONTINUE

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```

C      D = D*BIGA
C      A(KK) = 1.0/BIGA
C      80 CONTINUE
C
C      K = N
C      100 K = K - 1
C      IF ( K ) 150, 150, 105
C      105 I = L(K)
C      IF ( I - K ) 120, 120, 108
C      108 JQ = N*(K - 1)
C      JR = N*(I - 1)
C      DO 110 J = 1, N
C      JK = JQ + J
C      HOLD = A(JK)
C      JI = JR + J
C      A(JK) = -A(JI)
C      110 A(JI) = HOLD
C      120 J = M(K)
C      IF ( J - K ) 100, 100, 125
C      125 KI = K - N
C      DO 130 I = 1, N
C      KI = KI + N
C      HOLD = A(KI)
C      JI = KI - K + J
C      A(KI) = -A(JI)
C      130 A(JI) = HOLD
C      GO TO 100
C      150 RETURN
C      END
C      SUBROUTINE INV3X3( A, AINV )
C      DIMENSION A(3,3), AINV(3,3), B(3,3)
C
C      DET = A(1,1)*A(2,2)*A(3,3) + A(1,2)*A(2,3)*A(3,1)
C      1   + A(1,3)*A(2,1)*A(3,2) - A(1,3)*A(2,2)*A(3,1)
C      2   - A(1,1)*A(2,3)*A(3,2) - A(1,2)*A(2,1)*A(3,3)
C
C      B(1,1) = A(2,2)*A(3,3) - A(2,3)*A(3,2)
C      B(1,2) = A(1,3)*A(3,2) - A(1,2)*A(3,3)
C      B(1,3) = A(1,2)*A(2,3) - A(2,2)*A(1,3)
C      B(2,1) = A(3,1)*A(2,3) - A(2,1)*A(3,3)
C      B(2,2) = A(1,1)*A(3,3) - A(3,1)*A(1,3)
C      B(2,3) = A(2,1)*A(1,3) - A(1,1)*A(2,3)
C      B(3,1) = A(2,1)*A(3,2) - A(3,1)*A(2,2)
C      B(3,2) = A(3,1)*A(1,2) - A(1,1)*A(3,2)
C      B(3,3) = A(1,1)*A(2,2) - A(1,2)*A(2,1)
C
C      DET = 1.0/DET
C
C      DO 100 I = 1, 3
C      DO 100 J = 1, 3
C      AINV(I,J) = DET*B(I,J)
C      CONTINUE
C      100
C

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```
RETURN
END
SUBROUTINE ZEROM( A, NROW, NCOL )
DIMENSION A(NROW,NCOL)
C
DO 10 I = 1, NROW
DO 10 J = 1, NCOL
A(I,J) = 0.0
CONTINUE
10
C
RETURN
END
SUBROUTINE CROSS( A, B, C )
DIMENSION A(3), B(3), C(3)
C
C(1) = A(2)*B(3) - A(3)*B(2)
C(2) = A(3)*B(1) - A(1)*B(3)
C(3) = A(1)*B(2) - A(2)*B(1)
C
RETURN
END
```

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C          SUBROUTINE OUTPUT
C
COMMON / PREUP / XKM(71) , PKM(71,71)
COMMON / LINFMNT / F(71,71) , NS , NPAR
COMMON / UDWORK / RG(71) , U(2556) , PO(2556) , SF(2556) , SG(71) , RESID , COVZ
COMMON / LINHMT / H(35,71) , NMEAS
COMMON / SHBDAT / TVACLS(2) , XISPLS(2) , XMD(2) , AEXIT(2)
1           , CVPFH(2) , CVTVCs(2) , CVISPS(2) , CVDM(2) , CVAE(2)
2           , OMMASS(2)

COMMON / SRBMEA / POHHAT(2)
COMMON / SMEDAT / TVACL(3) , XISPL(3) , WDO2H(3) , WDH2H(3) , WD(3)
1           , CVTVCL(3) , CVISPL(3) , CVWD02(3) , CVWDH2(3)
2           , CVWD(3) , CVWDGO(3) , CVWDGH(3) , PCTAG(3) , OMASE(3)
COMMON / SMEMEA / XLH(6,3)
COMMON / GIMBAL / CCLBB1(3,3) , CCLBB2(3,3) , CCLBB3(3,3) , CCLBA(3,3)
1           , CCLBB(3,3) , PLN , RATEC(3) , THTC(3)
COMMON / STAGE / ISTANCE
C
DATA KO / 0 /
DATA TLAST / 0.0 /
C
C DATA WTLOU , WTLHU , WTLLOON , WTLHON / 4 * 0 . 0 /
C
C NTS = NS + NPAR
KO = KO + 1
C
C FILTER STATE VARIABLES
C
WRITE(*, 901) VAR(1) , TLAST , KO , NMEAS
WRITE(7,901) VAR(1) , TLAST , KO , NMEAS
WRITE(7,902) (XKM(I) , I = 1 , NTS)
WRITE(7,902) (PKM(I,I) , I = 1 , NTS)
WRITE(7,902) (RG(I) , I = 1 , NTS)
WRITE(7,902) COVZ
WRITE(7,902) RESID
C
C IF ( KO - NMEAS ) 20 , 10 , 10
10 CONTINUE
C
C MAIN ENGINE PERFORMANCE ESTIMATES
C
WRITE(8,902) VAR(1) , PLN , (TVACL(I) , I = 1 , 3) , (XISPL(I) , I = 1 , 3)
WRITE(8,903) (WDO2H(I) , I = 1 , 3) , (WDH2H(I) , I = 1 , 3)
WRITE(8,903) (XLH(2,I) , I = 1 , 3) , (XLH(3,I) , I = 1 , 3)
WRITE(8,903) (WD(I) , I = 1 , 3) , WTLOU , WTLHU , WTLLOON , WTLHON
C
C IF ( ISTANCE .EQ. 1 ) THEN
C
C SOLID ROCKET BOOSTER PERFORMANCE ESTIMATES
C
WRITE(9,910) VAR(1) , POHHAT(1) , XISPLS(1) , TVACS(1) , XMD(1) , AEXIT(1)
WRITE(9,910) VAR(1) , POHHAT(2) , XISPLS(2) , TVACS(2) , XMD(2) , AEXIT(2)
C
C ELSE

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```
END IF
C      TLAST = VAR(1)
C      KO = 0
C      20 CONTINUE
C      RETURN
C      901 FORMAT( 2E15.8, 2I5 )
C      902 FORMAT( 8E10.4 )
C      903 FORMAT( 10X, 7E10.4 )
C      910 FORMAT( 3X, F7.3, 2F10.3, F13.1, 2F10.3 )
C      END
```

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```
C      SUBROUTINE ZDVEC
C      COMMON / DRVITV / XDOT(71), PD(71,71)
C      COMMON / PROGAG / X(71), P(71,71)
C      DATA TAUACB,TAURAZ,TAUREL,TAURRG / 1.E+2,3*4.E+2 /
C
C      OOTAU A = 1./TAUACB
C      OOTAUZ = 1./TAURAZ
C      OOTAU E = 1./TAUREL
C      OOTAU R = 1./TAURRG
C
C      XDOT(50) = -OOTAU A*X(50)
C      XDOT(51) = -OOTAU A*X(51)
C      XDOT(52) = -OOTAU A*X(52)
C
C      XDOT(53) = -OOTAUZ*X(53)
C      XDOT(54) = -OOTAU E*X(54)
C      XDOT(55) = -OOTAU R*X(55)
C      XDOT(56) = -OOTAUZ*X(56)
C      XDOT(57) = -OOTAU E*X(57)
C      XDOT(58) = -OOTAU R*X(58)
C      XDOT(59) = -OOTAUZ*X(59)
C      XDOT(60) = -OOTAU E*X(60)
C      XDOT(61) = -OOTAU R*X(61)
C
C      RETURN
C      END
```

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SUBROUTINE LINFB
C
COMMON DER(2700), VAR(2700), TEMP(5400), NDER
COMMON / LINFBMT / R(71,71), NS, NPAR
COMMON / CONST / A(71), S(71), R(12)
C
DATA TAUACB,TAURAZ,TAUREL,TAURRG / 1.E+2,3*4.E+2 /
C
C
OOTAUU = 1./TAUACB
OOTAUZ = 1./TAURAZ
OOTAUE = 1./TAUREL
OOTAUR = 1./TAURRG
C
F(50,50) = -OOTAUU
F(51,51) = -OOTAUZ
F(52,52) = -OOTAUE
C
F(53,53) = -OOTAUZ
F(54,54) = -OOTAUU
F(55,55) = -OOTAUR
F(56,56) = -OOTAUZ
F(57,57) = -OOTAUU
F(58,58) = -OOTAUE
F(59,59) = -OOTAUZ
F(60,60) = -OOTAUU
F(61,61) = -OOTAUR
C
S(50) = 2.*A(50)**2/TAUACB
S(51) = 2.*A(51)**2/TAUACB
S(52) = 2.*A(52)**2/TAUACB
C
S(53) = 2.*A(53)**2/TAURAZ
S(54) = 2.*A(54)**2/TAUREL
S(55) = 2.*A(55)**2/TAURRG
S(56) = 2.*A(56)**2/TAURRG
S(57) = 2.*A(57)**2/TAUREL
S(58) = 2.*A(58)**2/TAURRG
S(59) = 2.*A(59)**2/TAURAZ
S(60) = 2.*A(60)**2/TAUREL
S(61) = 2.*A(61)**2/TAURRG
C
RETURN
END

```

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SUBROUTINE REFRAC ( IRDR, EL, RNGH, DELEL, DELRNG )
C
COMMON / EDATA / RE, FLAT, OMEGE, XMU, XJ2, CRAD
COMMON / RDRDAT / XXNO(3), RLAT(3), RLONG(3), SALT(3), NRDR
C
DATA A, B, C / 17590., 30.55, 0.0 /
DATA RO / 6378165. /
DATA CRAD / 57.295779 /
C
C
RANGE = .3048*RNGH
HSTA = .3048*SALT( IRDR )
XNO = XXNO( IRDR )
C
ALT = SQRT( RO**2 + RANGE**2 + 2.*RO*RANGE*SIN( EL/CRAD ) ) - RO
HS0 = 7000.
C
DO 10 I = 1, 50
C
HS = A - B*(XNO*1.E+6)*EXP( ( HSTA - C )/HS0 )
C
WRITE(*, 901) HS, HS0
901 FORMAT ( 10X, 2E12.5 )
C
IF ( ABS( HS - HS0 ) .LE. 1.0 ) GO TO 20
C
HS0 = HS
C
WRITE(*, 902) I
902 FORMAT ( 2DH FAILED TO CONVERGE IN, 15, 18H STEPS IN "REFRAC" )
C
CONTINUE
10
CONTINUE
C
20
CONTINUE
C
IF ( ALT.LT.6000. ) THEN
C
RRNG = RANGE/RO
RR2 = RRNG*RRNG
C
RALT = ALT/HS
RA2 = RALT*RALT
RA3 = RA2*RALT
C
DELRNG = XNO*RANGE*( 1. + 67.*RR2 )*
1 ( 1. - .49939*RALT + .17472*RA2 - .04344*RA3 )
1 DELEL = XNO*RANGE*COS(EL/CRAD)/(2.*HS)*( 1. + 46.*RR2 )*
1 ( 1.-.333324*RALT + .08558*RA2 - .01681*RA3 )
C
ELSE
C
IF ( ALT.LT.1.E+5 ) THEN
C
HSTR = ( 1. - EXP( -ALT/HS ) )*HS
C
ELSE

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C      HSTR = HS
C      END IF
C
XNO2 = XNO*XNO
RALT = ALT/RO
RA2 = RALT/RALT
RHS = HSTR/RO
C
A1 = .394 + 1.16E+5*XNO2
A2 = .09 + 7.1E+5*XNO2
A3 = .004 + 1.E+5*XNO2
B1 = 59.9 + 1.14E+4*XNO - 1.9E+7*XNO2
B2 = -3.379 - 1.E+3*XNO + 8.E+6*XNO2
B3 = .007
C1 = .7181 - 246.*XNO + 2.1E+4*XNO2
C2 = 27.5 - 7.8E+3*XNO - 9.96E+7*XNO2
C3 = -4.2 - 2.3E+3*XNO - 4.32E+7*XNO2
C4 = 141.1 - 1.1E+4*XNO + 4.03E+8*XNO2
C5 = -20.4 - 9.E+4*XNO - 3.1E+7*XNO2
C
AA = ( A1 + A2*RALT )/( 1. + A3*RALT )
BB = ( B1 + B2*RALT )/( 1. + B3*RALT )
CC = ( C1 + C2*RALT + C3 * RA2 )/( 1. + C4*RALT + C5*RA2 )
C
SEL = SIN( EL/CRAD )
CEL = COS( EL/CRAD )
C
ROOT = SQRT( SEL**2 + 2.*RHS )
C
DELEL = XNO*CEL*( 1.+AA*EXP( -BB*SEL ) )/( 1.-CC ) *ROOT+C*SEL)
DELEL = DELEL*( 1.- 2.*RHS/( ROOT + SEL ) )
DELRNG = 2.*XNO*HSTR/( ROOT + SEL )
DELRNG = DELRNG*( 1.-2.7E+7*(XNO**1.5)*RHS*(CEL***(1.4E+6*XNO) ) )
C
END IF
C
DELRNG = DELRNG/.3048
DELEL = DELEL*CRAD
C
RETURN
END
C

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